

## Basic Behaviour

basic behaviour in space
follow course
approach target dock at target
basic behaviour
in network of passages
follow passage
follow wall
approach target
turn into passage
turn into i-th passage
stop
searching
spiral searching
block searching
meandering

## Tactical Navigation

directional navigation
in space
compass navigation dead reckoning
positional navigation
in space
landmark navigation celestial navigation
branching
in network of passages
binary branching
rectangular branching
directional branching
n-way branching
branching at marked
junction

## Strategic

Navigation
route navigation homog. route navigation heterog. route navigation
explorative navigation path finding threading
combined navigation positional path finding traversing
making a detour making a shortcut
premeditated navigation route map navigation map navigation

## Basic Behaviour

basic behaviour in (enclosed or open) space

| Title | Percept | Representation | Action |
| :--- | :--- | :--- | :--- |
| follow <br> course | course; orientation | course (direction) | adjust orientation to course, steer <br> clear of obstacles |
| approach <br> target | remaining distance, <br> view of target | distance | if remaining distance near Zero, <br> switch to new behaviour |
| dock at <br> target | position, orientation | target position <br> (direction, distance), <br> orientation at target | maneuver into target position and <br> orientation |

basic behaviour in network of passages (tunnels, corridors, roads, trails)

| follow <br> passage | walls, obstacles |  | follow passage centralized <br> between walls, avoid obstacles |
| :--- | :--- | :--- | :--- |
| follow <br> wall | wall, obstacles | \{left \| right\} | follow wall, avoid obstacles |
| approach <br> target | [remaining <br> distance,] view of <br> (marked) junction | [distance] | if remaining distance near Zero, <br> switch to new behaviour |
| turn into <br> passage | junction with \{left <br> right $\}$ passage | \{left \| right \} | turn \{left \| right\} into resp. passage |
| turn into <br> i-th <br> passage | junction with n <br> passages | i | turn into i-th passage |
| stop at <br> target | walls, [dead end] | target position <br> (direction, distance) | stop |

## searching

| spiral <br> searching | locality in space | characteristics of <br> target location | spiral outwards until location is <br> found |
| :--- | :--- | :--- | :--- |
| block <br> searching | locality in <br> rectangular grid of <br> passages | characteristics of <br> target location | search each block in vicinity by <br> spiraling until location is found |
| meander- <br> ing | locality in <br> rectangular grid of <br> passages | characteristics of <br> target location | search in vicinity by meandering <br> until location is found |

## Tactical Navigation

## directional navigation in space

| Title | Percept | Representation | Action |
| :--- | :--- | :--- | :--- |
| compass <br> navigatio <br> $n$ | compass direction; <br> orientation, elapsed <br> time, speed | target position <br> (direction, distance), <br> orientation at target | compute course to target, <br> remaining distance; follow course, <br> approach target; change course <br> into target orientation |
| dead <br> reckoning | accumulated <br> homing vector; <br> direction | target position <br> (direction, distance), <br> orientation at target | lompute course to target, <br> remaining distance; <br> follow course, approach target; <br> change course into target <br> orientation |

## positional navigation in space

| landmark <br> navigatio <br> $n$ | view of landmarks, <br> orientation | location <br> characterized by <br> landmarks, <br> orientation at target | triangulate vector to target, <br> navigate directionally |
| :--- | :--- | :--- | :--- |
| celestial <br> navigatio <br> $n$ | view of moving <br> celestial bodies, <br> orientation | location in absolute <br> coordinate system, <br> orientation at target | triangulate vector to target, <br> navigate directionally |

branching in network of passages

| Title | Percept | Representation | Action |
| :--- | :--- | :--- | :--- |
| binary <br> branching | passage with <br> bifurcation | \{left \| right\} | follow to bifurcation; <br> follow \{left \| right\} wall |
| rectangul <br> ar <br> branching | passage with <br> crossing in <br> rectangular grid | \{left \| straight | right\} | follow to crossing; <br> follow (straight) or <br> turn into \{left \| right\} passage |
| directiona <br> l <br> branching <br> passage with <br> crossing in <br> directional grid, <br> direction | direction <br> $\{\mathrm{N}\|\mathrm{E}\| \mathrm{S} \mathrm{\mid} \mathrm{~W} \mathrm{\}}$ | follow to crossing; <br> follow (straight) or <br> turn into \{left \| right\} passage |  |
| n-way <br> branching | passage with n-way <br> junction | i | follow to junction; <br> turn into i-th branch |
| branching <br> at marked <br> junction | passage with <br> marked n-way <br> junction | marked branch | follow to junction; <br> turn into (marked) i-th branch |

## Strategic Navigation

route navigation

| Title | Percept | Representation | Action |
| :--- | :--- | :--- | :--- |
| homog. <br> route <br> navigatio <br> n | \{locations $\}$ | tactic, sequence of <br> (target location) | apply tactic to locations in <br> sequence, til end of route; <br> stop/dock at target |
| heterog. <br> route <br> navigatio <br> $n$ | $\{$ locations \} | sequence of (tactic, <br> target location) | (apply tactic to location) in <br> sequence, til end of route |

## explorative navigation

| path <br> finding | enclosed or open <br> space, possibly <br> obstructed | target location | construct route: sequence of <br> (tactic [for next passage towards <br> target, possibly by making <br> detours], <br> intermediate location), <br> until target is found |
| :--- | :--- | :--- | :--- |


| threading | labyrinth of <br> passages | (characteristics of) <br> target location | construct thread (inverse route): <br> sequence of (inverse tactic [for <br> next passage towards target], <br> intermediate location) \| backtrack <br> using thread, <br> until target is found |
| :--- | :--- | :--- | :--- |

## combined navigation

| positional <br> path <br> finding | enclosed or open <br> space, possibly <br> obstructed | target location | combine positional navigation <br> (e.g. landmark navigation using <br> GPS) and path finding |
| :--- | :--- | :--- | :--- |
| traversing | enclosed or open <br> space, possibly <br> obstructed | target location | combine directional/positional <br> navigation <br> (e.g. dead-reckoning/landmark <br> navigation) and explorative <br> navigation around obstacles |
| making a <br> detour | (temporarily) <br> obstructed route | route | construct route via evasive <br> location to target of obstructed <br> route; <br> navigate with alternative route |
| making a <br> shortcut | "longer" route | route | construct "shorter/direct" route to <br> target of "longer" route; navigate <br> with alternative route |

premeditated navigation

| route map <br> navigatio <br> n | route marked on <br> map, $\{$ locations $\}$ | sequence of (tactic <br> abstraction, location <br> abstraction) on map | lonstruct route: sequence of <br> (concretize: (tactic abstraction, <br> location abstraction) -> (tactic, <br> location) ); navigate with route |
| :--- | :--- | :--- | :--- |
| map <br> navigatio <br> $n$ | source, target <br> location marked on <br> map, $\{$ locations $\}$ | source, target <br> location marked on <br> map | construct route map by abstract <br> navigation on map; <br> navigate with route map |

