Model-based Testing for Safety-Critical Systems

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FoMSESS 2015

With contributions by
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Overview

• Model-based testing
• Standards for safety-critical transportation systems
• What standards require about model-based testing
• Complete test strategies …
• … and their relevance for model-based testing of safety-critical systems
• Discussion
Overview

• Model-based testing
  • Standards for safety-critical transportation systems
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Model-based Testing

Instead of writing test procedures,

• develop a **test model** specifying expected behaviour of SUT (system under test)

• use **generator** to identify “relevant” test cases from the model and calculate concrete test data

• generate **test procedures** fully automatic

• perform **tracing** requirements ↔ test cases in a fully automatic way
Overview

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• **Standards for safety-critical transportation systems**
  • What standards require about model-based testing
  • Complete test strategies …
  • … and their relevance for model-based testing of safety-critical systems

• Discussion
Standards for Safety-critical Transportation Systems

- Railway domain: **CENELEC EN 50128:2011**
  Railway applications - Communication, signalling and processing systems - Software for railway control and protection systems

- Avionic domain: **RTCA DO-178C**
  Software considerations in airborne systems and equipment certification

- Automotive domain: **ISO 26262**
  Road vehicles – Functional safety
Overview

- Model-based testing
- Standards for safety-critical transportation systems
- **What standards require about model-based testing**
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- ... and their relevance for model-based testing of safety-critical systems
- Discussion
What Standards Require About Model-based Testing

- All standards acknowledge the model-driven development and V&V approach
- Only ISO26262 explicitly uses the term *model-based testing*
- RTCA DO-178B and its supplements addresses the model-driven approach in the most comprehensive way
Automotive Domain

• ISO 26262 – Part 6: Product development: software level – Appendix B: Model-based development

“In model-based development,] Testing activities are also treated differently since models can be used as a useful source of information for the testing process (model-based testing).”
Avionic Domain

• The RTCA DO-178C standard is complemented by several supplements; relevant for this presentation are

  • RTCA DO-331. Model-Based Development and Verification Supplement to DO-178C and DO-278A

  • RTCA DO-333. Formal Methods Supplement to DO-178C and DO-278A
SRATS. System requirements allocated to SW
HLR. High-level requirements
LLR. Low-level requirements

Figure MB.DP1-4
Example C: Separate Models Used To Express HLR and LLR/SW Architecture

DO-178( ) / ED-12( ) Applies
References of RTCA DO-331 to Model-based Testing

- The term “model-base testing” is never used, but (model-based) simulation is addressed [DO-331;MB.6.8]

For Design Models, simulation may be used in combination with testing and appropriate coverage analysis to satisfy objectives related to the verification of the Executable Object Code. As simulation may involve different object code and a different environment than the target application, simulation alone cannot be used to satisfy objectives related to verification of the Executable Object Code. … However, if simulation cases are run in the target computer environment using the Executable Object Code, then they are also considered test cases and DO-178C section 6.4 applies.
References of RTCA DO-331 to Model-based Testing

- (Design) models have to be verified with respect to the original (informal) requirements
- Model coverage analysis is performed to verify the completeness of the design model
- Model coverage analysis can also be used (as soon as the model has been verified) to check the completeness of testing activities
Model Coverage Criteria

• … according to RTCA DO-331

• Requirements coverage

• Transition coverage (of state machines)

• Decision coverage (of guard conditions and decision tables etc.)

• Coverage of all equivalence classes, boundary conditions and enumerable value ranges
Complete Test Strategies

• Recall: **complete = sound + exhaustive**

  • **sound** = every correct SUT (system under test) behaviour is accepted by each test suite generated according to the strategy

  • **exhaustive** = every erroneous SUT behaviour will be uncovered by at least one test case

• RTCA DO-331 acknowledges the existence of complete strategies (MB.12.3.1 Exhaustive Input Testing)
What is not Addressed by the Standards

• How are requirements reflected (traceable) in the models?

• Adequacy of test cases (suitability of strategies, coverage criteria) with respect to
  
  - Selection of equivalence classes
  
  - Timing constraints
  
  - Concurrent behaviours

• How can security aspects be modelled and verified?
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Complete Test Strategies

• For black-box testing, completeness is specified with respect to a fault model
  - Reference model
  - Conformance relation
  - Fault domain

\[ \mathcal{F} = (\mathcal{S}, \sim, \mathcal{D}((\mathcal{S}, m, \mathcal{I}_2))) \]
Complete Test Strategies

• For black-box testing:

• **complete = sound + exhaustive**

  • **sound** = every correct SUT behaviour is accepted by each test suite generated according to the strategy

  • **exhaustive** = every erroneous SUT behaviour will be uncovered by at least one test case, **as long as the true SUT behaviour is reflected by a member of the fault domain**
Complete Test Strategies

• Why are black-box tests important for safety-critical systems?

  • HW/SW integration testing and system integration testing **must be performed on the unaltered target system**

  • Typically, the target system does not provide sufficient monitoring means for white/grey-box testing

  • This is because standards do not allow for code to be present in the target, if it does not contribute to the specified functionality
Example

• Complete test strategy:
  • Novel equivalence class partition testing strategy
  • Applicable to
    • Nondeterministic models with Kripke Structure semantics
    • Infinite (or very large) input domains
    • Finite internal states
    • Finite control outputs
Example

• Typical applications:
  • Analogue input sensors and discrete control decisions
  • Airbag controller
  • Speed controllers (e.g. in train protection systems)
  • Route controller in interlocking systems
Example

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  • Analogue input sensors and discrete control decisions
  • Airbag controller
  • Speed controllers (e.g. in train protection systems)
  • Route controller in interlocking systems

Application example to be discussed below
Construction Principle for Equivalence Class Testing Strategies

• Associate test model with **Kripke Structure K** expressing behavioural semantics
  
  • States are valuation functions over input variables, internal model variables, and output variables
  
  • Specify **conformance relation** between reference model behaviour K and SUT behaviour K’
    
    • **I/O-equivalence.** Every input sequence produces the same output sequence in K and K’ (suitable for deterministic applications)
    
    • **Reduction.** SUT behaviour K’ is a subset of reference model behaviours K (suitable for nondeterministic K)
Construction Principle for Equivalence Class Testing Strategies

- Factorise K-state space into I/O-equivalence classes

- Classes are enumerated over internal state and output combinations

- States of the same class produce the same responses to all input sequences

\[ \mathcal{A} = \{ A_1, \ldots, A_n \} \]

\[ \forall i, s, s' \in A_i : s(\bar{m}, \bar{y}) = s'(\bar{m}, \bar{y}) \land L(s) = L(s') \]
Construction Principle for Equivalence Class Testing Strategies

- Factorise K-input space into input equivalence class partitions
  
  - All input vectors of the same input class, when applied to members of the same I/O-equivalence class,
    
    - produce the same outputs
    
    - have the same target I/O-equivalence classes
Construction Principle for Equivalence Class Testing Strategies

- Together, I/O-equivalence classes and input equivalence classes induce an FSM abstraction of the Kripke Structure

\[ h : A \times I \rightarrow A \times D_O \]

deterministic case

\[ h : A \times I \rightarrow P(A \times D_O) \]

nondeterministic case
Construction Principle for Equivalence Class Testing Strategies

• For (deterministic or nondeterministic) FSM, complete strategies exist

• When generating a test suite for an FSM abstraction, choose any representative

\[ \bar{c} \in X \in \mathcal{I} \]

when abstract input \( X \) is required
Complete Test Strategy

- Fault model for black-box testing
  - Reference model
  - Conformance relation
  - Fault domain

\[ \mathcal{F} = (S, \sim, D(S, m, I_{2})) \]
Complete Test Strategy

CSM model as Kripke Structure –
semantic representation of SysML model

\[ \mathcal{F} = (S, \sim, D(S, m, I_2)) \]
Complete Test Strategy

$I/O$-equivalence as conformance relation

$\mathcal{F} = (\mathcal{S}, \sim, \mathcal{D}(\mathcal{S}, m, \mathcal{I}_2))$
Complete Test Strategy

Maximal number of I/O-equivalence classes for each member of the fault domain

$$\mathcal{F} = (S, \sim, D(S, m, I_2))$$
Complete Test Strategy

A refined IECP – satisfying

\[ \forall X \in \mathcal{I}, X' \in \mathcal{I}' : \\
(X \cap X' \neq \emptyset \Rightarrow \\
\exists X_2 \in \mathcal{I}_2 : X_2 \subseteq X \cap X') \]

\[ \mathcal{F} = (\mathcal{S}, \sim, \mathcal{D}(\mathcal{S}, m; \mathcal{I}_2)) \]
Complete Test Strategy

A refined IECP – satisfying

\[ \forall X \in \mathcal{I}, X' \in \mathcal{I} : \\
\quad (X \cap X' \neq \emptyset \Rightarrow \\
\quad \exists X_2 \in \mathcal{I}_2 : X_2 \subseteq X \cap X') \]

\[ \mathcal{F} = (S, \sim, \mathcal{D}(S, m; \mathcal{I}_2)) \]
Complete Test Strategy

IECP of fault domain member

A refined IECP – satisfying

\[ \forall X \in \mathcal{I}, X' \in \mathcal{I}' : 
( X \cap X' \neq \emptyset \Rightarrow 
\exists X_2 \in \mathcal{I}_2 : X_2 \subseteq X \cap X') \]

\[ \mathcal{F} = (\mathcal{S}, \sim, \mathcal{D}(\mathcal{S}, m; \mathcal{I}_2)) \]
Complete Test Strategy

A refined IECP – satisfying

\( \forall X \in \mathcal{I}, X' \in \mathcal{I}' : \)

(\( X \cap X' \neq \emptyset \Rightarrow \exists X_2 \in \mathcal{I}_2 : X_2 \subseteq X \cap X' \))

\( \mathcal{F} = (\mathcal{S}, \sim, \mathcal{D}(\mathcal{S}, m; \mathcal{I}_2)) \)
If \( X \) triggers behaviour in reference model state \( s \), and \( X' \) triggers non-conforming behaviour of model representing SUT behaviour, then there exists \( X_2 \) in intersection of \( X, X' \), and a member of \( X_2 \) will be used in the test.

\[
\forall X \in \mathcal{I}, X' \in \mathcal{I}' : (X \cap X' \neq \emptyset \Rightarrow \exists X_2 \in \mathcal{I}_2 : X_2 \subseteq X \cap X')
\]

\[\mathcal{F} = (S, \sim, \mathcal{D}(S, m, \mathcal{I}_2))\]
Example. Railway network and interlocking tables

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th>Points</th>
<th>Signals</th>
<th>Path</th>
<th>Conflicts</th>
</tr>
</thead>
<tbody>
<tr>
<td>1a</td>
<td>mb10</td>
<td>mb13</td>
<td>t11:p; t13:m</td>
<td>mb11; mb12; mb20</td>
<td>t10; t11; t12</td>
<td>1b;2a;2b; 3;4;5a;5b;6b; 7</td>
</tr>
<tr>
<td>7</td>
<td>mb20</td>
<td>mb11</td>
<td>t11:m</td>
<td>mb10;mb12</td>
<td>t11;t10</td>
<td>1a;1b;2a;2b; 3;5b;6a</td>
</tr>
</tbody>
</table>

... ... ... ... ... ... ... ...
Railway network and interlocking tables

Marker Board = Virtual signal
Direction = DOWN

<p>| | | | | | |</p>
<table>
<thead>
<tr>
<th></th>
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<tbody>
<tr>
<td>id</td>
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<td>Dest</td>
<td>Points</td>
<td>Signals</td>
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<td>---</td>
<td>---</td>
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<td>mb10</td>
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<td>t11:p; t13:m</td>
<td>mb11; mb12; mb20</td>
<td>t10; t11; t12</td>
</tr>
<tr>
<td>...</td>
<td>...</td>
<td>...</td>
<td>...</td>
<td>...</td>
<td>...</td>
</tr>
<tr>
<td>7</td>
<td>mb20</td>
<td>mb11</td>
<td>t11:m</td>
<td>mb10; mb12</td>
<td>t11; t10</td>
</tr>
</tbody>
</table>
Railway network and interlocking tables

Point positions
p = PLUS (straight)
m = MINUS
Railway network and interlocking tables

<table>
<thead>
<tr>
<th>id</th>
<th>Src</th>
<th>Dest</th>
<th>Points</th>
<th>Signals</th>
<th>Path</th>
<th>Conflicts</th>
</tr>
</thead>
<tbody>
<tr>
<td>1a</td>
<td>mb10</td>
<td>mb13</td>
<td>t11:p;</td>
<td>mb11; mb12; mb20</td>
<td>t10; t11; t12</td>
<td>1b; 2a; 2b; 3; 4; 5a; 5b; 6b; 7</td>
</tr>
<tr>
<td>7</td>
<td>mb20</td>
<td>mb11</td>
<td>t11:m</td>
<td>mb10; mb12</td>
<td>t11; t10</td>
<td>1a; 1b; 2a; 2b; 3; 5b; 6a</td>
</tr>
</tbody>
</table>
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<td>mb11; mb12; mb20</td>
<td>t10; t11; t12</td>
<td>1b; 2a; 2b; 3; 4; 5a; 5b; 6b; 7</td>
</tr>
<tr>
<td></td>
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<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>mb20</td>
<td>mb11</td>
<td>t11:m</td>
<td>mb10; mb12</td>
<td>t11; t10</td>
<td>1a; 1b; 2a; 2b; 3; 5b; 6a</td>
</tr>
</tbody>
</table>
Route Controller

Requirements

• All routes can be allocated

• Conflicting routes are never allocated at the same time, as long as conflicting elements are still in use (sequential release method)

• An element along a route is sequentially released, if
  • all previous elements have been sequentially released
  • the train has left the element under consideration

• Routes are marked as free, as soon as all elements have been sequentially released
Sequential release method

Route 7 can be allocated

Route 1 is allocated

No conflicts anymore with Route 1

Sequentially released

Points | Signals | Path | Conflicts
---|---|---|---
1 | mb10 | mb13 | t11:p; t13:m mb11; mb12; mb20
2;3;4;5;6;7

7 | mb20 | mb11 | t11:m mb10; mb12 t11; t10 | 1;2;3;5;6
Example – Nondeterministic Reference Models

• Even in a safety-critical context, nondeterministic models may be used …

• … mostly to reduce model checking complexity by means of over-approximation

• As a consequence, it is useful to have complete model-based testing strategies at hand that can cope with nondeterministic models …

• … though the SUT will usually be deterministic
If no conflicting routes are allocated, route controller model specifies **nondeterministic decision** whether to allocate Route 1 or Route 2.

<table>
<thead>
<tr>
<th>Id</th>
<th>Source</th>
<th>Dest</th>
<th>Conflicts</th>
<th>Id</th>
<th>Source</th>
<th>Dest</th>
<th>Conflicts</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>mb10</td>
<td>mb14</td>
<td>3,4,5,7</td>
<td>5</td>
<td>mb15</td>
<td>mb12</td>
<td>. . .</td>
</tr>
<tr>
<td>2</td>
<td>mb10</td>
<td>mb21</td>
<td>3,6,7,8</td>
<td>6</td>
<td>mb15</td>
<td>mb20</td>
<td>. . .</td>
</tr>
<tr>
<td>3</td>
<td>mb12</td>
<td>mb11</td>
<td>. . .</td>
<td>7</td>
<td>mb20</td>
<td>mb11</td>
<td>. . .</td>
</tr>
<tr>
<td>4</td>
<td>mb13</td>
<td>mb14</td>
<td>. . .</td>
<td>8</td>
<td>mb21</td>
<td>mb14</td>
<td>. . .</td>
</tr>
</tbody>
</table>
Route Controller – Routes 1,2

Input variables

Output variables

Dynamic Internal State:
route/element modes

Static Internal State:
interlocking tables

$p \in \text{Point} : p.\text{POS}$

$e \in \text{Section} : e.\text{vacancy status}$

$r_3, r_3, \ldots, r_8 : \text{RouteStatus}$

$s \in \text{Signal} : s.\text{CMD}$

$p \in \text{Point} : p.\text{CMD}$
Examples for I/O-Equivalence classes

- A1: No train at b10 and Routes 1,2 free and Routes 3,5,6,7 free and t12,t13,t20 empty

- A2: Train in direction UP at b10 and Route 1 allocated and Routes 2,3,5,6,7 free and t12,t13,t20 empty

- A3: Train in direction UP at b10 and Route 2 allocated and Routes 1,3,5,6,7 free and t12,t13,t20 empty
Examples for Input Equivalence Classes and FSM Transitions

- X1: Train at b10 in direction up and Routes 3,5,6,7 free and t12,t13,t20 empty
Overview

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• Standards for safety-critical transportation systems

• What standards require about model-based testing

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• … and their relevance for model-based testing of safety-critical systems

• Discussion
Relevance of Complete Strategies

• Relevance from the certification viewpoint

  • Justified strategy:
    • e.g. selection of equivalence classes
    • new test cases are guaranteed to increase the test strength

• General relevance

  • Superior test strength – also for SUT behaviours outside the fault domain
### Table 2. Results for the Ceiling Speed Monitor

<table>
<thead>
<tr>
<th>Suite B,C</th>
<th>No. TC</th>
<th>IEC-P-Tests (B) / (C)</th>
<th>(A) (Random Testing)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Mutation Score</td>
<td>Line Cov.</td>
</tr>
<tr>
<td>(B,\mathcal{D}_1)</td>
<td>21</td>
<td>62 %</td>
<td>86 %</td>
</tr>
<tr>
<td>(C,\mathcal{D}_1,1)</td>
<td>21</td>
<td>76 %</td>
<td>97 %</td>
</tr>
<tr>
<td>(C,\mathcal{D}_1,10)</td>
<td>183</td>
<td>82 %</td>
<td>97 %</td>
</tr>
<tr>
<td>(C,\mathcal{D}_1,25)</td>
<td>453</td>
<td>82 %</td>
<td>97 %</td>
</tr>
<tr>
<td>(B,\mathcal{D}_2)</td>
<td>186</td>
<td>87 %</td>
<td>100 %</td>
</tr>
<tr>
<td>(C,\mathcal{D}_2,1)</td>
<td>186</td>
<td>88 %</td>
<td>100 %</td>
</tr>
<tr>
<td>(C,\mathcal{D}_2,10)</td>
<td>882</td>
<td>94 %</td>
<td>100 %</td>
</tr>
<tr>
<td>(B,\mathcal{D}_3)</td>
<td>610</td>
<td>93 %</td>
<td>100 %</td>
</tr>
<tr>
<td>(C,\mathcal{D}_3,1)</td>
<td>610</td>
<td>100 %</td>
<td>100 %</td>
</tr>
<tr>
<td>(C,\mathcal{D}_3,10)</td>
<td>3002</td>
<td>100 %</td>
<td>100 %</td>
</tr>
</tbody>
</table>

Column No. TC records the number of test cases applied. \((B,\mathcal{D}_i)\) denotes application of strategy (B) with fault domain \(\mathcal{D}_i, i = 1, 2, 3\), \((C,\mathcal{D}_i,q)\) denotes application of strategy (C) with fault domain \(\mathcal{D}_i, i = 1, 2, 3\) and \(\min = q\). Columns ‘Line Cov.’ record the line coverage achieved with the execution of the respective test suite.
Table 2. Results for the Ceiling Speed Monitor

<table>
<thead>
<tr>
<th>Suite B,C</th>
<th>No. TC</th>
<th>Mutation Score</th>
<th>Line Cov.</th>
<th>No. TC</th>
<th>Mutation Score</th>
<th>Line Cov.</th>
</tr>
</thead>
<tbody>
<tr>
<td>(B,(D_1))</td>
<td>81</td>
<td>21</td>
<td>34%</td>
<td>75%</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(C,(D_{1,1}))</td>
<td>1</td>
<td>34%</td>
<td>75%</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>(C,(D_1))</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>(C,(D_{1,10}))</td>
<td>610</td>
<td>93%</td>
<td>100%</td>
<td>610</td>
<td>80%</td>
<td>97%</td>
</tr>
<tr>
<td>(B,(D_2))</td>
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<td></td>
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<td></td>
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<td></td>
</tr>
<tr>
<td>(C,(D_{2,1}))</td>
<td>186</td>
<td>63%</td>
<td>92%</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>(C,(D_{2,10}))</td>
<td>3002</td>
<td>100%</td>
<td>100%</td>
<td>3002</td>
<td>92%</td>
<td>97%</td>
</tr>
<tr>
<td>(B,(D_3))</td>
<td>610</td>
<td>93%</td>
<td>100%</td>
<td>610</td>
<td>80%</td>
<td>97%</td>
</tr>
<tr>
<td>(C,(D_{3,1}))</td>
<td>610</td>
<td>100%</td>
<td>100%</td>
<td>610</td>
<td>80%</td>
<td>97%</td>
</tr>
<tr>
<td>(C,(D_{3,10}))</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Column No. TC records the number of test cases applied. \((B,\(D_i\))\) denotes application of strategy \((B)\) with fault domain \(\mathcal{D}_i, i = 1, 2, 3\), \((C,\(D_i,q\))\) denotes application of strategy \((C)\) with fault domain \(\mathcal{D}_i, i = 1, 2, 3\) and \(\text{min} = q\). Columns ‘Line Cov.’ record the line coverage achieved with the execution of the respective test suite.
Table 3. Results for the Airbag Controller

<table>
<thead>
<tr>
<th>Suite</th>
<th>No. TC</th>
<th>Mutation Score</th>
<th>Line Cov.</th>
<th>No. TC</th>
<th>Mutation Score</th>
<th>Line Cov.</th>
</tr>
</thead>
<tbody>
<tr>
<td>(B, D₁)</td>
<td>368</td>
<td>89 %</td>
<td>97 %</td>
<td>368</td>
<td>66 %</td>
<td>94 %</td>
</tr>
<tr>
<td>(C, D₁,1)</td>
<td>368</td>
<td>96 %</td>
<td>100 %</td>
<td>368</td>
<td>66 %</td>
<td>94 %</td>
</tr>
<tr>
<td>(C, D₁,10)</td>
<td>3816</td>
<td>97 %</td>
<td>100 %</td>
<td>3816</td>
<td>68 %</td>
<td>97 %</td>
</tr>
<tr>
<td>(B, D₂)</td>
<td>3248</td>
<td>99 %</td>
<td>100 %</td>
<td>3248</td>
<td>68 %</td>
<td>94 %</td>
</tr>
<tr>
<td>(C, D₂,1)</td>
<td>3248</td>
<td>100 %</td>
<td>100 %</td>
<td>3248</td>
<td>68 %</td>
<td>94 %</td>
</tr>
</tbody>
</table>
Complete IECP strategy — full requirements coverage — random selection from each input partition

**Table 3. Results for the Airbag Controller**

<table>
<thead>
<tr>
<th>Suite</th>
<th>(A) Random Testing</th>
<th>Mutation Score</th>
<th>Line Cov.</th>
</tr>
</thead>
<tbody>
<tr>
<td>(B, (D_1))</td>
<td>368</td>
<td>66 %</td>
<td>94 %</td>
</tr>
<tr>
<td>(C, (D_1,1))</td>
<td>368</td>
<td>66 %</td>
<td>94 %</td>
</tr>
<tr>
<td>(C, (D_1,10))</td>
<td>3816</td>
<td>68 %</td>
<td>97 %</td>
</tr>
<tr>
<td>(B, (D_2))</td>
<td>3248</td>
<td>99 %</td>
<td>94 %</td>
</tr>
<tr>
<td>(C, (D_2,1))</td>
<td>3248</td>
<td>100 %</td>
<td>94 %</td>
</tr>
</tbody>
</table>

Experimental results submitted to TAP 2015
Overview

- Model-based testing
- Standards for safety-critical transportation systems
- What standards require about model-based testing
- Complete test strategies …
- … and their relevance for model-based testing of safety-critical systems
- Discussion
Discussion

• Conclusion

• We have motivated that complete test suites are of practical value, because they exhibit considerable test strength also outside the specified fault domain.

• We advocate the inclusion of complete test suites into the catalogues of recommended methods in standards for safety-critical standards.
Discussion

• Open questions

  • Is the strength of „conceptually complete“ test suites still superior to other approaches, if only a part of the test suite is executed?

  • Is the strength of complete test suites still superior to other approaches, if the true SUT performs security attacks whose behaviour is outside the fault domain?
Further Reading


Further Reading


**Vasilevskii, M.P.:** Failure diagnosis of automata. Kibernetika (Transl.) 4, 98–108 (1973)
Many thanks for listening!