Query Conservative Extensions in Horn Description Logics with Inverse Roles

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Abstract
We investigate the decidability and computational complexity of query conservative extensions in Horn description logics (DLs) with inverse roles. This is more challenging than without inverse roles because characterizations in terms of unbounded homomorphisms between universal models fail, blocking the standard approach to establishing decidability. We resort to a combination of automata and mosaic techniques, proving that the problem is 2EXPTIME-complete in Horn-ALCHIF (and also in Horn-ACC and in ECT). We obtain the same upper bound for deductive conservative extensions, for which we also prove a CONEXPTIME lower bound.

1 Introduction
In the past years, access of incomplete data mediated by description logic (DL) ontologies has gained increasing importance [Poggi et al., 2008, Bienvenu and Ortiz, 2015]. The main idea is to specify domain knowledge and semantics of the data in the ontology, resulting in more complete answers to queries. Significant research activity has led to efficient algorithms and tools for a wide range of DLs such as DL-Lite [Calvanese et al., 2007], more expressive Horn-DLs [Eiter et al., 2012, Trivela et al., 2015, Bienvenu et al., 2016] and “full Boolean” DLs such as ALC [Kollia and Glimm, 2013, Zhou et al., 2015].

In contrast to query answering, which is by now well-understood, there is a need to develop reasoning services for ontology engineering that are tailored towards query-centric applications and support tasks such as ontology versioning and module extraction from ontologies. For example, if one wants to safely replace an ontology with a new version or with a smaller subset of itself (a module), then the new ontology should preserve the answers to queries over all ABoxes (which store the data) [Kontchakov et al., 2010]. The same guarantee ensures that one can safely replace an ontology with another version in an application [Konev et al., 2012]. In both cases, ontologies need to be tested not for their logical equivalence, but for giving the same answers to relevant queries over relevant datasets.

This requirement can be formalized using conservative extensions. In the following, we use the DL term TBox instead of ontology. A TBox $T_2 \supseteq T_1$ is a $(\Gamma, \Sigma)$-query conservative extension of a TBox $T_1$, where $\Gamma$ and $\Sigma$ are signatures of concept/role names relevant for data and queries, respectively, if all $\Sigma$-queries give the same answers w.r.t. $T_1$ and $T_2$, for every $\Gamma$-ABox. Note that the subset relationship $T_2 \supseteq T_1$ is natural when replacing a TBox with a module, but not in versioning, so we might not want to insist on it. In this more general case, $T_1$ and $T_2$ are called $(\Gamma, \Sigma)$-query inseparable. Conservativity and inseparability of TBoxes, as defined above, are useful when knowledge is considered static and data changes frequently. Variants of these notions for knowledge bases (KBs), which consist of a TBox and an ABox, can be used for applications with static data [Wang et al., 2014, Arenas et al., 2016].

We also consider the basic notion of query entailment: $T_1 (\Gamma, \Sigma)$-query entails $T_2$ if all $\Sigma$-queries give at least the answers w.r.t. $T_1$ that they give w.r.t. $T_2$, on any $\Gamma$-ABox. Query inseparability and conservativity are special cases of entailment: inseparability is bidirectional entailment and conservativity is entailment with the assumption that $T_1 \subseteq T_2$. It thus suffices to prove upper bounds for query entailment and lower bounds for conservative extensions. As a query language, we concentrate on conjunctive queries (CQs); since we work with Horn-DLs and quantify over the queries, this is equivalent to using unions of CQs (UCQs) or positive existential queries (PEQs). CQ entailment has been studied for various DLs [Kontchakov et al., 2009, Lutz and Wolter, 2010, Konev et al., 2012, Botoeva et al., 2016], also in the KB version [Botoeva et al., 2016b, Botoeva et al., 2016c] and for OBDA specifications [Bienvenu and Rosati, 2015], see also the survey [Botoeva et al., 2016a]. Nevertheless, there is still a notable gap in our understanding of this notion: query entailment between TBoxes is poorly understood in Horn DLs with inverse roles, often considered a crucial feature, for which there do not seem to be any available results. This is for a reason: it has been observed in [Botoeva et al., 2016a, Botoeva et al., 2016b] that standard techniques for Horn DLs without inverse roles fail when inverse roles are added.

In fact, for Horn-DLs without inverse roles query entailment can be characterized by the existence of homomorphisms between universal models [Lutz and Wolter, 2010, Botoeva et al., 2016a]. The resulting characterizations provide an important foundation for decision procedures, often based on tree automata [Botoeva et al., 2016a].
the presence of inverse roles, however, such characterizations are only correct if we require the existence of \(n\)-bounded homomorphisms, for any \(n\) [Boteva et al., 2016a; Boteva et al., 2016b]. It is not obvious how the existence of such infinite families of bounded homomorphisms can be verified using tree automata (or related techniques) and, consequently, decidability results for query conservative extensions in Horn-DLs with inverse roles are difficult to obtain. The only result we are aware of concerns inseparability of KBs, and it is proved using intricate game-theoretic techniques.

In this paper, we develop decision procedures for query entailment and related problems in Horn DLs with inverse roles. The main idea is to provide a more refined characterization, mixing unbounded and bounded homomorphisms and using bounded homomorphisms only in places where this is strictly necessary. We can then deal with the “unbounded part” using tree automata while the “bounded part” is addressed by precomputing relevant information using a mosaic technique. In this way, we establish decidability and a 2EXPSPACE upper bound for query entailment (and thus inseparability and conservativity) in Horn-\(\text{ALCHIF}\). Together with lower bounds from [Boteva et al., 2016c], we get 2EXPSPACE-completeness for all fragments of Horn-\(\text{ALCHIF}\) that contain \(\text{ELI}\) or Horn-\(\text{ACC}\).

We additionally study the case of deductive entailment between TBoxes, i.e., the question whether \(T_1\) entails at least the same concept and role inclusions as well as functionality assertions over \(\Sigma\) as \(T_2\). This problem too has not previously been studied for Horn DLs with inverse roles. We consider \(\text{ELCHI}_L\)-TBoxes and show that deductive entailment is equivalent to a restricted version of query entailment. We obtain a model theoretic characterization, a decision procedure, and a 2EXPSPACE upper complexity bound. We also give a \(\text{CONEXPTIME}\) lower bound.

Omitted proofs can be found in the long version here: www.informatik.uni-bremen.de/tdki/research/papers.html

2 Preliminaries

2.1 Horn-\(\text{ALCHIF}\)

We introduce Horn-\(\text{ALCHIF}\), a member of the Horn-\(\text{SHIQ}\) family of DLs whose reasoning problems have been widely studied [Hustadt et al., 2007; Krötzsch et al., 2007; Eiter et al., 2008; Kazakov, 2009; Lutz and Wolter, 2012; Ibanez-Garcia et al., 2014]. Let \(\text{NC}, \text{NR}, \text{NI}\) be sets of concept, role, and individual names. A role is either a role name \(r\) or an inverse role \(r^\prime\). As usual, we identify \((r^\prime)^\prime\) and \(r\), allowing to switch between roles names and their inverses easily. A concept inclusion (CI) is of the form \(L \sqsubseteq R\), where \(L\) and \(R\) are concepts defined by the syntax rules

\[
R, R' ::= T \mid \bot \mid A \mid \neg A \mid R \sqcap R' \mid \neg L \sqcup R \mid \exists r.R \mid \forall r.R
\]

\[
L, L' ::= T \mid \bot \mid A \mid L \sqcap L' \mid L \sqcup L' \mid \exists r.L
\]

with \(A\) ranging over concept names and \(r\) over roles. A role inclusion (RI) is of the form \(r \sqsubseteq s\) with \(r, s\) roles and a functionality assertion (FA) is of the form \(\text{func}(r)\) with \(r\) a role. \(\text{ELCHI}_L\)-concepts are expressions that are built according to the syntax rule for \(L\) above, but do not use “\(L\)”.

A Horn-\(\text{ALCHIF}\) TBox \(T\) is a set of CIs, RIs, and FAs. An \(\text{ELCHI}_L\) TBox is a set of \(\text{ELI}\) -CIs, RIs, and FAs. To avoid dealing with rather messy technicalities that do neither seem to be very illuminating from a theoretical viewpoint nor too useful from a practical one\(^1\), we generally assume that functional roles cannot have any subroles, that is, \(r \sqsubseteq s\) implies \(\text{func}(r) \notin T\). We conjecture that our main results also hold without that restriction. An ABox \(A\) is a non-empty set of concept and role assertions of the form \(A(a)\) and \(r(a, b)\), where \(A \in \text{NC}, r \in \text{NR}\), and \(a, b \in \text{NI}\). We write \(\text{ind}(A)\) for the set of individuals in \(A\).

The semantics is defined as usual in terms of interpretations \(I = (\Delta^I, \cdot^I)\) complying with the standard name assumption, i.e., \(a^I = a\) for all \(a \in \text{Ni}\) [Baader et al., 2017]. An interpretation \(I\) is a model of a TBox \(T\) if it satisfies all inclusions and assertions in it, and likewise for ABoxes. \(A\) is consistent with \(T\) if \(T\) and \(A\) have a common model.

A signature \(\Sigma\) is a set of concept and role names. A \(\Sigma\)-ABox is an ABox that uses only concept and role names from \(\Sigma\), and likewise for \(\Sigma\)-\(\text{ELCHI}_L\)-concepts and other syntactic objects.

Generally and without further notice, we work with Horn-\(\text{ALCHIF}\) TBoxes that are in a certain nesting-free normal form, that is, they contain only CIs of the form

\[
T \sqsubseteq A, \ A \sqsubseteq \bot, \ A_1 \sqcap A_2 \sqsubseteq B, \ A \sqsubseteq \exists r.B, \ A \sqsubseteq \forall r.B
\]

where \(A, B, A_1, A_2\) are concept names and \(r\) is a role. It is well-known that every Horn-\(\text{ALCHIF}\) TBox \(T\) can be converted into a TBox \(T'\) in normal form (introducing additional concept names) such that \(T'\) is a logical consequence of \(T\) and every model of \(T\) can be extended to one of \(T'\) by interpreting the additional concept names, see e.g. [Bienvenu et al., 2016]. As a consequence, all results obtained in this paper for TBoxes in normal form lift to the general case.

2.2 Query Conservative Extensions and Entailment

A conjunctive query (CQ) is of the form \(q(x) = \exists y \varphi(x, y)\), where \(x\) and \(y\) are tuples of variables and \(\varphi(x, y)\) is a conjunction of atoms of the form \(A(v)\) or \(r(v, w)\) with \(A \in \text{NC}\), \(r \in \text{NR}\), and \(v, w \in \text{x u y}\). We call \(x\) answer variables and \(y\) quantified variables of \(q\). A CQ \(q\) is tree-shaped if it does not contain atoms of the form \(r(x, x)\) and the undirected graph \((\text{x u y}, \{\{v, w\} \mid r(v, w)\text{ is an atom in }q\})\) is a tree; tree-shaped CQs are thus connected and may contain multi-edges. A tree-shaped CQ \(q\) is strongly tree-shaped or an stCQ if the root is the one and only answer variable and \(q\) has no multi-edges, that is, for any distinct variables \(z, z'\) in \(q\), there is at most one role atom that contains both \(z\) and \(z'\).

A match of \(q\) in an interpretation \(I\) is a function \(\pi: \text{x u y} \rightarrow \Delta^I\) such that \(\pi(v) \in A^I\) for every atom \(A(v)\) of \(q\) and \((\pi(v), \pi(w)) \in r^I\) for every atom \(r(v, w)\) of \(q\). We write \(I \models q = a_1, \ldots, a_n\) if there is a match of \(q\) in \(I\) with \(\pi(x_i) = a_i\) for all \(i < n\). A tuple \(a\) of elements from \(\text{Ni}\) is a certain answer to \(q\) over an ABox \(A\) given a TBox \(T\), written \(T,A \models q(a)\), if \(I \models q(a)\) for all models of \(T\) and \(A\).

\(^1\)E.g., out of 439 available ontologies in BioPortal [Matentzoglu and Parsia, 2017], only 21 (\(\leq 4.8\%\)) contain the described pattern. A significant fraction of the occurrences of the pattern appear to be due to modeling mistakes.
We also consider the following lemma relates the two notions of CQ entailment.

Example 2 Let $\Gamma_1 = \{ \text{PhDStud} ⊑ \exists \text{AdvBy}, \text{Prof}, \text{adv} ⊑ \text{AdvBy}^{-} \}$ and $\Gamma_2 = \Gamma_1 \cup \{ \text{func}(\text{advBy}) \}$. $\Sigma = \{ \text{Prof} \}$ and $\Gamma = (\text{PhDStud}, \text{adv})$. Then $\Gamma_1 ⊑_{\Sigma, \Sigma} \Gamma_2$ because of the witness $(\text{PhDStud}(\text{john}), \text{adv}(\text{mary}, \text{john}))$. If we drop from Definition 1 the condition that $\Lambda$ must be consistent with both $\Gamma_1$ and $\Gamma_2$, then we obtain an alternative notion of CQ entailment that we call $CQ$ entailment with inconsistent ABoxes. While this new notion trivially implies CQ entailment in the original context, the converse fails.

Example 3 Let $\Gamma_1 = \emptyset, \Gamma_2 = \{ A_1 \cap A_2 \subseteq \perp \}$ and $\Sigma = \{ B \}$. Then $\Gamma_1 ⊑_{\Sigma, \Sigma} \Gamma_2$ but $\Gamma_1$ does not entail $\Gamma_2$ because of the witness of $\text{PhDStud}(\text{john}, \text{adv}(\text{mary}, \text{john}))$. If $\Gamma_1$ and $\Gamma_2$ are Horn-ACLF TBoxes, then $\Gamma_1 ⊑_{\Sigma, \Sigma} \Gamma_2$.

The following lemma relates the two notions of CQ entailment. CQ evaluation is the problem to decide, given a TBox $\mathcal{A}$, an ABox $\mathcal{A}$, a CQ $q$, and a tuple $a \in \text{ind}(\mathcal{A})$, whether $\mathcal{A} ⊑ q(a)$.

Lemma 4 CQ entailment with inconsistent ABoxes can be decided in polynomial time given access to oracles deciding CQ entailment and CQ evaluation.

Consequently and since CQ evaluation is in EXPTime in Horn-ACLF TBoxes [Lunter et al., 2008], all complexity results obtained in this paper also apply to CQ entailment with inconsistent ABoxes.

It is easy to see that $\Gamma_1 ⊑_{\Sigma, \Sigma} \Gamma_2$ if there is a $\Gamma$-role $r$ and a $\Sigma$-role $s$ with $\Gamma_2 \models r \subseteq s$ but $\Gamma_1 \not\models r \subseteq s$. We write $\Gamma_1 \models_{\Sigma, \Sigma} \Gamma_2$ if there is no such $r$ and $s$. Clearly, $\Gamma_1 \models_{\Sigma, \Sigma} \Gamma_2$ can be decided via $|\Gamma| \cdot |\Sigma|$ many Horn-ACLF TBox subsumption tests, thus in EXPTime [Tobies, 2001]. It is thus safe to assume $\Gamma_1 \models_{\Sigma, \Sigma} \Gamma_2$ when deciding CQ entailment, which we will generally do from now on to avoid dealing with special cases.

2.3 Deductive Conservative Extensions

Another natural notion of entailment is deductive entailment, which generalizes the notion of deductive conservatism to TBoxes [Ghilardi et al., 2006, Lutz et al., 2007; Konev et al., 2009, Lutz and Wolter, 2010], and which separates two TBoxes in terms of concept and role inclusions and functionality assertions, instead of ABoxes and queries.

Definition 5 Let $\Sigma$ be a signature and let $\mathcal{T}_2$ and $\mathcal{T}_2$ be $\Sigma$-deductive entailments of $\mathcal{T}_2$, written $\mathcal{T}_1 \models_{\Sigma, \Sigma} \mathcal{T}_2$, if for all $\Sigma$-ACLF $\mathcal{T}_1$-concept inclusions $\alpha$ and all $\Sigma$-RI$s$ and $\Sigma$-FA$s$ $\alpha$: $\mathcal{T}_2 \models \alpha$ implies $\mathcal{T}_1 \models \alpha$.

If additionally $\mathcal{T}_1 \subseteq \mathcal{T}_2$, then we say that $\mathcal{T}_2$ is a $\Sigma$-deductive conservative extension of $\mathcal{T}_1$. If $\mathcal{T}_1 \models_{\Sigma, \Sigma} \mathcal{T}_2$ and vice versa, then $\mathcal{T}_1$ and $\mathcal{T}_2$ are $\Sigma$-deductively inseparable.

Although closely related, it is not difficult to see that deductive and query entailment are orthogonal.

Example 6 (1) Let $\mathcal{T}_1, \mathcal{T}_2$ be as in Example 2 and $\Sigma = \{ A_1, A_2, B \}$. Then $\mathcal{T}_1 \models_{\Sigma, \Sigma} \mathcal{T}_2$, but $\mathcal{T}_2 \not\models_{\Sigma, \Sigma} \mathcal{T}_1$.

(2) Let $\mathcal{T}_1 = \emptyset$ and $\mathcal{T}_2 = \{ A \subseteq \exists r . B \}$, and $\Sigma = \{ A, B \}$. Then $\mathcal{T}_1 \models_{\Sigma, \Sigma} \mathcal{T}_2$, but $\mathcal{T}_2 \not\models_{\Sigma, \Sigma} \mathcal{T}_1$ as witnessed by $\{ (A(a)), \exists r . B(x, a) \}$, however $\mathcal{T}_1 \models_{\Sigma, \Sigma} \mathcal{T}_2$.

Nevertheless, the two notions are sufficiently closely related so that we have the following.

Lemma 7 In $\Sigma$-ACFL, deductive entailment can be decided in polynomial time given access to oracles for stCQ entailment and stCQ evaluation.

2.4 Homomorphisms and the Universal Model

For interpretations $\mathcal{I}_1, \mathcal{I}_2$ and a signature $\Sigma$, a $\Sigma$-homomorphism from $\mathcal{I}_1$ to $\mathcal{I}_2$ is a total function $h : \Delta_{\mathcal{I}_1} \rightarrow \Delta_{\mathcal{I}_2}$ such that (1) $h(a) = a$ for all $a \in \mathcal{N}_{\mathcal{I}_1}$, (2) $h(d) \in \Delta_{\mathcal{I}_2}$ for all $d \in \Delta_{\mathcal{I}_1}$, $A \in \mathcal{N}_{\mathcal{I}_1}$, and (3) $h(d, h(d')) \in \Delta_{\mathcal{I}_2}$ for all $(d, d') \in \Delta_{\mathcal{I}_1}$, $d \in \mathcal{N}_{\mathcal{I}_1}$, and $d' \in \Delta_{\mathcal{I}_1}$. If there is a $\Sigma$-homomorphism from $\mathcal{I}_1$ to $\mathcal{I}_2$, we write $\mathcal{I}_1 \rightarrow_{\Sigma} \mathcal{I}_2$.

Let $\mathcal{T}$ be a Horn-ACFL TBox in normal form and $\mathcal{A}$ an ABox consistent with $\mathcal{T}$. A type for $\mathcal{T}$ is a set $t \subseteq \text{sub}(T) \cap \mathcal{N}_{\mathcal{I}_1}$ such that $T \models t \subseteq A$ implies $A \in t$ for all concept names $A$. For $a \in \text{ind}(\mathcal{A})$, let $\text{tp}(a) = \{ A \mid \mathcal{T}, \mathcal{A} \models A(a) \}$ be the type of a relative to $\mathcal{T}$. When $a \in \text{ind}(\mathcal{A})$, $t, t'$ are types for $\mathcal{T}$, and $r$ is a role, we write

- $a \models_{r, \mathcal{T}} t$ if $T, A \models \exists r . \bigwedge t(a)$ and $t$ is maximal with this condition, and
- $t \models_{r, \mathcal{T}} t'$ if $T \models \bigwedge t \cap \exists r . t'$ and $t'$ is maximal with this condition.

A path for $\mathcal{T}$ and $\mathcal{A}$ is a finite sequence $\pi = a r_1 \cdots r_n t_n \in \mathcal{N}_{\mathcal{I}_1}$ such that $\mathcal{T} \models \bigwedge t \subseteq A$ implies $A \in t$ for all concept names $A$.

For every $1 \leq i < n$, we have $t_i \models_{r_i, \mathcal{T}} t_{i+1}$, and, if $\text{func}(r) \in \mathcal{T}$, then $r_{i-1} \not\models_r t_i$.

When $n > 0$, we use $\text{tail}(\pi)$ to denote $t_n$. Let Paths be the set of all paths for $\mathcal{T}$ and $\mathcal{A}$. The universal model $\mathcal{I}_{\mathcal{T}, \mathcal{A}}$ of $\mathcal{T}$ and $\mathcal{A}$ is defined as follows:

\[ \Delta_{\mathcal{I}_{\mathcal{T}, \mathcal{A}}} = \text{Paths} \]

\[ A^r_{\mathcal{I}_{\mathcal{T}, \mathcal{A}}} = \{ a \in \text{ind}(\mathcal{A}) \mid \mathcal{T}, \mathcal{A} \models A(a) \} \cup \{ \pi \in \Delta_{\mathcal{I}} \setminus \text{ind}(\mathcal{A}) \mid \mathcal{T} \models \bigwedge t \subseteq A \} \]

\[ r^r_{\mathcal{I}_{\mathcal{T}, \mathcal{A}}} = \{ (a, b) \in \text{ind}(\mathcal{A})^2 \mid s(a, b) \in \mathcal{A}, T \models s \subseteq r \} \cup \{ (\pi, s\pi) \mid s\pi \in \text{Paths} \land T \models s \subseteq r \} \cup \{ (s\pi, \pi) \mid s\pi \in \text{Paths} \land T \models s \subseteq r \} \]
of $T$ and $A$, we have $I \rightarrow I_{T,A}$. Consequently, $T, A \models q(a)$ iff $I_{T,A} \models q(a)$, for all CQs $q(x)$ and tuples $a$ of individuals.

We also need universal models of a TBox $T$ and a type $t$, instead of an ABox. More precisely, we define $I_{T,t} = I_{T,A_t}$, where $A_t = \{ A(a) \mid A \in t \}$ for a fixed $a \in N$.

### 3 Model-theoretic Characterization

We aim to provide a model-theoretic characterization of query entailment that will be the basis for our decision procedure later on. The first step towards this characterization consists in showing that non-entailment is always witnessed by tree-shaped ABoxes and tree-shaped CQs with at most one answer variable. Here, an ABox $A$ is tree-shaped if it does not contain an assertion of the form $r(a, a')$, the undirected graph $G_A = (\text{ind}(A), \{ \{a, b\} \mid r(a, b) \in A \})$ is a tree, and for any $a, b \in \text{ind}(A)$, $A$ contains at most one role assertion that involves both $a$ and $b$.

**Lemma 8** Let $T_1$ and $T_2$ be Horn-$\mathcal{ALCHIF}$ TBoxes with $T_1 \models R^I_{T_1 \Sigma} T_2$. If $T_1 \not\models C^I_{T_1 \Sigma} T_2$, then there is a witness $(A, q, a)$ where $A$ and $q$ are tree-shaped and $|a| \leq 1$, i.e., $q$ has at most one answer variable. If $T_1 \not\models C^I_{T_1 \Sigma} T_2$, then there is such a witness where additionally $q$ is an stCQ.

Our goal is to characterize query entailment in terms of homomorphisms between (universal) models. Homomorphisms are natural because answers to CQs are preserved under homomorphisms (both on interpretations and on ABoxes). In fact, they are preserved even under bounded homomorphisms if the bound is not smaller than the number of variables in the CQ.

Let $I_1, I_2$ be interpretations, $d \in A^T$, and $n \geq 0$. We say that there is an $n$-bounded $\Sigma$-homomorphism from $I_1$ to $I_2$, written $I_1 \rightarrow^\Sigma_n I_2$, if for any subinterpretation $I_1'$ of $I_1$ with $|\Delta I_1'| \leq n$, we have $I_1' \rightarrow^\Sigma I_2$. Moreover, we write $I_1 \rightarrow^\Sigma I_2$ if $I_1 \rightarrow^\Sigma_n I_2$ for any $n$. The following characterization follows from the definition of CQ entailment, Lemma 8, and the connection between CQs and suitably bounded homomorphisms.

**Lemma 9** Let $T_1$ and $T_2$ be Horn-$\mathcal{ALCHIF}$ TBoxes with $T_1 \models R^I_{T_1 \Sigma} T_2$. Then $T_1 \models C^I_{T_1 \Sigma} T_2$ iff for all tree-shaped $\Gamma$-ABoxes $A$ consistent with $T_1$ and $T_2$, $I_{T_1,A} \rightarrow^\Sigma_n I_{T_2,A}$. Ideally, we would like to use Lemma 9 as a basis for a decision procedure based on tree automata. To this end, it is useful that the ABox $A$ and models $I_{T_1,A}$ and $I_{T_2,A}$ in the lemma are tree-shaped. What is problematic is that Lemma 9 speaks about bounded homomorphisms, for any bound (corresponding to the bounded size of CQs), since it does not seem possible to verify such a condition using automata. We would thus like to replace bounded homomorphisms with unbounded ones, which does not compromise the characterization in the case of Horn-DLs without inverse roles [Lutz and Wolter, 2010, Botoeva et al., 2016c]. However, this is not true already for $\mathcal{ELT}$ TBoxes [Botoeva et al., 2016a].

**Example 10** Let $T_1 = \{ A \subseteq \exists s.B, B \subseteq \exists r^{-}B \}$, $T_2 = \{ A \subseteq \exists s.B, B \subseteq \exists rB \}$, $\Gamma = \{ A \}$, and $\Sigma = \{ r \}$. Then both $I_{T_1,A}$ and $I_{T_2,A}$ contain an infinite $r$-path; the $r$-path in $I_{T_1,A}$ has a final element while the one in $I_{T_2,A}$ does not. Hence $I_{T_2,A} \not\models^\Sigma I_{T_1,A}$ but $T_1 \models C^I_{T_1 \Sigma} T_2$ (see Thm. 11 below).

We now show that it is possible to refine Lemma 9 so that it makes a much more careful statement in which bounded homomorphisms are partly replaced by unbounded ones. It is then possible to check the unbounded homomorphism part of the characterization using tree automata as desired, and to deal with bounded homomorphisms using a mosaic technique that “precompiles” relevant information about unbounded homomorphisms to be used in the automaton construction.

We start with introducing relevant notation. For a signature $\Sigma$, we use $I_{\Sigma}^{\text{con}}$ to denote the restriction of the interpretation $I$ to those elements that can be reached from an ABox individual by traveling along $\Sigma$-roles (forwards or backwards). Tree-shaped interpretations are defined analogously to tree-shaped CQs (thus multi-edges are allowed). For a TBox $T$, an ABox $A$, and $a \in \text{ind}(A)$, we use $I_{T,A|a}$ to denote the subtree interpretation in the universal model $I_{T,A}$ rooted at $a$. A $\Sigma$-subtree in $I_{T,A}$ is a maximal tree-shaped, $\Sigma$-connected sub-interpretation $I$ of $I_{T,A}$ that does not comprise any ABox individuals. The root of $I$ is the (unique) element of $\Delta I$ that can be reached from an ABox individual on a shortest path among all element of $\Delta I$. The refined characterization uses simulations instead of homomorphisms for the stCQ case because they are insensitive to multi-edges. Given a signature $\Sigma$ and two interpretations $I, J$, a $\Sigma$-simulation of $I$ in $J$ is a relation $\sigma \subseteq \Delta I \times \Delta J$ such that: (1) $(a, a) \in \sigma$ for all $a \in N$, (2) if $a \in A^I$ with $A \in \Sigma$ and $(d, e) \in \sigma$, then $e \in A^J$, and $(3)$ if $(d, d') \in r^I$ with $r \in \Sigma$-role and $(d, e) \in \sigma$, then there is some $e'$ with $(e, e') \in r^J$ and $(d', e') \in \sigma$. We write $I \lessdot \Sigma J$ if there is a $\Sigma$-simulation of $I$ in $J$.

**Theorem 11** Let $T_1$ and $T_2$ be Horn-$\mathcal{ALCHIF}$ TBoxes with $T_1 \models R^I_{T_1 \Sigma} T_2$. Then $T_1 \models C^I_{T_1 \Sigma} T_2$ iff for all tree-shaped $\Gamma$-ABoxes $A$ consistent with $T_1$ and $T_2$, and for all tree-shaped, finitely branching models $I_1$ of $A$ and $T_1$, the following hold:

1. $I_{T_2,A}^{\text{con}} \models^\Sigma I_1$;
2. for all $\Sigma$-subtrees $I$ in $I_{T_2,A}$, one of the following holds:
   (a) $I \models^\Sigma I_1$;
   (b) $I \models^\Sigma \text{ind}(A)$.

Furthermore, $T_1 \models C^I_{T_1 \Sigma} T_2$ iff $I_{T_2,A}^{\text{con}} \models^\Sigma I_1$ for all $A$ and $I_1$ as above iff $I_{T_2,A}^{\text{con}} \models^\Sigma I_{T_1,A}$.

### 4 Decidability and Complexity

We prove that, in Horn-$\mathcal{ALCHIF}$, CQ entailment can be decided in $2\text{EXPTime}$. By existing lower bounds, the former is thus $2\text{EXPTime}$-complete in all fragments of Horn-$\mathcal{ALCHIF}$ that contain $\mathcal{ELT}$ or Horn-$\mathcal{ALC}$. Moreover, stCQ entailment in Horn-$\mathcal{ALCHIF}$ and deductive entailment in $\mathcal{ELHIF}_I$ can also be decided in $2\text{EXPTime}$. We establish a CON$\text{EXPTIME}$ lower bound and leave the precise complexity open.

To obtain the upper bounds, we use a combination of tree automata and mosaics to implement the characterization in Theorem 11. We start with a mosaic-based decision procedure for Condition (2b). Note that a $\Sigma$-subtree $I$ in $I_{T_2,A}$ can be uniquely identified by the type $t_2$ of its root. It therefore suffices to show the following.
Theorem 12 Given two Horn-ALCHIF TBoxes $\mathcal{T}_1$ and $\mathcal{T}_2$ and types $t_i$ for $\mathcal{T}_i$, $i \in \{1, 2\}$, it can be decided in time $2^{|\mathcal{I}(\mathcal{T}_1)|}$ whether $\mathcal{I}_{\mathcal{T}_1,t_1} \models \text{con} \rightarrow \text{fin} \mathcal{I}_{\mathcal{T}_2,t_2}$. Moreover, for a polynomial $p$, $\mathcal{I}_{\mathcal{T}_1,t_1}$ has a central idea for applying a mosaic approach to the set of all interpretations $\mathcal{I}$ obtained as a limit of this construction.

Lemma 13 Let $\mathcal{T}$ be a Horn-ALCHIF TBox, $t_0 \in \text{tp}(\mathcal{T})$, and $\mathcal{I}$ a tree-structured interpretation. Then $\mathcal{I} \models \text{fin} \mathcal{I}_{\mathcal{T},t_0}$ iff there is a $\mathcal{J} \in \text{can}_\omega(\mathcal{T}, t_0)$ with $\mathcal{I} \rightarrow \mathcal{J}$.

We can now use Lemma 13 to devise the mosaic-based procedure for deciding the existence of a bounded homomorphism. Let $\mathcal{T}_1, \mathcal{T}_2$ be as in Theorem 11. We denote with $\text{rol}(\mathcal{T}_1)$ the set of all roles $r, r^{-1}$ such that the (possibly inverse) role $r$ occurs in $\mathcal{T}_1$. Moreover, for a set of roles $\rho$, denote with $\rho;\Sigma$ the restriction of $\rho$ to $\Sigma$-roles.

Fix now some $t_1 \in \text{tp}(\mathcal{T}_1)$. Intuitively, a mosaic for $t_1$ represents a possible 1-neighborhood of some element in $\mathcal{I}_{\mathcal{T}_1,t_1}$ together with a decoration with sets of types for $\mathcal{T}_2$ that can be homomorphically embedded into the neighborhood. Formally, a mosaic for $t_1$ is a tuple $\mathcal{M} = (t^{-}, \rho, t, S, t)$ such that $(t^{-}, \rho, t, S) = t_1 \times \text{rol}(\mathcal{T}_1)$ for some $d \in \Delta_{\mathcal{I}}$, $t_1$ contains an element of the same type as the root that has such a predecessor, and so on, ad infinitum. We will now make this precise.

An interpretation $\mathcal{I}$ is quasi tree-shaped if:
1. $\Delta_{\mathcal{I}} \subseteq \{-1\} \cup \mathbb{N}$;
2. $d, e \in \Delta_{\mathcal{I}}$ implies that $d = e \cdot c$ or $d = e \cdot c$ for some $c \in \{-1\} \cup \mathbb{N}$.

For $d, e \in \Delta_{\mathcal{I}}$, we say that $e$ is a successor of $d$ if $e = d \cdot c$ for some $c \in \mathbb{N}$ or $d = e \cdot -1$. This convention, quasi tree-shaped interpretations can be viewed as directed graphs. The directedness does not correspond to the distinction between roles and inverse roles; in particular, there can be several role edges in both directions between the same $d$ and $e$. Quasi tree-shaped interpretations can be viewed as a finite or infinite trees that need not have a root as they can extend indefinitely not only downwards but also upwards.

Let $\mathcal{T}$ be a Horn-ALCHIF TBox and let $\text{tp}(\mathcal{T})$ be the set of all types for $\mathcal{T}$ consistent with $\mathcal{T}$. For every $t_0 \in \text{tp}(\mathcal{T})$, we use $\text{tp}(\mathcal{T}, t_0)$ to denote the set of all $t \in \text{tp}(\mathcal{T})$ that occur in the universal model $\mathcal{I}_{\mathcal{T},t_0}$ of $t_0$ and $\mathcal{T}$. Furthermore, given a quasi tree-shaped interpretation $\mathcal{I}$ and an element $d \in \Delta_{\mathcal{I}}$, the $\ell$-neighborhood of $d$ in $\mathcal{I}$ is a tuple $n_d^\ell(d) = (t^{-}, \rho, t, S)$ such that (a) $t = \text{tp}_d(d)$; (b) if there is a predecessor $d_0 \in \Delta_{\mathcal{I}}$ of $d$, then $t^{-} = \text{tp}_d(d_0)$ and $\rho = \{ r \mid (d_0, d) \in r^\ell \}$, otherwise $\rho = \emptyset$; (c) $S$ is the set of all pairs $(\rho', t')$ such that there is a successor $d'$ of $d$ such that $t' = \text{tp}_d'(d')$ and $\rho' = \{ r \mid (d, d') \in r^\ell \}$. We write $(t_1, \rho_1, t_1, S_1) \subseteq (t_2, \rho_2, t_2, S_2)$ if $t_1 \subseteq t_2, S_1 \subseteq S_2$ and, if $\rho_1 \neq \emptyset$, then $\rho_1 = \rho_2$ and $t_1 = t_2$.

In the following, we define a class $\text{can}_\omega(\mathcal{T}, t_0)$ of quasi tree-shaped models of $\mathcal{T}$. To construct a model from this class, choose a type $t \in \text{tp}(\mathcal{T}, t_0)$ and define $\mathcal{I} = ((d_0), \Delta_{\mathcal{I}})$ such that $\text{tp}_d(d_0) = t$. Then extend $\mathcal{I}$ by applying the following rule exhaustively in a fair way:

(R) Let $d \in \Delta_{\mathcal{I}}$. Choose some $e \in \Delta_{\mathcal{I}}$ such that $n_1^\ell(d) \subseteq n_1^\ell(e)$, and add to $d$ the predecessor and/or successors required to achieve $n_1^\ell(d) = n_1^\ell(e)$.

The potentially infinite class $\text{can}_\omega(\mathcal{T}, t_0)$ is the set of all interpretations $\mathcal{I}$ obtained as a limit of this construction.

Lemma 14 Let $t_i \in \text{tp}(\mathcal{T}_i)$ for $i \in \{1, 2\}$. Then there is a $\mathcal{J} \in \text{can}_\omega(\mathcal{T}_1, t_1)$ such that $\mathcal{I}_{\mathcal{T}_1,t_1} \models \text{con} \rightarrow \text{fin} \mathcal{I}_{\mathcal{T}_2,t_2}$. If $\mathcal{M}$ contains a mosaic $\mathcal{M}_p$ with $\mathcal{T}_2 \subseteq \text{tp}(\mathcal{M}_p)$.

Since there are at most $2^{|\mathcal{T}|^2}$ mosaics for $t_1$, we obtain the desired theorem.

We now develop the decision procedure for CQ and stCQ entailment in Horn-ALCHIF $\mathcal{F}$, based on Theorems 11 and 12.

Our main tool are alternating two-way tree automata with counting (2ATA$_c$), an extension of alternating tree automata over unranked trees (Grädel and Walukiewicz, 1999) with the ability to count. A tree is a non-empty (potentially infinite)
We aim to show that one can construct a 2ATA ABox element without having access to the anonymous (Θ = 2

is some successor of the current type in tree I is not a node labeling function.

A 2ATA, is a tuple \( (Q, \Theta, q_0, \delta, \Omega) \) where Q is a finite set of states, \( \Theta \) is the input alphabet, \( q_0 \) is the initial state, \( \delta \) is a transition function, and \( \Omega : Q \rightarrow \mathbb{N} \) is a priority function. The transition function \( \delta \) maps every state q and input letter \( a \in \Theta \) to a positive Boolean formula \( \delta(q, a) \) over the truth constants true and false and transition atoms of the form \( q, \neg q, \neg q \land \neg q \). Informally, a transition q expresses that a copy of \( A \) is sent to the current node in state q; \( \neg q \) means that a copy is sent in state q to the predecessor node which is required to exist; \( \neg q \land \neg q \) means that the predecessor node is not required to exist; \( \neg q \) (resp., \( \neg q \)) means that a copy of q is sent to n (resp., to all but n) successors. The semantics of 2ATA, is given in terms of runs as usual, please see the appendix. We use \( L(\mathfrak{A}) \) to denote the set of trees accepted by \( \mathfrak{A} \). It is standard to verify closure of 2ATA, under intersection. The following is obtained via reduction to standard alternating parity tree automata [Vardi 1998].

**Theorem 15.** The emptiness problem for 2ATA, can be solved in time exponential in the number of states.

Let \( T_1, T_2 \) be Horn-\( \mathcal{ALCHF} \) TBoxes and \( \Gamma, \Sigma \) signatures. We aim to show that one can construct a 2ATA, \( \mathfrak{A} \) such that \( L(\mathfrak{A}) \neq \emptyset \) iff \( T_1 \not\models_{\Sigma-CQ} T_2 \). In fact, \( \mathfrak{A} \) is the intersection of four 2ATA, \( \mathfrak{A}_1, \mathfrak{A}_2, \mathfrak{A}_3, \mathfrak{A}_4 \). They run over \( \Theta \)-labeled trees with \( \Theta = 2^{|\delta|} \times 2^{|\delta|} \times 2^{|\delta|} \), where \( \Theta_0 = \Gamma \cup \{ r \mid r \in \Gamma \} \) and \( \Theta_i = \text{sig}(T_i) \cup \{ r \mid r \in \text{sig}(T_i) \} \) for \( i = 1, 2 \). For a \( \Theta \)-labeled tree \( (T, L) \), we use \( L_{i}, i \in \{0, 1, 2\} \) to refer to the i-th component of L, that is, \( L(n) = (L_0(n), L_1(n), L_2(n)) \), for all n ∈ T. The component \( L_0 \) represents a (possibly infinite) ABox \( A = \{ A(n) \mid A \in L_0(n) \} \cup \{ r(n \rightarrow 1, n) \mid n \in E, r \in L_0(n) \} \), where \( r(a, b) \) is identified with \( r(b, a) \). The 2ATA, \( \mathfrak{A}_2 \) accepts a \( \Theta \)-labeled tree \( (T, L) \) iff \( A \) is finite, tree-shaped (and thus connected) and includes the root of T, and it is straightforward to construct.

Components \( L_1, L_2 \) give rise to interpretations \( I_1 = (T, \mathcal{A}_1^I), I_2 = (\text{ind}(A), \mathcal{A}_2^I) \), where for \( i \in \{1, 2\} \):

\[
\mathcal{A}_1^I = \{ A \mid A \in L_1(n) \}
\]

\[
\mathcal{A}_2^I = \{ (n, n \rightarrow 1) \mid r \in L_1(n) \} \cup \{ (n \rightarrow 1, n) \mid r \in L_1(n) \}
\]

\( \mathfrak{A}_2 \) verifies that \( I_1 \) is a model of \( \mathfrak{A} \) and \( T_1 \) which is standard, too. \( \mathfrak{A}_3 \) verifies that \( \mathfrak{A} \) is consistent with \( T_2 \), and \( I_2 \) is \( \mathfrak{I}_{T_2, A} \) restricted to \( \text{ind}(A) \). This involves computing the type of an ABox element without having access to the anonymous (that is: non-ABox) part of \( \mathfrak{I}_{T_2, A} \), using a characterization of ABox entailments [Bienvenu et al., 2013] in terms of derivation trees. Finally, \( \mathfrak{A}_4 \) verifies that either (1) or (2) from Theorem 11 is not satisfied. For (1), \( \mathfrak{A}_4 \) sends a copy of itself to every tree \( I \) starting at an ABox element in \( \mathfrak{I}_{T_2, A} \), and attempts to show that \( I \) cannot be homomorphically embedded into a corresponding tree in \( I_1 \). This attempt is successful if either incompatible types are found in the root or, recursively, there is some successor of the current type in \( \mathfrak{I}_{T_2, A} \) that cannot be mapped to any neighbor in \( I_1 \). Since the anonymous part of \( \mathfrak{I}_{T_2, A} \) is not explicit in the input, the current type is stored in the states, and the generating relation \( t \rightarrow t' \) is “hard-coded” into the transition function. For Condition (2a), \( \mathfrak{A}_4 \) non-deterministically guesses a \( \Sigma \)-subtree \( I \) and proceeds as in (1); Condition (2b) is verified based on Theorem 12 by pre-computing \( r_{\Sigma, \eta}^{-1} \). Thus the number of states of \( \mathfrak{A}_4 \) is exponential in \( |T_2| \) (because of the types) but only polynomial in \( |T_1| \). Automata \( \mathfrak{A}_1, \mathfrak{A}_2, \mathfrak{A}_3 \) have polynomially many states.

In the special case of stCQ entailment, we simply replace \( \mathfrak{A}_4 \) with a 2ATA, \( \mathfrak{A}_4' \) that refutes the simulation condition of Theorem 11 analogously to how \( \mathfrak{A}_4 \) refutes Condition (1).

To obtain the desired upper complexity bounds for query and deductive entailment, we observe that, in both cases, \( \mathfrak{A}_4 \) can be constructed in time polynomial in \( |T_1| \) and exponential in \( |T_2| \), and the emptiness check adds an exponential blowup (Theorem 15). For deductive entailment, we use the reduction to stCQ entailment (Lemma 7).

**Theorem 16.** In Horn-\( \mathcal{ALCHF} \), the following problems can be decided in time \( 2^{O(|T_2| \log |T_1|)} \), p a polynomial: (\( \Gamma, \Sigma \))-CQ entailment, \( (\Gamma, \Sigma) \)-CQ inseparability, and \( (\Gamma, \Sigma) \)-CQ conservative extensions. The same holds for \( \Sigma \)-deductive entailment, \( \Sigma \)-deductive inseparability, and \( \Sigma \)-deductive conservative extensions in \( \mathcal{ELHIF} \).

Matching lower bounds for all problems except deductive entailment are provided by [Botoeva et al., 2016c]. They hold even in the case where \( \Gamma = \Sigma \).

**Corollary 17.** In any fragment of Horn-\( \mathcal{ALCHF} \) that contains \( \mathcal{ELI} \) or Horn-\( \mathcal{ALC} \), the following problems are \( 2\mathit{EXPTIME} \)-complete: \( (\Gamma, \Sigma) \)-CQ entailment, \( (\Gamma, \Sigma) \)-CQ inseparability, and \( (\Gamma, \Sigma) \)-CQ conservative extensions.

In the description logic \( \mathcal{EL} \), which is \( \mathcal{EL} \) without inverse roles, deductive conservative extensions and deductive \( \Sigma \)-entailment are \( \mathit{EXPTIME} \)-complete [Lutz and Wolter, 2010]. This raises the question whether the upper bound for deductive entailment reported in Theorem 15 is tight. While we leave this question open, we observe that the transition from \( \mathcal{EL} \) to \( \mathcal{EL} \) does increase the complexity of deductive conservative extensions and related problems to at least \( \mathcal{CONEXPTIME} \). We consider this a surprising result since in reasoning problems that are not defined in terms of conjunctive queries, adding inverse roles does typically not result in an increase of complexity. The following is established by a non-trivial reduction of a tiling problem.

**Theorem 18.** In any DL between \( \mathcal{ELI} \) and \( \mathcal{ELHIF} \), deductive conservative extensions, deductive \( \Sigma \)-entailment, and deductive \( \Sigma \)-inseparability are \( \mathcal{CONEXPTIME} \)-hard.

5 Conclusion

As future work, it would be interesting to close the gap in complexity between \( \mathcal{CONEXPTIME} \) and \( 2\mathit{EXPTIME} \) for deductive entailment in \( \mathcal{ELI} \) and \( \mathcal{ELHIF} \). Furthermore, it would be interesting to extend the results to ontology languages from the family of Datenlog-in (aka existential rules), in particular to frontier-guarded TGDs.
Acknowledgments
This work was partially supported by DFG project LU 1417/2 and ERC Consolidator Grant 647289 CODA.

References


A  Proofs for Section 2

A.1  Additional Definitions and Properties

If an interpretation \( I \) is a common model of a TBox \( T \) and ABox \( A \), then we also write \( I \models (T, A) \) and call \( I \) a model of \((T, A)\).

The following is standard to prove.

**Lemma 19** For every Horn-A\(\text{LCCH} \) TBox \( T \) in normal form and ABox \( A \) consistent with \( T \), the following hold:

1. \( I_{T,A} \models (T, A) \).
2. For all models \( I \) of \((T, A)\), we have \( I_{T,A} \rightarrow I \).
3. For all types \( t, t' \) for \( T \) with \( t \subseteq t' \), we have \( I_{T,t} \rightarrow I_{T,t'} \).
4. \( T, A \models q(a) \) iff \( I_{T,A} \models q(a) \), for all CQs \( q(x) \) and tuples \( a \) of individuals.

In the following subsections, we need to deal with the question whether any \( \Gamma \)-ABox that is inconsistent with some TBox \( T_2 \) is inconsistent with another TBox \( T_1 \). We say that \( T_1 \) \( \Gamma \)-inconsistency entails \( T_2 \), written \( T_1 \models^= T_2 \), if for all \( \Gamma \)-ABoxes \( A \): if \( A \) is inconsistent with \( T_2 \), then \( A \) is inconsistent with \( T_1 \).

A.2  Proof of Lemma 4

**Lemma 4** CQ entailment with inconsistent ABoxes can be decided in polynomial time given access to oracles deciding CQ entailment and CQ evaluation.

To prove Lemma 4 we proceed in two steps: first, we show how to deal with inconsistency entailment as defined in Section A.1; second we show how to use this type of entailment to deal with CQ entailment with inconsistent ABoxes.

For the first step, we can reduce inconsistency entailment to CQ entailment because, if \( A \) is inconsistent with \( T_1 \), then either (a) \( I_{T,A} \) contains a B-instance for some \( B \subseteq \bot \subseteq T \), or (b) \( A \) contains a "fork" \( \{r(a, b), r(a, c)\} \) that is prohibited by \( \text{func}(r) \). We write \( T_1 \models^\forall \bot \models^= T_2 \) if for all \( \Gamma \)-ABoxes \( A \) \( \{r(a, b), r(a, c)\} \) is prohibited. If \( A \) is inconsistent with \( T_2 \), then also with \( T_1 \). Thus, if we have a witness ABox \( A \) for \( T_1 \models^= T_2 \), then \( A \) is inconsistent with \( T_2 \) either by Case (a) – which we can detect via CQ entailment if we allow a fresh concept name in the CQ and slightly modify the TBoxes – or by Case (b), which implies \( T_1 \models T_2 \).

**Lemma 20** Let \( \Gamma \) be a signature and let \( T_1 \) and \( T_2 \) be Horn-A\(\text{LCCH}\) TBoxes. Furthermore, let \( A \) be a fresh concept name and \( T_1^A \) be obtained from \( T_1 \) by replacing each occurrence of \( \bot \) with \( A \) and adding the axioms \( \exists s . A \subseteq A \) and \( \exists s^- . A \subseteq A \) for every role \( s \) occurring in \( T_1 \). Then the following are equivalent:

1. \( T_1 \models T_2 \)
2. \( T_1^A \models^{\forall \text{q}} T_2^A \) and \( T_1 \models^{\forall \text{fork}} T_2 \)
3. \( T_1^A \models^{\forall \text{stq}} T_2^A \) and \( T_1 \models^{\forall \text{fork}} T_2 \)

Note that we only need the equivalence between (1) and (2) to prove Lemma 4. However, we will need (3) later to prove Lemma 4. Indeed, (2) and (3) are obviously equivalent given the primitive query signature \( \{A\} \) and the propagation of \( A \) throughout the \( T_1^A \).

**Proof.**

"1 \( \Rightarrow \) 2": We prove the contrapositive. Assume \( T_1^A \not\models^{\forall \text{q}} T_2^A \) or \( T_1 \not\models^{\forall \text{fork}} T_2 \). In case \( T_1 \not\models^{\forall \text{fork}} T_2 \), every witness ABox \( A \) is a witness for \( T_1 \not\models T_2 \).

In case \( T_1^A \not\models^{\forall \text{q}} T_2^A \) is violated, consider a witness \( \langle A, q, a \rangle \). Since \( A \) is the only symbol allowed in \( q \), all atoms of \( q \) have the form \( A(z) \) for arbitrary variables \( z \). If \( q \) consists of several atoms, then it is disconnected and we can omit all but one atom from \( q \) and still have a witness (see also proof of Lemma 8 Property 4). Hence we can assume w.l.o.g. that \( q \) is of the form (i) \( q(x) = A(x) \) or (ii) \( q() = \exists y A(y) \) and, furthermore, that \( A \) and thus the universal models \( I_{T,A} \) are connected. (Due to the "propagation" of \( A \) in \( T_1 \), we can even assume that \( q \) is of the form (i) only, but that does not matter in the following argumentation.) We now have:

- \( A \) is inconsistent with \( T_2 \):
  Assume to the contrary that \( A \) is consistent with \( T_2 \) and consider the universal model \( I_{T_2,A} \) for \( T_2 \) and \( A \) (Section 2.3). Clearly, for all domain elements \( d \) of \( I_{T_2,A} \), we have \( T_2 \not\models \top \models^\forall \text{tp}_{I_{T_2,A}}(d) \subseteq A \). Since \( A \) is fresh and by the definition of \( T_2^A \) we get \( T_2^A \not\models \top \models^\forall \text{tp}_{I_{T_2,A}}(d) \subseteq A \).

Now Lemma 19(1) for \( T_2^A \) implies that \( I_{T_2,A} \models I_{T_2} \); hence \( I_{T_2,A} \) satisfies all axioms in \( T_2^A \) that have been taken over from \( T_2 \) without modification, i.e., all axioms that are not of the form \( B \subseteq A \). But axioms of the latter form are also satisfied because \( T_2^A \not\models \top \models^\forall \text{tp}_{I_{T_2,A}}(d) \subseteq A \) for every domain element \( d \). Hence \( I_{T_2,A} \models I_{T_2} \).

Now, since \( I_{T_2,A} \) has no A-instance, we cannot have \( T_2^A \models \top \models^\forall \text{tp}_{I_{T_2,A}}(d) \not\subseteq A \) for every domain element \( d \). Since \( A \) is fresh, we have \( T_2 \not\models \top \models^\forall \text{tp}_{I_{T_2,A}}(d) \not\subseteq A \). With the same reasoning as above, we get \( I_{T_2,A} \models (T_1,A) \); hence \( A \) is consistent with \( T_1 \).

Consequently \( T_1 \not\models T_2 \), as desired.

"2 \( \Rightarrow \) 3": This is immediate because \( T_1^A \models^{\forall \text{q}} T_2^A \) implies \( T_1^A \models^{\forall \text{stq}} T_2^A \).

"3 \( \Rightarrow \) 1": We prove the contrapositive. Assume \( T_1 \not\models T_2 \), i.e., there is a \( \Gamma \)-ABox \( A \) that is inconsistent with \( T_2 \) but consistent with \( T_1 \). We need to show that \( T_1^A \not\models^{\forall \text{stq}} T_2^A \) or \( T_1 \not\models^{\forall \text{fork}} T_2 \).
From $\mathcal{A}$ being inconsistent with $\mathcal{T}_2$, we first conclude that one of the following two properties must hold.

(i) There is some $d \in B^{T_{2A}}$ with $B \subseteq \perp \subseteq T_2$.

(ii) $\mathcal{A}$ contains a "fork" $\mathcal{A}' = \{r(a, b), r(a, c)\}$ such that $\mathcal{A}'$ is inconsistent with $\mathcal{T}_2$.

Indeed, if neither (i) nor (ii) holds, then we have $\mathcal{I}_{T_2, \mathcal{A}} \models (T_2, \mathcal{A})$, contradicting the inconsistency of $\mathcal{A}$ with $\mathcal{T}_2$: First, $\mathcal{I}_{T_2, \mathcal{A}} \models \mathcal{A}$ follows directly from the construction of $\mathcal{I}_{T_2, \mathcal{A}}$. Second, $\mathcal{I}_{T_2, \mathcal{A}} \models \mathcal{T}_2$ can be shown analogously to the (omitted) standard proof of Lemma 19, via a case distinction over the axioms in $\mathcal{T}_2$, using "not (i)" and "not (ii)" instead of the assumption that $\mathcal{A}$ is consistent with $\mathcal{T}_2$.

Now first assume that (ii) holds. Since $\mathcal{A}$ is consistent with $\mathcal{T}_1$, so is $\mathcal{A}'$. Hence $T_1 \not|= T_{\forall \fork}$. In case (ii) does not hold, (i) must hold. To show that $T_{\forall \mathcal{A}} \not|= \mathcal{A}^\forall$ consider the stCQ $q = A(x)$ and some $a \in \text{ind}(\mathcal{A})$ to which the element $d$ from (i) is connected in $\mathcal{I}_{T_2, \mathcal{A}}$, i.e., if $d \in \text{ind}(\mathcal{A})$, then choose $a = d$; otherwise choose $a$ such that $d$ is in the subtree $\mathcal{I}_{T_2, \mathcal{A}|a}$. We then have:

- $\mathcal{A}$ is consistent with $\mathcal{T}_2^\forall$:
  
  Since $T_{\forall \mathcal{A}}$ does not contain $\perp$ and $\mathcal{A}$ does not contain forks as in (ii), $\mathcal{A}$ is consistent with $T_{\forall \mathcal{A}}$ is consistent, as witnessed by the universal model $\mathcal{I}_{T_{\forall \mathcal{A}}}$ (we again refer to the standard proof of Lemma 19, except that the FA case in the ABox part of $\mathcal{I}_{T_{\forall \mathcal{A}}}$ is now due to "not (ii)"

- $\mathcal{A}$ is consistent with $\mathcal{T}_1^\forall$:
  
  It is not difficult to see that $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}} \models (T_1^\forall, \mathcal{A})$: From $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}} \models (T_1, \mathcal{A})$, it follows that $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}}$ is a model of $\mathcal{A}$ and satisfies all axioms in $T_1^\forall$, which $\mathcal{T}_1$ shares with $\mathcal{T}_1$. The modified axioms $B \subseteq \mathcal{A}$ with $B \subseteq \perp \subseteq \mathcal{T}_1$ are satisfied, too, because $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}}$ cannot have any $B$-instances. Finally, the additional propagation axioms are satisfied because $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}}$ has no $A$-instance as $A$ is fresh.

- $T_{\forall \mathcal{A}}, \mathcal{A} \models q(a)$:
  
  Due to (i), we have $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}} \models \exists y B(y)$ for some $B \subseteq \perp \subseteq T_2$. Hence $\mathcal{I}_{\mathcal{T}_2, \mathcal{A}} \models \exists y B(y)$, which follows from the construction of both universal models (in fact the only difference between $\mathcal{I}_{T_{\forall \mathcal{A}}, \mathcal{A}}$ and $\mathcal{I}_{T_{\forall \mathcal{A}}} \models \exists y B(y)$, which follows from the construction of both universal models (in fact the only difference between $\mathcal{I}_{T_{\forall \mathcal{A}}, \mathcal{A}}$ and $\mathcal{I}_{T_{\forall \mathcal{A}}}$ may be A-instances).

Hence $\mathcal{I}_{T_{\forall \mathcal{A}}, \mathcal{A}}$ has a $B$-instance in the subtree $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}|a}$ and thus, by construction, an $A$-instance. By the "propagation" of $\mathcal{A}$ in $T_{\forall \mathcal{A}}$, we have that $\mathcal{A}$ is an instance of $\mathcal{A}$ in $\mathcal{I}_{T_{\forall \mathcal{A}}, \mathcal{A}}$; hence $\mathcal{I}_{T_{\forall \mathcal{A}}, \mathcal{A}} \models A(a) = q$.

- $T_{\forall \mathcal{A}}, \mathcal{A} \not|= q(a)$:
  
  Follows from $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}} \models (T_1^\forall, \mathcal{A})$ (as shown above) and $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}} \not|= q(a)$ (given the lack of $A$-instances).

Proposition 21 Fork entailment $T_1 \not|= T_2$ can be (Turing) reduced in polynomial time to stCQ evaluation.

Proof. Perform 2 many ABoxes consistency checks by evaluating the stCQ $A(a)$ on both $\mathcal{T}_2$, where $A$ is a concept name that does not occur in any of the $\mathcal{T}_i$.

For the second step, we can now reduce CQ entailment with inconsistent ABoxes to the disjunction of our original notion of CQ entailment and inconsistency entailment. We need an additional notion: Given a TBox $\mathcal{T}$ and signatures $\Gamma, \Sigma$, we say that $\mathcal{T}$ is ($\Gamma, \Sigma$)-universal if

(*) for all $\Gamma$-ABoxes $\mathcal{A}$ and $\Sigma$-CQs $q(x)$ and all tuples $a \subseteq \text{ind}(\mathcal{A})$ with $|a| = |x|$, we have $T, \mathcal{A} \models q(a)$.

Lemma 22 Let $\Gamma, \Sigma$ be signatures and let $\mathcal{T}_1$ and $\mathcal{T}_2$ be Horn-ACCHorn TBoxes. Then $\mathcal{T}_1 \models (\Gamma, \Sigma)$-CQ entails $\mathcal{T}_2$ with inconsistent ABoxes if one of the two following conditions holds.

1. $\mathcal{T}_1 \models^{\forall \Sigma} \mathcal{T}_2$ and $\mathcal{T}_1 \models^{\forall \Gamma} \mathcal{T}_2$.

2. $\mathcal{T}_1 \not|= (\Gamma, \Sigma)$-universal.

Proof. We prove both implications via contraposition.

"$\Rightarrow$". Assume (1) and (2) are both false, i.e., $\mathcal{T}_1$ is not ($\Gamma, \Sigma$)-universal and either (a) $\mathcal{T}_1 \not|= \mathcal{T}_2$, or (b) $\mathcal{T}_1 \not|= \Gamma$. In case (a), $\mathcal{T}_1$ trivially does not ($\Gamma, \Sigma$)-CQ entail $\mathcal{T}_2$ with inconsistent ABoxes. In case (b), consider a witness $\Gamma$-ABox $\mathcal{A}$. Since $\mathcal{T}_1$ is not ($\Gamma, \Sigma$)-universal, there is a $\Gamma$-ABox $\mathcal{A}'$, a $\Sigma$-CQ $q(x)$ and a tuple $a \subseteq \text{ind}(\mathcal{A}')$ with $|a| = |x|$ such that $\mathcal{T}_1, \mathcal{A}' \not|= q(a)$. We assume w.l.o.g. that $\mathcal{A}$ and $\mathcal{A}'$ use distinct sets of individuals. We set $\mathcal{A}'' = \mathcal{A} \cup \mathcal{A}'$ and have:

- $\mathcal{T}_2, \mathcal{A}'' \models q(a)$ because $\mathcal{A}$ is inconsistent with $\mathcal{T}_2$ and so is $\mathcal{A}''$.

- $\mathcal{T}_1, \mathcal{A}' \not|= q(a)$: let $\mathcal{F}$ be the disjoint union of the universal model $\mathcal{I}_{\mathcal{T}_1, \mathcal{A}'}$ and the model $\mathcal{I}$ witnessing $\mathcal{T}_1, \mathcal{A}' \not|= q(a)$. Clearly $\mathcal{F} \models (\mathcal{T}_1, \mathcal{A}'')$ but $\mathcal{F} \not|= q(a)$.

Hence $\mathcal{T}_1$ does not ($\Gamma, \Sigma$)-CQ entail $\mathcal{T}_2$ with inconsistent ABoxes, as desired.

"$\Leftarrow$". Assume $\mathcal{T}_1$ does not ($\Gamma, \Sigma$)-CQ entail $\mathcal{T}_2$ with inconsistent ABoxes and consider a witness $(\mathcal{A}, q, a)$. Then it is immediate that (2) does not hold. Furthermore, if $\mathcal{A}$ is consistent with both $\mathcal{T}_1$ and $\mathcal{T}_2$, then $\mathcal{T}_1 \not|= \mathcal{T}_2$. Otherwise $\mathcal{A}$ must be inconsistent with $\mathcal{T}_2$ but consistent with $\mathcal{T}_1$; hence $\mathcal{T}_1 \not|= \mathcal{T}_2$. Therefore (1) does not hold either.

Proposition 23 ($\Gamma, \Sigma$)-universality can be (Turing) reduced in polynomial time to stCQ evaluation.

Proof. It suffices to check Condition (*) above (i) for all singleton $\Gamma$-ABoxes $\{A(a)\}$ and all single-atom $\Sigma$-CQs $B(x)$ or $r(x, x)$, and (ii) for all two-element $\Gamma$-ABoxes $\{r(a, b)\}$ and all $\Sigma$-CQs as in (i) but with possibly two distinct answer variables.
A.3 Proof of Lemma 7

Lemma 7 In $\mathcal{ELHI}^\mathcal{F}_I$, deductive entailment can be decided in polynomial time given access to oracles for stCQ entailment and stCQ evaluation.

Lemma 7 is an immediate consequence of the following lemma because the additional $T_1 \models^R \Sigma \models T_2$ can be reduced to stCQ entailment and stCQ evaluation via Lemma 20.

Lemma 24 Let $\Sigma$ be a signature and $T_1, T_2 \in \mathcal{ELHI}^\mathcal{F}_I$ TBoxes such that $T_1 \models^\mathcal{ELHI}^\mathcal{F}_I T_2$. Then $T_1 \models^\Sigma T_2$ iff $T_1 \models^{stCQ} T_2$ and $T_1 \models^\perp T_2$.

Proof. We prove both implications via contraposition.

\(\Leftarrow\). We assume that $T_1 \models^\Sigma \Sigma \models T_2$. In this case this is witnessed by a $\Sigma$-FA $\text{func}(r)$, we immediately get a witness $\Sigma\text{-ABox} = \{r(a,b), r(a,c), \} \times T_1 \models^\perp T_2$ and are done.

Otherwise, $T_1$ contains all $\Sigma$-FAs from $T_2$, and there is a witness $\Sigma\text{-CI} C \subseteq D$ (witness RIs are excluded by the assumption $T_1 \models^R \Sigma \models T_2$). Since $\mathcal{ELHI}_I$-concepts that contain $\perp$ are equivalent to $\perp$, the left-hand side $C$ cannot contain $\perp$ (i.e., is an $\mathcal{EL}$ concept) and, if $D$ does, then $C \subseteq \perp$ is a witness. We show that such witnesses give rise to either a witness $A_C$ for $T_1 \models^\perp T_2$ or a witness $(A_C, q_d, a)$ for $T_1 \models^{stCQ} T_2$ with $q_d(a)$ an stCQ.

We first consider the case that there is a witness $C \subseteq \perp$ with $C$ an $\mathcal{EL}$ concept. We can construct from $C$ in the obvious way a tree-shaped $\Sigma$-ABox $A_C$ and root $a$: $A_C$ reflects the tree structure of $C$; however, to respect the $\Sigma$-FAs in $T_1$ (and thus those in $T_2$), we need to merge the subtrees of all nodes that are $r$-neighbors of the same node, whenever $\text{func}(r) \in T_1$. Consider the universal model $I_{T_2, A_C}$ and observe that $a \in C^{T_2, A_C}$ from the construction of $I_{T_2, A_C}$. Since $T_2 \models C \subseteq \perp$, we have that $I_{T_2, A_C}$ is not a model of $T_2$. Hence, by the contraposition of Lemma 19, $A_C$ is inconsistent with $T_2$. On the other hand, since $T_1 \models C \subseteq \perp$, there is a model $I \models T_1$ and an instance $d \in C^I$. We can turn $I$ into a model of $A_C$ by interpreting the ABox individuals accordingly ("partial" unraveling might be necessary to ensure that the standard name assumption is respected), witnessing the consistency of $A_C$ with $T_1$. We thus have $T_1 \models^\perp T_2$ and are done.

In the second case, all witnesses $C \subseteq D$ consist solely of $\mathcal{EL}$ concepts $C$. We construct the same ABox $A_C$ with root $a$ from $C$ and transform $D$ into a $\Sigma$-stCQ $q_d(x)$ with a single answer variable that represents the tree shape of $D$. Now $(A_C, q_d, a)$ is a witness to $T_1 \models^{stCQ} T_2$ for the following reasons.

\(\Rightarrow\). Assume $T_1 \models^{stCQ} T_2$ or $T_1 \models^\perp T_2$.

In case $T_1 \models^\perp T_2$, consider a witness $\Sigma$-Box $A$ and assume w.l.o.g. that $A$ is tree-shaped. Let $a \in \text{ind}(A)$ be its root. We can assume that $T_1$ contains all $\Sigma$-FAs from $T_2$ (otherwise $T_1 \models^{\mathcal{ELHI}^\mathcal{F}_I} T_2$ and we are done). We turn $A$ into a $\Sigma$-EL concept $C_A$ in the obvious way. Then $C_A \subseteq \perp$ is a witness to $T_1 \models^\Sigma T_2$:

1. $T_2 \models C_A \subseteq \perp$ because, if there were a model $I$ of $T_2$ with $d \in C_A$, we could turn it into a model of $(T_2, A)$ by interpreting the ABox individuals accordingly (possibly involving partial unraveling as above), which would contradict the assumption that $A$ is a witness to $T_1 \models^\perp T_2$.

2. $T_1 \models C_A \subseteq \perp$, witnessed by $I_{T_1, \cdot A}$.

In case $T_1 \models^{stCQ} T_2$, by Lemma 24 there is a witness $(A, q, a)$ with $A$ tree-shaped and $q$ a $\Sigma$-stCQ with exactly one answer variable. We construct $C_A$ as above and another $\Sigma$-EL concept $C_q$ from $q$ in the obvious way. It can be shown analogously to the previous case that $C_A \subseteq D_q$ is a witness to $T_1 \models^{\mathcal{ELHI}^\mathcal{F}_I} T_2$.

B Proofs for Section 3

B.1 Unraveling ABoxes

To obtain tree-shaped ABoxes or CQs, we use unraveling, which needs to be more cautious in the presence of inverse roles and functionality. In particular, we need to ensure that, whenever a role is functional in an ABox, then so it is in its unraveling. We define an unraveling for Horn-ALCHIF similar to the one for Horn-ALCIF in (Lutz and Wolter 2012).

Let $A$ be an ABox. The unraveling $U^n_A$ of $A$ at an individual $a \in \text{ind}(A)$ is the following ABox:

\[ \text{ind}(U^n_A) = \{b_0r_0b_1 \cdots b_{n-1}r_rb_n \mid n \geq 0, \text{ where } b_0 = a, b_i \in \text{ind}(A), \text{ for all } 0 \leq i \leq n, \ \text{and } (b_i, b_{i+1}) \in A \text{ for all } 0 \leq i < n, \text{ and } (b_{n-1}, r_{n-1}) \neq (a, r) \} \]
(b_{i+1}, r_i) (the latter inequality is needed to ensure preservation of functionality).

- The concept assertions in $U^q_A$ are all assertions of the shape $C(\alpha)$ such that $\alpha = b_0 \cdots b_{n-1} r_{n-1} b_n \in \text{ind}(A)$ and $C(b_n) \in A$. The role assertions in $U^q_A$ are all assertions of the shape $r(b_0 \cdots b_{n-1} r_{n-1}) \alpha$ such that $\alpha = b_0 \cdots b_{n-1} r_{n-1} b_n \in \text{ind}(A)$.

The following is standard to prove:

**Proposition 25** Let $\mathcal{T}$ be a Horn-ACCLIFT TBox, $A$ an ABox, and $a \in \text{ind}(A)$. If $A$ is consistent with $\mathcal{T}$, then so is $U^q_A$.

### B.2 Proof of Lemma 8

We reformulate the lemma to make its statement more explicit.

**Lemma 8** reformulated equivalently. Let $\mathcal{T}_1, \mathcal{T}_2$ be Horn-ACCLIFT TBoxes with $\mathcal{T}_1 \models_{\Sigma +} \mathcal{T}_2$. If $\mathcal{T}_1 \not\models_{\Sigma +} \mathcal{T}_2$, then there is a tree-shaped $\Gamma$-ABox $A$ consistent with $\mathcal{T}_1$ and $\mathcal{T}_2$, and a tree-shaped $\Sigma$-CQ $q$ such that one of the following holds:

1. $q$ has a single answer variable and there is an $a \in \text{ind}(A)$ such that $\mathcal{T}_2, A \models q(a)$ but $\mathcal{T}_1, A \not\models q(a)$;
2. $q$ is Boolean and $\mathcal{T}_2, A \models q$ but $\mathcal{T}_1, A \not\models q$.

If $\mathcal{T}_1 \not\models_{\Sigma + CO} \mathcal{T}_2$, then there is a tree-shaped $\Gamma$-ABox $A$ and a tree-shaped $\Sigma$-st-CQ $q$ with (1).

**Proof.** Unrestricted CQs. Assume $\mathcal{T}_1 \not\models_{\Sigma + CO} \mathcal{T}_2$, i.e., $\mathcal{T}_2, A \models q(a)$ and $\mathcal{T}_1, A \not\models q(a)$, for some $\Gamma$-ABox $A$ consistent with both $\mathcal{T}_1$, some $\Sigma$-CQ $q$ and some tuple $a$. Lemma 19 yields $I_{\mathcal{T}_2, A} \models q(a)$ and $I_{\mathcal{T}_1, A} \not\models q(a)$. We first show that the following properties of $q$ and $a$ are without loss of generality:

(a) Every match of $q(x)$ into $I_{\mathcal{T}_2, A}$ maps every quantified variable into the anonymous part.

(b) $q(x)$ does not contain atoms of the form $r(x_1, x_2)$ with $x_1, x_2$ answer variables.

(c) If $x = (x_1, \ldots, x_n)$ and $a = (a_1, \ldots, a_n)$, then $a_i \neq a_j$ for all $i, j$ with $1 \leq i < j \leq n$.

(d) $q(x)$ is connected.

For (a), take a match $\pi$ of $q$ in $I_{\mathcal{T}_2, A}$ and a quantified variable $y$ such that $\pi(y) = b \in \text{ind}(A)$. Obtain $q'(x, y)$ from $q(x)$ by removing the quantification over $y$, thus making $y$ an answer variable.

Clearly, we have $I_{\mathcal{T}_2, A} \models q'(a, b)$ and $I_{\mathcal{T}_1, A} \not\models q'(a, b)$, and thus $\mathcal{T}_2, A \models q'(a, b)$ and $\mathcal{T}_1, A \not\models q'(a, b)$.

For (b), observe that such atoms can always be dropped, since they cannot be inferred via $\mathcal{T}_1$ or $\mathcal{T}_2$: Let $q(x) = \exists y (r(x_1, x_2) \land \varphi(x', y))$ with $x_1, x_2 \in x$, and let $I_{\mathcal{T}_2, A} \models q(a)$ be witnessed by the match $\pi$ with $\pi(x_i) = a_i$, $i = 1, 2$.

Construct the CQ $q'(x') = \exists y \varphi(x', y)$ by dropping the atom $r(x_1, x_2)$ (and thus possibly removing $x_1$ and/or $x_2$ from the free variables). It is clear that $I_{\mathcal{T}_2, A} \models q'(a')$ for the corresponding restriction $a'$ of the tuple $a$; thus it suffices to show that $I_{\mathcal{T}_1, A} \not\models q'(a')$.

From $I_{\mathcal{T}_2, A} \models q(a)$ we can conclude that $(a_1, a_2) \in r^2 I_{\mathcal{T}_2, A}$. By construction of $I_{\mathcal{T}_2, A}$ there is some $\Gamma$-role $r'$ with $r'(a_1, a_2) \in A$ and $\mathcal{T}_2 \models r' \subseteq r$ (which includes the possibility $r' = r$, i.e., $r(a_1, a_2) \in A$). Due to $\mathcal{T}_1 \models_{\Sigma +} \mathcal{T}_2$, we also have $\mathcal{T}_1 \models r' \subseteq r$ and hence $(a_1, a_2) \in r^2 I_{\mathcal{T}_1, A}$. This implies the desired $I_{\mathcal{T}_1, A} \not\models q'(a')$ because, otherwise, any match $q'$ of $q$ in $I_{\mathcal{T}_1, A}$ with $\pi(x_i) = a_i$, $i = 1, 2$, could be extended to a match of $q$.

This construction does not introduce any violations of (a).

For (b), observe that, whenever $a_i = a_j$ for some $i, j$ with $1 \leq i < j \leq n$, we can always drop $x_i$ and $x_j$: Let $x'$ be $x_i$ and $a_i$ and $a_j$, and $a_i$ removed, and transform $q(x)$ into $q'(x')$ by replacing every occurrence of $x_i$. Then $\mathcal{T}_2, A \models q'(a')$ and $\mathcal{T}_1, A \not\models q'(a')$. This construction does not introduce any violations of (a) or (b).

For (c), observe that $\mathcal{T}_2, A \models q(a)$ and $\mathcal{T}_1, A \not\models q(a)$ implies $\mathcal{T}_2, A \models q'(a)$ and $\mathcal{T}_1, A \not\models q'(a)$ for some connected component $q'$ of $q$. This construction does not introduce any violations of (a), (b), or (c).

While this is easy to see for (b) and (c), Property (a) requires a closer look: If the possibly disconnected CQ $q$ satisfies (a) and has at least one match $\pi$ in $I_{\mathcal{T}_2, A}$, then every match of any connected component $q'$ in $I_{\mathcal{T}_1, A}$ can be extended to a match of $q$ in $I_{\mathcal{T}_2, A}$ via $\pi$ restricted to the remaining connected components. Since the match of $q$ satisfies (a), so does the match of $q'$.

Thus, as long as $q$ violates any of the above properties, we apply the corresponding modification as described and in the order given. From now on, we assume that $q$ satisfies properties (a) to (c). Furthermore, they imply:

(e) $q(x)$ does not contain a proper path between any two answer variables, which is a non-empty sequence of atoms $r_1(z_1, z_2), r_2(z_2, z_3), \ldots, r_n(z_n, z_{n+1})$ with variables $z_1, z_{n+1} \in x$ and $z_i \in y$ for $1 < i < n$, and with roles $r_i$, such that $z_i \neq z_{i-1}$ for every $1 < i < n$.

To show this, assume the opposite, i.e., $q(x)$ contains a proper path as above between two answer variables $x, x'$. By (b) we have $n > 1$. By (d) and (e), $q(x)$ maps all $z_i$ with $1 < i < n$ to the anonymous part of $I_{\mathcal{T}_2, A}$. However, there is no corresponding proper path between any two ABox individuals in $I_{\mathcal{T}_2, A}$; a contradiction.

Assume now that $q(x) = \exists y \varphi(x, y)$ is not tree-shaped, i.e., there is a cycle $r_1(z_1, z_2), r_2(z_2, z_3), \ldots, r_n(z_n, z_{n+1})$ with variables $z_i \in x \cup y$, $z_1 = z_{n+1}$, and roles $r_i$ such that $z_{i+1} \neq z_{i-1}$ for every $1 < i < n$ and $z_2 \neq z_n$. By (b), we have $z_i \in y$ for all $1 \leq i < n + 1$. Let $\pi$ be a match of $q(x)$ in $I_{\mathcal{T}_2, A}$. By (a), $q(x)$ maps all variables to the anonymous part of $I_{\mathcal{T}_2, A}$, which, by construction, is acyclic. Hence $\pi$ cannot satisfy the properties of a match; contradiction.

Assume now that $x$ in $q(x)$ contains more than one answer variable, say $x \neq x'$, matched by $a$ and $a'$ in $I_{\mathcal{T}_2, A}$, with $a \neq a'$ due to (c). By (b), $q(x)$ is connected, and thus, there is a path from $x$ to $x'$ in $q(x)$. Since $x \neq x'$, there is even a proper path; contradicting (c).

Thus, we now have that $q$ is tree-shaped and behaves as required by (1) or (2). It remains to transform $A$ into a tree-shaped ABox: In case $q$ is Boolean, we get from (b) and (c) that every match of $q$ in $I_{\mathcal{T}_2, A}$ is into the anonymous subtree rooted
We prove both implications via contraposition.

**Proof.**

B.4 Proof of Theorem 11

Moreover, we write interpretation $A$ of $\mathcal{T}$.

We interpret $\mathcal{T}$ as described.

**Assume** $\mathcal{T} \models q(a)$ and $\mathcal{T} \not\models q(a)$, which is still consistent with both $\mathcal{T}_1$, $\mathcal{T}_2$, then $\mathcal{T}_1 \not\models q(a)$.

Clearly, we can also assume that $\mathcal{B}$ is connected.

**stCQs.** Since stCQs are already tree-shaped and have exactly one answer variable, the previous argument for unrestricted CQs reduces to observing Properties (a) and (c) and unraveling the witness ABox as described.

\[ \begin{align*}
\text{We will thus use Conditions (1b) and (2b) as alternative characterizations of bounded homomorphisms and simulations.}
\end{align*} \]

The second insight shows that, under additional conditions, we can extract an unbounded homomorphism from a suitable family of bounded ones.

**Lemma 27** Let $\mathcal{I}_1, \mathcal{I}_2$ be finitely branching interpretations and let $\mathcal{I}_1$ be $\Sigma$-connected.

1. If there are $d_0 \in \Delta_{\mathcal{I}_1}$ and $e_0 \in \Delta_{\mathcal{I}_2}$ such that for each $i \geq 0$ there is a $\Sigma$-homomorphism $h_i$ from $\mathcal{I}_1|_{d_0}^{i}$ to $\mathcal{I}_2$ with $h_i(d_0) = e_0$, then $\mathcal{I}_1 \rightarrow \mathcal{I}_2$.

2. If there are $d_0 \in \Delta_{\mathcal{I}_1}$ and $e_0 \in \Delta_{\mathcal{I}_2}$ such that for each $i \geq 0$ there is a $\Sigma$-simulation $\rho_i$ of $\mathcal{I}_1|_{d_0}^{i}$ in $\mathcal{I}_2$ with $(d_0, e_0) \in \rho_i$, then $\mathcal{I}_1 \not\leq \Sigma \mathcal{I}_2$.

**Proof.** We only show (1); Part (2) is analogous. We are going to construct a $\Sigma$-homomorphism $h$ from $\mathcal{I}_1$ to $\mathcal{I}_2$ step by step, obtaining the desired homomorphism in the limit. We will take care that, at all times, the domain of $h$ is finite and

\[ \begin{align*}
(\ast) \text{ there is a sequence } h_0, h_1, \ldots \text{ with } h_i, A\Sigma \text{-homomorphism from } \mathcal{I}_1|_{d_0}^{i} \text{ to } \mathcal{I}_2 \text{ such that whenever } h(d) \text{ is already defined, then } h_i(d) = h(d) \text{ for all } i \geq 0.
\end{align*} \]

Start with setting $h(d_0) = e_0$. The original sequence $h_0, h_1$ from the lemma witnesses (\ast). Now consider the set $\Lambda$ that consists of all elements $d \in \Delta_{\mathcal{I}_1}$ such that $h(d)$ is undefined and there is an $e \in \Delta_{\mathcal{I}_2}$ with $h(e)$ is defined and such that $d$ is reachable from $e$ along a $\Sigma$-role edge. Since the domain of $h$ is finite and $\mathcal{I}_1$ is finitely branching, $\Lambda$ is finite. By (\ast), since every $d \in \Lambda$ is reachable in one step from an element $e$ such that $h(e)$ is defined, and since $\mathcal{I}_2$ is finitely branching, for each $d \in \Lambda$ there are only finitely many $e'$ such that $h_i(d) = e'$ for some $i$. Thus there must be a function $\delta : \Lambda \rightarrow \Delta_{\mathcal{I}_2}$ such that, for infinitely many $i$, we have $h_i(d) = \delta(d)$ for all $d \in \Lambda$. Extend $h$ accordingly, that is, set $h(d) = \delta(d)$ for all $d \in \Lambda$. Clearly, the sequence $h_0, h_1, \ldots$ from (\ast) after the extension is no longer sufficient to witness (\ast) after the extension. We fix this by skipping homomorphisms that do not respect $\delta$, that is, define a new sequence $h_0', h_1', \ldots$ by using as $h_i'$ the restriction of $h_i$ to the domain of $\mathcal{I}_1|_{d_0}^{i}$ where $j \geq i$ is smallest such that $h_j(d) = \delta(d)$ for all $d \in \Lambda$. This finishes the construction. Note that we will automatically have $h(a) = a$ for all individual names $a$ (as required), no matter whether $d_0$ is an individual name or not.

**We are now ready to prove Theorem 11**

**Theorem 11** Let $\mathcal{T}_1$ and $\mathcal{T}_2$ be Horn-ALCHIF TBoxes with $\mathcal{T}_1 \models_{\Gamma, \Sigma} \mathcal{T}_2$. Then $\mathcal{T}_1 \models_{\Gamma, \Sigma} \mathcal{T}_2$ iff for all tree-shaped $\Gamma$-ABoxes $\mathcal{A}$ consistent with $\mathcal{T}_1$ and $\mathcal{T}_2$, $\mathcal{I}_2|_{\mathcal{T}_2, \mathcal{A}} \cong_{\Sigma} \mathcal{I}_1$ for all $\mathcal{A}$ and $\mathcal{I}_1$ as above iff $\mathcal{I}_2|_{\mathcal{T}_2, \mathcal{A}} \cong_{\Sigma} \mathcal{I}_1$.

We prove the second part of Theorem 11 (the stCQ case), we need a bounded variant of simulations, analogously to bounded homomorphisms. We write $\mathcal{I}_1 \leq_{\Sigma} \mathcal{I}_2$ if for any subinterpretation $\mathcal{I}_1'$ of $\mathcal{I}_1$ with $|\Delta_{\mathcal{I}_1'}| \leq n$, we have $\mathcal{I}_1' \leq_{\Sigma} \mathcal{I}_2$. Moreover, we write $\mathcal{I}_1 \leq_{\Sigma} \mathcal{I}_2$ if $\mathcal{I}_1 \leq_{\Sigma} \mathcal{I}_2$ for any $n$.

We begin with two useful insights about bounded homomorphisms (and simulations) and their connection to unbounded ones. We use $\mathcal{I}_1|_{d_0}$ to denote the restriction of $\mathcal{I}_1$ to elements that can be reached by starting at $d_0$ and traveling along at most $n$ role edges (forwards or backwards).

The first insight is straightforward.

**Fact 26** Let $\Sigma$ be a signature and $\mathcal{I}_1, \mathcal{I}_2$ be interpretations such that $\mathcal{I}_2$ is finitely branching.

1. The following are equivalent.
   (a) $\mathcal{I}_1 \rightarrow_{\Sigma} \mathcal{I}_2$
   (b) For every $d \in \Delta_{\mathcal{I}_2}$ and every $i \geq 0$ : $\mathcal{I}_1|_{d_0}^{i} \rightarrow_{\Sigma} \mathcal{I}_2$
2. The following are equivalent.
   (a) $\mathcal{I}_1 \leq_{\Sigma} \mathcal{I}_2$
   (b) For every $d \in \Delta_{\mathcal{I}_2}$ and every $i \geq 0$ : $\mathcal{I}_1|_{d_0}^{i} \leq_{\Sigma} \mathcal{I}_2$
Proof. Unrestricted CQs, “if”. We show the contrapositive. Thus first assume that $T_1 \not\models^CQ_{\Gamma,\Sigma} T_2$. By Lemma 8 there is a tree-shaped $\Gamma$-ABox $A$ consistent with both $T_i$, and a tree-shaped $\Sigma$-CQ $q$ such that either

(1') $q$ has a single answer variable and there is an element $a \in \text{ind}(A)$ such that $T_2, A \models q(a)$ but $T_1, A \not\models q(a)$ or

(2') $q$ is Boolean and $T_2, A \models q$ but $T_1, A \not\models q$.

In case (1') holds, $q$ is connected. Let $h$ be a match of $q$ in $I_{T_2, A}$; in particular $h(x) = a$. Since $q$ contains an answer variable, we must have $I_{T_2, A(0)} \not\models h(x)$ otherwise the composition of $h$ and the witnessing homomorphism shows $I_{T_1, A} \models q(a)$, which is not the case. Thus Condition (1) is violated for $I_1 = I_{T_2, A}$.

In case (2') holds, consider again a match $h$ of $q$ in $I_{T_2, A}$. Let $I_{T_i, A}$ be the restriction of $I_{T_2, A}$ to the elements in the range of $h$. Clearly, we have $I_{T_2, A} \not\models h(x)$. Consequently, $I_{T_i, A} \not\models q$ and $I_{T_i, A}$, where $n$ is the number of variables in $q$, implying that Conditions (2a) and (2b) are both false.

Unrestricted CQs, “only if”. Assume that $T_1 \models^CQ_{\Gamma,\Sigma} T_2$ and let $A$ be a tree-shaped $\Gamma$-ABox consistent with both $T_i$. We first show the following:

Claim. For all models $I_1$ of $(T_1, A)$, we have $I_{T_2, A} \rightarrowfin_{\Sigma} I_1$.

Proof of claim: Assume to the contrary that $I_{T_2, A} \not\models^CQ_{\Gamma,\Sigma} I_1$. Then $I_{T_2, A} \not\models^CQ_{\Gamma,\Sigma} I_1$ for some $n$, that is, there is a subinterpretation $I$ of $I_{T_2, A}$ with $|\Delta^2| \leq n$ such that $I \not\models h(x)$. Let $a$ be the ABox individuals in $I$ and let $q_I$ be $q$ viewed as a CQ whose variables correspond to the domain elements of $I$ and the ABox individuals are represented by answer variables. Then it can be verified that $I_{T_2, A} \models q_I(a)$ and $I_1 \not\models q_I(a)$.

Condition 1 is a consequence of Lemma 27. Fix a tree-shaped, finitely branching model $I_1 \models (T_1, A)$ and let $I_{T_2, A}^{con}$ be the disjoint union of the connected interpretations $I_1, \ldots, I_k$. In each $I_i$, we find at least one individual $a_i$ from $\text{ind}(A)$. Let $\ell \in \{1, \ldots, k\}$. By the claim above and Fact 26, we find a sequence $h_0, h_1, \ldots$ such that $h_i$ is a $\Sigma$-homomorphism from $I_i^{d0}$ to $I_i$. Note that we must have $h_i(a_i) = a_i$ for all $i$. Thus, Lemma 27 yields $I \rightarrowfin_{\Sigma} I_1$ and, in summary, $I_{T_2, A}^{con} \rightarrowfin_{\Sigma} I_1$.

Now for Condition 2. Let $I$ be a $\Sigma$-subtree in $I_{T_2, A}$ with root $d_0$. By the claim above and Fact 26 there is a sequence $h_0, h_1, \ldots$ such that $h_i$ is a $\Sigma$-homomorphism from $I_i^{d0}$ to $I_{T_2, A}$.

First assume that there is an $e_0 \in \Delta^2_{T_2, A}$ such that $h_i(d_0) = e_0$ for infinitely many $i$. Construct a new sequence $h_0', h_1', \ldots$ with $h_i'$ a $\Sigma$-homomorphism from $I_i^{d0}$ to $I_{T_2, A}$ by skipping homomorphisms that do not map $d_0$ to $e_0$, that is, $h_i'$ is the restriction of $h_i$ to the domain of $I_i^{d0}$ where $j \geq i$ is smallest such that $h_j(d_0) = e_0$. Clearly, $h_j'(d_0) = e_0$ for all $i$. Thus, Lemma 27 yields $I \rightarrowfin_{\Sigma} I_{T_2, A}$ and thus, by Lemma 19 (2), $I \rightarrowfin_{\Sigma} I_1$ for every tree-shaped, finitely branching model $I_1 \models (T_1, A)$.

It remains to deal with the case that there is no $e_0 \in \Delta^2_{T_2, A}$ such that $h_i(d_0) = e_0$ for infinitely many $i$. We can assume that there is an $a_0 \in \text{ind}(A)$ such that $h_i(d_0) \in \Delta^2_{T_2, A}(a_0)$ for all $i$; in fact, there must be an $a_0$ such that $h_i(d_0) \in \Delta^2_{T_2, A}(a_0)$ for infinitely many $i$ and we can again skip homomorphisms to achieve this for all $i$. It is important to note that the remaining homomorphisms do not necessarily map all ancestors of $d_0$ in $I$ to elements in $I_{T_2, A}(a_0)$, due to the presence of inverse roles. Now, since $I_{T_2, A}$ is a finitely branching, for all $i, n \geq 0$ we must find a $j \geq i$ such that $h_j(d_0)$ is a domain element whose distance from $a_0$ exceeds $n$ (otherwise the previous case would apply). We can use this fact to construct a sequence $h_0', h_1', \ldots$ with $h_i$, a $\Sigma$-homomorphism from $I_i^{d0}$ to $I_{T_2, A}(a_0)$, is easy to verify that this implies $I \rightarrowfin_{\Sigma} I_{T_2, A}(a_0)$; in fact, $h_0', h_1', \ldots$ can again be found by skipping homomorphisms.

If we now fix an arbitrary (tree-shaped, finitely branching) model $I_1 \models (T_1, A)$, by Lemma 19 (1) and (2) we have $tp_{I_{T_1, A}(a_0)} \subseteq tp_{I_2}(a_0)$ and thus $I_1 \rightarrowfin_{\Sigma} I_2$. Hence $I \rightarrowfin_{\Sigma} I_1 \rightarrowfin_{\Sigma} I_2$ as required.

stCQs. We need to show that the following three conditions are equivalent.

(i) $T_1 \models^{stCQ}_{\Gamma,\Sigma} T_2$

(ii) $I_{T_2, A}^{con} \not\models_{\Sigma} I_1$ for all tree-shaped $\Gamma$-ABoxes $A$ consistent with $T_1$ and $T_2$, and for all tree-shaped, finitely branching models $I_1$ of $(T_1, A)$.

(iii) $I_{T_2, A}^{con} \not\models_{\Sigma} I_{T, A}$ for all $A$ as above.

(ii) $\Leftrightarrow$ (iii). The “only if” direction follows from Lemma 19 (1); the “if” direction follows from $I_{T_1, A} \not\models_{\Sigma} I_1$, which is a direct consequence of Lemma 19 (2).

(i) $\Rightarrow$ (ii). This implication is analogous to the “if” direction of the case for unrestricted CQs above, except that the witness stCQ is rooted and connected, which rules out Case (2') and thus Condition (2).

(i) $\Rightarrow$ (ii). Assume that $T_1 \models^{stCQ}_{\Gamma,\Sigma} T_2$ and let $A$ be a tree-shaped $\Sigma$-ABox consistent with both $T_i$. We first show the following:

Claim. For all models $I_1$ of $(T_1, A)$ : $I_{T_2, A}^{con} \not\models_{\Sigma} I_1$.

Proof of claim: Assume to the contrary that $I_{T_2, A}^{con} \models_{\Sigma} I_1$. Then $I_{T_2, A}^{con} \models_{\Sigma} I_1$ for some $n$, that is, there is a subinterpretation $I$ of $I_{T_2, A}$ with $|\Delta| \leq n$ such that $I \models h'(x)$. We can assume w.l.o.g. that $I$ is connected and contains at least one ABox individual (otherwise we just extend $I$ and increase $n$ accordingly). Let $a$ be the ABox individuals in $I$ and let $q_I$ be $q$ viewed as a tree-shaped CQ whose variables correspond to the domain elements of $I$ and the ABox individuals are represented by answer variables. Clearly $I \models q(a)$ and thus $I_{T_2, A}^{con} \models q(a)$; let $\pi$ be a match of $q$ in $I$. To transform $q$ into an stCQ, perform the following operations.

- Remove all binary atoms involving only answer variables (see Condition (5) in the proof of Lemma 8).
- Restrict the resulting CQ to one connected component, with exactly one answer variable $x$ (see Condition (4) in the proof of Lemma 8); then $x$ is the root of the tree $q$.
- Let $a = \pi(x)$.
- “Split” multi-edges along the tree structure of $q$: if there are $n$ binary atoms involving variables $z_1, z_2$ of $q$ with $z_2$ being a child of $z_1$ in the tree $q$, introduce $n$ copies of $z_2$
and its subtree, and redirect each of the n original atoms to its corresponding copy. Apply this step exhaustively.

The result of this transformation is an stCQ q’, which still satisfies \( I_{t_0,A} \models q'(a) \). On the other hand, \( I_1 \not\models q'(a) \) because, otherwise, a match \( \pi' \) of \( q'(x) \) in \( I_1 \) would give rise to a simulation of \( I \) in \( I_1 \).

Having established the claim, we proceed as follows: Let a be an ABox individual in \( I_{t_0,A}^{\Sigma} \). By the claim and Fact 26 there is a sequence \( h_0, h_1, \ldots \) such that \( h_i \) is a \( \Sigma \)-homomorphism from \( I_{t_2,A}^{\Sigma} \) to \( I_1 \). Obviously \( h_i(a) = a \) for all \( i \). From Lemma 27 we obtain \( I_{t_2,A}^{\Sigma \cong} \models \Sigma I_1 \) as desired.

\[ \square \]

C Proof for Section 4

C.1 Proof of Theorem 12

Theorem 12. Given two Horn-ALCHIF TBoxes \( T_1 \) and \( T_2 \) and types \( t_i \) for \( T_i \), \( i \in \{1, 2\} \), it can be decided in time \( 2^{2^{|T_2|}|\Sigma T_1|} \) whether \( I_{t_2,t_2}^{\Sigma \cong} \rightarrow^\infty \Sigma I_{t_1,t_1} \), \( p \) a polynomial.

Proof. By Lemma 13 we can decide \( I_{t_2,t_2}^{\Sigma \cong} \rightarrow^\infty \Sigma I_{t_1,t_1} \) by checking whether \( \exists J \in \text{can}_\infty (T_1, t_1) \) with \( I_{t_2,t_2}^{\Sigma \cong} \rightarrow^\Sigma \Sigma J \). By Lemma 14 this can be done by constructing the corresponding set \( M \) of mosaics for \( t_1 \), removing all mosaics that are not good, and checking whether the remaining set \( M \) contains a mosaic \( M \) with \( t_2 \in M \).

The desired upper bound is now a consequence of the following observations:

- The size of each 1-neighborhood in \( I_{t_1,t_1} \) is bounded by \( q(|T_1|) \), a polynomial for \( q \).
- The number of mosaics for \( t_1 \) is bounded by \( 2^q(|T_1|)|\Sigma T_1|^2 \) for a polynomial \( q ' \): there are at most \( 2^{|T_1|} \) many 1-neighborhoods in \( I_{t_1,t_1} \), and each such neighborhood admits at most \( 2^{|T_1|} \) many decorations with sets of types.
- Given a tuple \( (t', \rho, t, S, t) \), one can decide in time \( 2^q(|T_1|) \), \( q ' \) a polynomial, whether \( (t', \rho, t, S) \) is a 1-neighborhood. Moreover, we can decide in time \( 2^q(|T_1|) \), \( q ' \) a polynomial, whether \( (M) \) is satisfied.
- Conditions 1 and 2 of a mosaic being good can be checked in the desired time.

\[ \square \]

C.2 Proof of Lemma 13

Lemma 13. Let \( T \) be a Horn-ALCHIF TBox, \( t_0 \in tp(T) \), and \( I \) a tree-shaped interpretation. Then \( I \rightarrow^\infty \Sigma I_{t_0,t_0} \) iff there is a \( J \in \text{can}_\infty (T_0, t_0) \) with \( I \rightarrow_{t_2} J \).

Proof. “\( \Rightarrow \)”. Let \( d_0 \) be the root of \( I \). By Fact 26 there is a sequence \( h_0, h_1, \ldots \) such that \( h_i \) is a \( \Sigma \)-homomorphism from \( I_1^{d_0} \) to \( I_{t_0,t_0} \). Note that the set \( tp(T) \) is finite, and that \( I_{t_0,t_0} \) is finitely branching. By skipping homomorphisms, we can thus construct a new sequence \( h_0', h_1', \ldots \) such that \( h_i' \) is a \( \Sigma \)-homomorphism from \( I_1^{d_0} \) to \( I_{t_0,t_0} \), and, additionally, for every \( 0 \leq i \leq j \) and \( d \in \Delta I_{t_0,t_0}^{d_0} \) the following properties hold:

(i) \( n_1^{I_{t_0,t_0}}(h_i'(d)) = n_1^{I_{t_0,t_0}}(h_j'(d)) \), and

(ii) if \( e \) is a successor of \( d \) in \( I \), then \( h_i'(e) \) is a successor of \( h_j'(d) \) in \( I_{t_0,t_0} \) iff \( h_i'(e) \) is a successor of \( h_j'(d) \).

Guided by \( h_i' \), we construct a sequence of interpretations \( J_0, J_1, \ldots \) and a sequence \( g_0, g_1, \ldots \) with \( g_i \), a \( \Sigma \)-homomorphism from \( I_1^{d_0} \) to \( J_i \) such that for all \( 0 \leq i \leq j \) and \( d \) in the domain of \( I_1^{d_0} \), we have \( g_i(d) = g_j(d) \). Throughout the construction, we maintain the invariant

\[ n_1^{J_i} (g_i(d)) \subseteq n_1^{I_{t_0,t_0}}(h_i'(d)) \]

for all \( i, d \) such that \( g_i(d) \) is defined.

We start with \( J_0 = \{(e_0), \omega\} \) such that \( tp_{J_0}(e_0) = tp_{I_{t_0,t_0}}(h_0'(d_0)) \) and \( g_0(d_0) = e_0 \). Clearly (i) is satisfied. Assuming that \( J_i \) and \( g_i \) are already defined, we extend them to \( J_{i+1} \) and \( g_{i+1} \) by doing the following for every \( d, d' \in \rho_{\infty} \) with \( d \in \Delta I_{t_0,t_0}^{d_0} \) and \( d' \not\in \Delta I_{t_0,t_0}^{d_0} \). By invariant (i) and Item (i), we have \( n_1^{J_i} (g_i(d)) \subseteq n_1^{I_{t_0,t_0}}(h_i'(d)) \) for all \( j \geq i \); thus, we can apply (R) to \( g_i(d) \) and \( h_i'(d) \). More precisely, we obtain \( J_{i+1} \) by adding a predecessor and/or successors to achieve

\[ n_1^{J_{i+1}} (g_i(d)) = n_1^{I_{t_0,t_0}}(h_i'(d)) \]

To define \( g_{i+1}(d') \), we distinguish two cases according to Item (ii):

- \( h_j'(d') \) is a successor of \( h_i'(d) \) for all \( j \geq i \). Then there is some \( (\rho', t') \) in component \( S \) of \( n_1^{I_{t_0,t_0}}(h_i'(d)) \) such that \( (h_i'(d), h_j'(d')) \in \rho_{t_0}^{\infty} \), \( \rho \) maximal and \( tp_{I_{t_0,t_0}}(h_i'(d')) = t' \). By (**) that pair is also in component \( S \) of \( n_1^{J_{i+1}}(g_i(d)) \). Take a corresponding \( \rho ' \)-successor \( e' \) of \( e \) in \( J_{i+1} \) and set \( g_{i+1}(d') = e' \). Clearly (i) is satisfied.

- \( h_j'(d) \) is a successor of \( h_i'(d') \) for all \( j \geq i \). Then \( t = tp_{I_{t_0,t_0}}(h_i'(d')) \) and \( \rho \) is maximal with \( (h_i'(d'), h_j'(d)) \in \rho_{t_0}^{\infty} \). By (**) the \( t '-\rho \) component in \( n_1^{J_{i+1}}(g_i(d)) \) are identical. Take a corresponding \( \rho'-\)predecessor \( e' \) of \( e \) in \( J_{i+1} \) and set \( g_{i+1}(d') = e' \). Clearly (i) is satisfied.

The construction of \( J \) and \( h \) is finished by setting \( h = \bigcup_{i \geq 0} g_i \) and \( J' = \bigcup_{i \geq 0} J_i \), and defining \( J \) as the result of exhaustive application of rule (R) to \( J' \).

“\( \Leftarrow \)”. It suffices to show \( J \rightarrow^\infty \Sigma I_{t_0,t_0} \). To this end, denote with \( J_i \), \( i \geq 0 \), the finite submodel of \( J \) obtained after \( i \) rule applications, and with \( d_i \) the root of \( J_i \). We verify the following claim, which implies \( J \rightarrow^\infty \Sigma I_{t_0,t_0} \).

Claim. For all \( i \geq 0 \), we have:

(i) there is an \( e_0 \in \Delta I_{t_0,t_0} \) with \( tp_{I_{t_0,t_0}}(e_0) = tp_{J_i}(d_i) \);

(ii) for all \( e_0 \in \Delta I_{t_0,t_0} \) with \( tp_{I_{t_0,t_0}}(e_0) \supseteq tp_{J_i}(d_i) \), we have \( (J_i, d_i) \rightarrow (I_{t_0,t_0}, e_0) \).

3We write \( I \rightarrow^\infty J \) to denote that, for every \( n \geq 0 \), there are \( n \)-bounded homomorphisms from \( I \) to \( J \), without restricting the signature.
We prove the claim by induction on $i$. For $i = 0$, Points (i) and (ii) are clear by definition of $J_0$. For the inductive step, consider $J_{i+1}$ and suppose (R) has been applied to some $d \in \Delta^J_i$ and $e \in \Delta^{J_{i+1}}$.

Observe that Point (i) is trivially preserved when $d$ is not the root of $J_i$. In case $d = d_i$, it is preserved by the condition on the choice of $e$ in (R): $e$ has the same type as $d_i$ and, by construction, the predecessor $e'$ of $e$ (if it exists) has the same type as $d_{i+1}$.

For Point (ii), we distinguish two cases:

• The extension of $J_i$ to $J_{i+1}$ has not added any predecessors to $d_i$. In particular, we then have $d_{i+1} = d_i$. Let $e_0$ be as in (ii), i.e., $\tp_{J_i}(e_0) \geq \tp_{J_i}(d_{i+1}) = \tp_{J_i}(d_i)$. By induction hypothesis, there is a homomorphism $h : (J_i, d_{i+1}) \rightarrow (\mathcal{I}_{T_0}, e_0)$. We extend $h$ to the domain of $J_{i+1}$ by doing the following for each newly added successor $d' \neq d$.

Let $\tp_{J_{i+1}}(d) = t$ and $\tp_{J_{i+1}}(d') = t'$ and $\rho$ maximal with $(d, d') \in \rho^{\geq}$. By the choice of $e$ in (R), $e$ is of type $t$ and has a successor of type $t'$. By construction of the universal model, there is $r' \in \rho$ with $t \leadsto_{r'}^n t'$ and $\rho = \{ s \mid T \models r \subseteq s \}$. Denote with $\hat{t} = \tp_{\mathcal{I}_{T_0}}(h(d))$. The definition of a homomorphism yields $t \subseteq \hat{t}$. Thus, there is $\hat{t}' \geq t'$ such that $\hat{t} \leadsto_{\hat{t}'} t'$. By definition of the universal model, $h(d)$ has a $\rho$-successor of type $\hat{t}'$ or a $\rho$-predecessor of type $\hat{t}''$, for $\hat{t}'' \geq \hat{t}$. We extend $h$ by setting $h(d')$ to that predecessor or successor, respectively.

• The extension of $J_i$ to $J_{i+1}$ has added a $\rho$-predecessor $d'$ to $d_i$. Then $d_i = d$ and $d' = d_{i+1}$. Let $\tp_{J_{i+1}}(d) = t$ and $\tp_{J_{i+1}}(d') = t'$. By construction of the universal model, there is $r \in \rho$ with $t \leadsto_{r} t'$ and $\rho = \{ s \mid T \models r \subseteq s \}$. Let $e_0$ be as in (ii), that is, $\hat{t} := \tp_{\mathcal{I}_{T_0}}(e_0) \geq t'$. We then have that $\hat{t} \leadsto_{r} \hat{t}$ for some $\hat{t} \geq t$. By definition of the universal model, $h(e_0)$ has a $\rho$-successor of type $\hat{t}$ or a $\rho$-predecessor of type $\hat{t}'' \geq t$. Let this element be $\hat{t}_0$. By induction hypothesis, there is a homomorphism $h : (J_i, d_i) \rightarrow (\mathcal{I}_{T_0}, e_0)$. We extend $h$ by first setting $h'(d'_i) = e_0$ and then extending $h$ to all successors of $d$ as in the previous case.

It should be clear that $h$, updated as above, witnesses $(J_{i+1}, d_{i+1}) \rightarrow (\mathcal{I}_{T_0}, e_0)$. □

C.3 Proof of Lemma 14

Lemma 14 Let $t_i \in \text{tp}(T_i)$ for $i \in \{1, 2\}$. Then there is a $J \in \text{can}_\Sigma(T_1, t_1)$ such that $\mathcal{I}_{T_2, t_2} \overset{\Sigma}{\rightarrow} J$ iff $\mathcal{M}_p$ contains a mosaic $M$ with $t_2 \in \text{LM}(\mathcal{M}_p)$.

Proof. “⇒”. Let $h$ be a $\Sigma$-homomorphism from $\mathcal{I}_{T_2, t_2} \overset{\Sigma}{\rightarrow} J$ to some $J \in \text{can}_\Sigma(T_1, t_1)$. For every $d \in \Delta^J$, denote with $T_h(d)$ the set of all types mapped to $d$ by $h$, that is,

$$T_h(d) = \{ \tp_{\mathcal{I}_{T_2, t_2}}(e) \mid h(e) = d, e \in \Delta^{\mathcal{I}_{T_2, t_2} \overset{\Sigma}{\rightarrow}} \}.$$

For every element $d \in \Delta^J$, we define a tuple $M(d) = \{ t^- \rho, t, S, \ell \}$ by taking:

- $\{ t^-, \rho, t, S \} = n_1^J(d)$;
- $\ell(t) = T_h(d)$;
- If there is a predecessor $d'$ of $d$, then $\ell(t^-) = T_h(d')$; otherwise, set $\ell(t^-) = \emptyset$ (not important);
- For every successor $d'$ of $d$, with $\tp_{J}(d') = t'$ and $\rho = \{ r \mid (d, d') \in r^\geq \} \cup \{ \rho', t' \in S \} \cup \{ \ell(t', t) = T_h(d') \}$;

It is easy to verify that every $M(d) = \{ t^- \rho, t, S, \ell \}$ obtained in this way is actually a mosaic: By definition of $J$, we know that $\{ t^- \rho, t, S \} = n_1^{\mathcal{I}_{T_1 \overset{\Sigma}{\rightarrow}}} (d')$ for some $d' \in \Delta^{\mathcal{I}_{T_1 \overset{\Sigma}{\rightarrow}}}$. Moreover, by definition of the universal model $\mathcal{I}_{T_2, t_2}$ and the fact that $h$ is a homomorphism, Condition (M) is satisfied.

Let $\mathcal{M}(J) = \{ M \mid d \in \Delta^J \}$. It follows from the construction that all mosaics in $\mathcal{M}(J)$ are good in $\mathcal{M}(J)$; hence $\mathcal{M}(J) \subseteq \mathcal{M}_p$. Finally, let $d_0$ be the root of $\mathcal{I}_{T_2, t_2}$. By definition of $M := M(h(d_0))$, we have $t_2 \in \text{LM}(\mathcal{M}_p)$.

“⇐”. Assume $\mathcal{M}_p$ contains a mosaic $M$ with $t_2 \in \text{LM}(\mathcal{M}_p)$. We define the interpretation $\mathcal{J}$ as the limit of the following process. We maintain a partial function $q : \Delta^J \rightarrow \mathcal{M}_p$, intuitively mapping each domain element of $J$ to the mosaic that gave rise to it. Throughout the construction, the following invariant is preserved:

$$q(d) = \{ t^- \rho, t, S, \ell \}, \text{ then } n_1^J(d) = \{ t^- \rho, t, S, \ell \}. \quad \ast$$

We start with defining $J$ as the interpretation corresponding to the 1-neighbourhood represented by $M$, and define $q(e_0) = M$, where $e_0$ is the “center” of that 1-neighbourhood. By definition, the invariant $(\ast)$ is satisfied. Then extend $\mathcal{J}$ by applying the following step exhaustively in a fair way: Choose some $d \in \mathcal{J}$ such that $q(d)$ is undefined, and:

- If $d$ has a predecessor $d'$ such that $q(d') = M'$ then, due to $(\ast)$, there is $\rho, t \in S_{M'}$ such that $(d', d) \in \rho$ and $\tp_{J}(d) = t$. Let $N \in \mathcal{M}_p$ be the mosaic that exists according to Condition 1 of being good for $\rho, t \in S_{M'}$. Then extend $\mathcal{J}$ such that $n_1^J(d) = \{ t_N, \rho_N, t_N, S_N \}$ and set $q(d) = N$.

- If $d$ has a successor $d'$ such that $q(d') = M'$ then, due to $(\ast)$, we know that $\tp_{J}(d') \neq \bot$. Let $N \in \mathcal{M}_p$ be the mosaic that exists according to Condition 2 of being good. Then extend $\mathcal{J}$ such that $n_1^J(d) = \{ t_N, \rho_N, t_N, S_N \}$ and set $q(d) = N$.

It is immediate from the construction that these steps preserve $(\ast)$, and that always one of the cases applies. Moreover, by construction, any interpretation $\mathcal{J}$ obtained in the limit of such a process is an element of can$_\Sigma(T_1, t_1)$. It thus remains to construct a $\Sigma$-homomorphism $h$ witnessing $\mathcal{I}_{T_2, t_2} \overset{\Sigma}{\rightarrow} \mathcal{J}$. We proceed again inductively, maintaining the invariant:

If $h(d)$ is defined, then $\tp_{\mathcal{I}_{T_2, t_2}}(d) \in \ell_q(h(d))(\ell_q(h(d)))$. \((\dagger)\)

Let $d_0$ be the root of $\mathcal{I}_{T_2, t_2}$. We start with setting $h(d_0) = e_0$, where $e_0$ is as above. By the assumption that $t_2 \in \text{LM}(\mathcal{M}_p)$, invariant $(\dagger)$ is satisfied. Now, exhaustively apply the following step. Choose $d \in \Delta^{\mathcal{I}_{T_2, t_2}}$ such that $h(d)$ is not defined but $h(d') = e$ is defined for the predecessor $d'$ of $d$. Let
We first make precise the semantics of $2ATA_\Theta$. The emptiness problem for $2ATA_\Theta$, that is, the set of sources in the graph $\zeta$ that is accepting over it. We need to introduce strategy trees in time exponential in the number of states. Let $\gamma = \nu_1 \gamma_1 \cdots \gamma_i n\gamma_i \cdots \nu_m \gamma$. Let $\gamma$ be an infinite path in $T$, denote, for all $j \geq 0$, with $q_j$ the state such that $r(i_j) = (x_j, q_j)$. The path $\gamma$ is accepting if the largest number $m$ such that $\Omega(q_j) = m$ for infinitely many $j$ is even. A run $(T, r)$ is accepting, if all infinite paths in $T$, are accepting. $\mathfrak{A}$ accepts a tree if $\mathfrak{A}$ has an accepting run over it.

Theorem\[15\] The emptiness problem for $2ATA_\Theta$ can be solved in time exponential in the number of states.

The proof is by reduction to the emptiness problem of standard two-way alternating tree automata on trees of some fixed outdegree [Vardi, 1998]. We need to introduce strategy trees similar to [Vardi, 1998] Section 4A. A strategy tree for $\mathfrak{A}$ is a tree $(T, \tau)$ where $\tau$ labels every node in $T$ with a subset $\tau(x) \subseteq Q \times N \cup \{-1\} \times Q$, that is, with a graph with nodes from $Q$ and edges labeled with natural numbers or $-1$. Intuitively, $(q, i, p) \in \tau(x)$ expresses that, if we reached node $x$ in state $q$, then we should send a copy of the automaton in state $p$ to $x \cdot i$. For each label $\zeta$, we define state($\zeta$) = $\{q \mid (q, i, q') \in \zeta\}$, that is, the set of sources in the graph $\zeta$. A strategy tree is an input tree $(T', \tau)$ if $T = T'$, $q_0 \in \text{state}(\tau(\zeta))$, and for every $x \in T$, the following conditions are satisfied:

(i) if $(q, i, p) \in \tau(x)$, then $x \cdot i \in T$;
(ii) if $(q, i, p) \in \tau(x)$, then $p \in \text{state}(\tau(x \cdot i))$;
(iii) if $q \in \text{state}(\tau(x))$, then the truth assignment $\nu_{q,x}$ defined below satisfies $\delta(q, L(x))$;

- $\nu_{q,x}(p) = 1$ iff $(q, 0, p) \in \tau(x)$;
- $\nu_{q,x}((-p)) = 1$ iff $(q, -1, p) \in \tau(x)$;
- $\nu_{q,x}((-p)) = 1$ iff $x = \varepsilon$ or $(q, -1, p) \in \tau(x)$;
- $\nu_{q,x}([n]p) = 1$ iff $(q, i, p) \in \tau(x)$ for $n$ pairwise distinct $i \geq 1$;
- $\nu(\square_n p) = 1$ iff for all but at most $n$ values $i \geq 1$ with $x \cdot i \in T$, we have $(q, i, p) \in \tau(x)$.

A path $\beta$ in a strategy tree $(T, \tau)$ is a sequence $\beta = (u_1, q_1)(u_2, q_2) \cdots$ of pairs from $T \times Q$ such that for all $i > 0$, there is some $c_i$ such that $(q_i, c_i, q_{i+1}) \in \tau(u_i)$ and $u_{i+1} = u_i \cdot c_i$. Thus, $\beta$ is obtained by moves prescribed in the strategy tree. We say that $\beta$ is accepting if the largest number $m$ such that $\Omega(q_i) = m$, for infinitely many $m$, is even. A strategy tree $(T, \tau)$ is accepting if all infinite paths in $(T, \tau)$ are accepting.

Lemma 28 A $2ATA_\Theta$ accepts an input tree iff there is an accepting strategy tree on the input tree.

Proof. The “if”-direction is immediate: just read off an accepting run from the accepting strategy tree.

For the “only if”-direction, we observe that acceptance of an input tree can be defined in terms of a parity game between Player 1 (trying to show that the input is accepted) and Player 2 (trying to challenge that). The initial configuration is $(\varepsilon, q_0)$ and Player 1 begins. Consider a configuration $(x, q)$. Player 1 chooses a satisfying truth assignment $\nu$ of $\delta(q, L(x))$. Player 2 chooses an atom $\alpha$ with $\nu_{q,n}(\alpha) = 1$ and determines the next configuration as follows:

- if $\alpha = p$, then the next configuration is $(x, p)$;
- if $\alpha = (-p)$, then the next configuration is $(x \cdot 1, p)$ unless $x = \varepsilon$; in this case, Player 1 loses immediately;
- if $\alpha = (-p)$, then the next configuration is $(x \cdot 1, p)$ unless $x = \varepsilon$; in this case, Player 2 loses immediately;
- if $\alpha = \square_n p$, then Player 1 selects pairwise distinct $i_1, \ldots, i_n$ with $x \cdot i_j \in T$, for all $j$ (and loses if she cannot); Player 2 then chooses some $i$ and the next configuration is $(x \cdot i, \varepsilon)$;
- if $\alpha = \square_n p$, then Player 1 selects $n$ values $i_1, \ldots, i_n$; Player 2 then chooses some $\ell \notin \{i_1, \ldots, i_n\}$ such that $x \cdot \ell \in T$ (and loses if he cannot) and the next configuration is $(x \cdot \ell, p)$.

Player 1 wins an infinite play $(x_0, q_0)(x_1, q_1) \cdots$ if the largest number $m$ such that $\Omega(q_i) = m$, for infinitely many $i$, is even. It is not difficult to see that Player 1 has a winning strategy on an input tree iff $\mathfrak{A}$ accepts the input tree.

Observe now that the defined game is a parity game and thus Player 1 has a winning strategy iff she has a memoryless winning strategy. It remains to observe that a memoryless winning strategy is nothing else than an accepting strategy tree.

Lemma 29 If $L(\mathfrak{A}) \neq \emptyset$, then there is some $(T, L) \in L(\mathfrak{A})$ such that $T$ has outdegree at most $n$, $C$, where $n$ is the number of states in $\mathfrak{A}$ and $C$ is the largest number in (some transition $\square_n p$ or $\square_n p$ in $\delta$).
Proof. Let \( (T, L) \) be an input tree and \( \tau \) an accepting strategy tree on \( T \), and let \( C \) be the largest number appearing in \( \delta \). We inductively construct a tree \( (T', L') \) with \( T' \subseteq T \) and \( L' \) the restriction of \( L \) to \( T' \) and an accepting strategy tree \( \tau' \) on \( (T', L') \). For the induction base, we start with \( T' = \{ \varepsilon \} \) and \( \tau' \) the empty mapping. For the inductive step, assume that \( \tau'(x) \) is still undefined for some \( x \in T' \), and proceed as follows:

1. For every \((q, i, p) \in \tau(x)\) with \( i \in \{-1, 0\} \), add \((q, i, p) \in \tau'(x)\).
2. For every \( p \in \Theta \), define \( N_p = \{ i \geq 1 \mid (q, i, p) \in \tau(x), x \cdot i \in T \} \) and let \( N'_{p'} \subseteq N_p \) be a subset of \( N_p \) with precisely \( \min(C, |N_p|) \) elements. Then:
   - (a) for all \( i \in N'_{p'} \), add \( x \cdot i \in T' \);
   - (b) for all \((q, i, p) \in \tau(x)\) with \( i \in N'_{p'} \), add \((q, i, p) \in \tau'(x)\);
   - (c) for all \( q \in \text{state}(x) \) and \( i \in N'_{p'} \), add \((q, i, p) \in \tau'(x)\).

By Step 2 above, \( T' \) has outdegree bounded by \(|Q| \cdot C\). It remains to show that \( \tau' \) is an accepting strategy tree on \( T' \). Observe first that, by construction, \( q_0 \in \text{state}(\tau'(\varepsilon)) \).

We verify Conditions (i)–(iii) of a strategy tree being on an input tree. Conditions 1 follows directly from the construction. For (ii), assume that \((q, i, p) \in \tau'(x)\). By construction, there is some \( q' \) with \((q', i, p) \in \tau(x)\), and, by Condition (ii) \( p \in \text{state}(\tau(x \cdot i)) \). Hence, there is some \((p, j, p') \in \text{state}(\tau(x \cdot i))\). By construction, there is also some \((p', j, p'') \in \text{state}(\tau'(x \cdot i)), \text{thus } p \in \text{state}(x \cdot i)\).

For Condition (iii), take any \( x \in T' \) and \( q \in \text{state}(\tau'(x)) \). As \( q \in \text{state}(\tau(x)) \), we know that the first transition condition \( \delta(q, L(x)) \). We show that for all \( \alpha \in \text{state}(\tau'(x)) \) with \( v_{q,x}(\alpha) = 1 \), we also have \( v'_{q,x}(\alpha) = 1 \), where \( v'_{q,x} \) is the truth assignment defined for \( \tau \) in Condition (iii) satisfies \( \delta(q, L(x)) \).

We finally argue that \( \tau' \) is also accepting. Let \( \beta = (u_1, q_1)(u_2, q_2) \cdots \) be an infinite path in \((T', \tau')\). We construct an infinite path \( \beta' = (u'_1, q_1)(u'_2, q_2) \cdots \) in \((T, \tau)\) as follows:

- \( u'_1 = u_1 \);
- Let \( u_{i+1} = u_i \cdot \ell \) for some \( \ell \) with \((q_i, \ell, q_{i+1}) \in \tau'(x)\). If \( \ell \in \{0, 1\} \), we have \((q_i, \ell, q_{i+1}) \in \tau(x)\), by Step 1. We set \( u'_{i+1} = u'_i \cdot \ell' \).
- If \( \ell \geq 0 \) then, by Step 2(c), there is some \( \ell' \) and \((q_i, \ell', q_{i+1}) \in \tau(x) \) and \( x \cdot \ell' \in T' \). Set \( u'_{i+1} = u'_i \cdot \ell' \).

Since every infinite path in \((T, \tau)\) is accepting, so is \( \beta' \), and thus \( \beta \).

We now reduce to reduce the emptiness problem of 2ATA\(_k\) to the emptiness of alternating automata running on trees of fixed outdegree [Vardi, 1998], which we recall here. A tree \( T \) is \( k \)-ary if every node has exactly \( k \). A two-way alternating tree automaton over \( k \)-ary trees (2ATA\(_k\)) that are \( \Theta \)-labeled is a tuple \( A = (Q, \Theta, q_0, \delta, \Omega) \) where \( Q \) is a finite set of states, \( \Theta \) is the input alphabet, \( q_0 \in Q \) is an initial state, \( \delta \) is the transition function, and \( \Omega : Q \to N \) is a priority function. The transition function maps a state \( q \) and some input letter \( \theta \) to a transition condition \( \delta(q, \theta) \), which is a positive Boolean formula over the truth constants \( \text{true}, \text{false}, \text{and transitions of the form } (i, q, q') \in \{0, 1, \ldots, k\} \times Q \) such that \( S \) satisfies \( \varphi \).

The emptiness problem for 2ATA\(_k\)'s can be solved in time exponential in the number of states [Vardi, 1998].

Theorem 15 The emptiness problem for 2ATA\(_k\) can be solved in time exponential in the number of states.

Proof. Let \( \mathfrak{A} = (Q, \Theta, q_0, \delta, \Omega) \) be a 2ATA\(_k\) with \( n \) states and \( C \) the largest number in \( \delta \). We translate \( \mathfrak{A} \) to a 2ATA\(_k\) \( \mathfrak{B}'' = (Q', \Theta', q_0', \delta', \Omega) \) with \( k = n \cdot C \), the bound from Lemma 29. Set \( Q'' = Q \cup \{ q_0, q_1, q_2, \ldots \} \) and \( \Theta' = (\Theta \cup \{ \downarrow \}) \times \{0, 1\} \). The extended alphabet and the extra states are used to simulate transitions of the form \([-\ell]p\) and to allow for input trees of outdegree less than \( k \).

We obtain \( \delta' \) from \( \delta \) by replacing \( q \) with \((0, 1)\), \((q, 0) \) with \((1, q) \), and \((-1, q) \) with \((0, q_0) \cup (-1, q) \). Moreover, we replace

- \( \square_n q \) with \( \bigwedge_{x \in \{1, \ldots, n\} \backslash \{i\}} \bigwedge_{x \in \{1, \ldots, n\} \backslash \{i\}} \square_{x} \).

where, as usual, \( \{i\} \) denotes the set of all \( m \)-elementary subsets of a set \( M \). To deal with the case of smaller outdegree, we use the fresh symbol \( \downarrow \) as follows:

- For all \( q \in Q' \): \( \delta'(q, (\downarrow \downarrow, b)) = \begin{cases} \text{true} & \text{if } b = 0 \\ \text{false} & \text{if } b = 1 \end{cases} \)

To enforce the intended labeling in the second component and the correct behaviour for \( q_1 \), we set:

\[
\begin{align*}
\delta'(q_0, (\theta, b)) &= \begin{cases} \text{false} & \text{if } b = 0 \\ q_0 \land \bigwedge_{i=1}^{k} (i, q_1) & \text{otherwise} \end{cases} \\
\delta'(q_1, (\theta, b)) &= \begin{cases} \bigwedge_{i=1}^{k} (i, q_1) & \text{if } b = 0 \\ \text{false} & \text{otherwise} \end{cases} \\
\delta'(q_r, (\theta, b)) &= \begin{cases} \text{true} & \text{if } b = 1 \\ \text{false} & \text{otherwise} \end{cases}
\end{align*}
\]

Using Lemma 29, it is easy to verify that \( L(\mathfrak{A}) \) is empty iff \( L(\mathfrak{B}'' \mathfrak{A}) \) is empty. Moreover, since emptiness of 2ATA\(_k\)'s can be checked in exponential time in the number of states, this finishes the proof of Theorem 15. \( \square \)
C.5 Proof of Theorem 16

Theorem 16 In Horn-ALCHIF, the following problems can be decided in time $2^{o(1/|T_1|)}$, $p$ a polynomial: ($\Gamma$, $\Sigma$)-CQ entailment, inseparability, and conservative extensions. The same holds for $\Sigma$-deductive entailment in ECHIF.$L$.

We show the following lemma which, together with Theorem 15 and Lemma 7, implies Theorem 16.

Lemma 30 There are 2ATA, $\mathcal{A}_1, \mathcal{A}_2, \mathcal{A}_3, \mathcal{A}_4, \mathcal{A}_4'$ such that:
- $\mathcal{A}_1$ accepts $(T, L)$ iff $A$ is finite, tree-shaped, and contains $\varepsilon$;
- $\mathcal{A}_2$ accepts $(T, L)$ iff $T_1$ is a model of $A$ and $T_1$;
- $\mathcal{A}_3$ accepts $(T, L)$ iff $A$ is consistent with $T_2$, and $T_2$ is $T_{T_2\cdot A}$ restricted to $\text{ind}(A)$;
- $\mathcal{A}_4$ accepts $(T, L)$ iff either (1) or (2) from Theorem 11 is not satisfied, when $T_{T_2\cdot A}$ is replaced with $T_2$.
- $\mathcal{A}_4'$ accepts $(T, L)$ iff $\forall \exists \cdot T_2$ is exponential in $|T_2|$ (and independent of $T_2$), the number of states of $\mathcal{A}_1$ is polynomial in $|T_1|$ (and independent of $T_1$), and the number of states of $\mathcal{A}_4, \mathcal{A}_4'$ is exponential in $|T_2|$ (and independent of $T_2$). The automata can be constructed in time polynomial in $|T_1|$ and double-exponential in $|T_2|$.

The construction of the automaton $\mathcal{A}_1$ is straightforward, so we concentrate on $\mathcal{A}_2, \mathcal{A}_3, \mathcal{A}_4$, and $\mathcal{A}_4'$.

In what follows, we use $\bigcirc q$ and $\Box q$ to abbreviate $\Diamond_1 q$ and $\Diamond q$, respectively. We define $\mathcal{A}_2 = (Q_2, \Theta, q_0, \delta_2, \Omega_2)$ where

$$Q_2 = \{ q_0, q_A \} \cup \{ q_{\alpha} \mid \alpha \in T_1 \} \cup \{ q_{\rho}, Q_{\rho} \mid \rho \in \Theta_1 \} \cup \{ q_{r \cdot r', B}, q_{r \cdot B}, q_{r, B} \mid \exists r, B \in \text{cl}(T_1) \},$$

and $\Omega_2$ assigns 0 to all states. The idea of $\mathcal{A}_2$ is to check that the ABox is satisfied, realized in state $q_A$, and that every axiom TBox axiom in $T_1$ is satisfied everywhere, realized using states $q_{\alpha}$ below. Formally, the transition function $\delta_2$ is given as follows, for $\sigma = (L_0, L_1, L_2)$:

$$\delta_2(q_0, \sigma) = \bigcirc q_0 \land q_A \land \bigwedge_{\alpha \in T_1} q_{\alpha},$$

$$\delta_2(q_A, \sigma) = \bigwedge_{\rho \in \Theta_1} q_{\rho},$$

$$\delta_2(q_{\text{true}}(r), \sigma) = (q_{r} \land \Box q_{r}) \lor (q_{\bar{r}} \land \Diamond q_{\bar{r}}),$$

$$\delta_2(q_{r \cdot r', B}, \sigma) = q_{r} \lor q_{B},$$

$$\delta_2(q_{a \cdot r, B}, \sigma) = q_{a} \lor q_{r} \lor q_{B},$$

$$\delta_2(q_{\exists r, B}, \sigma) = q_{r} \lor q_{B},$$

$$\delta_2(q_{r \cdot B}, \sigma) = q_{r} \lor q_{B},$$

$$\delta_2(q_{\neg r, B}, \sigma) = \bigcirc q_{\bar{r}} \lor (q_{\bar{r}} \land \neg q_{B}),$$

Finally, we set for all $\rho \in \Theta_1$:

$$\delta_2(q_{\rho}, \sigma) = \begin{cases} 
\text{true} & \text{if } \rho \in L_1 \\
\text{false} & \text{if } \rho \not\in L_1
\end{cases},$$

$$\delta_2(q_{\rho}, \sigma) = \begin{cases} 
\text{true} & \text{if } \rho \not\in L_1 \\
\text{false} & \text{if } \rho \in L_1
\end{cases}.$$

Automaton $\mathcal{A}_4$ relies on a syntactic characterization of ABox entailment [Bienvenu et al., 2013], which we introduce first.

Let $T$ be a Horn-ALCHIF TBox and $A$ a tree-shaped ABox. A derivation tree for an assertion $A_0(a_0)$ in $A$ w.r.t. $T$ with $A_0 \in \text{ind}(A)$ is a finite $\text{ind}(A) \times \mathbb{N}_0$-labeled tree $(T, V)$ that satisfies the following conditions:

1. $V(\varepsilon) = (A_0, A_0)$;
2. if $V(x) = (A, A)$ and neither $A(a) \not\in A$ nor $\top \subseteq A \subseteq T$, then one of the following holds:
   - (i) $x$ has successors $y_1, \ldots, y_k$, $k \geq 1$ with $V(y_i) = (a, A_i)$ for $1 \leq i \leq k$ and $T \models A_1 \sqcap \cdots \sqcap A_k \subseteq A$;
   - (ii) $x$ has a single successor $y$ with $V(y) = (b, B)$ and there is an $\exists r. B \subseteq A \subseteq T$ and an $s(a, b) \in A$ such that $T \models s \subseteq r$;
   - (iii) $x$ has a single successor $y$ with $V(y) = (b, B)$ and there is a $B \subseteq \exists r. A \subseteq T$ such that $r(b, a) \in A$ and $\text{func}(r) \subseteq T$.

Note that the first item of Point 2 above requires $T \models A_1 \sqcap \cdots \sqcap A_n \subseteq A$ instead of $A_1 \sqcap A_2 \subseteq A \subseteq T$ to ‘shortcut’ anonymous parts of the universal model. In fact, the derivation of $A$ from $A_1 \sqcap \cdots \sqcap A_n$ by $T$ can involve the introduction of anonymous elements.

The main property of derivation trees is the following.

Lemma 31 Let $T$ be a Horn-ALCHIF TBox and $A$ an ABox consistent with $T$. Then for all assertions $A(a)$ with $A \in \text{ind}(A)$, we have $T, A \models A(a)$ iff there is a derivation tree for $A(a)$ in $A$ w.r.t. $T$.

Proof. The “if”-direction is immediate, so we concentrate on the “only if”-direction. We construct a sequence of interpretations $I_0, I_1, \ldots$ by the following procedure. We start with setting:

$$\Delta I_0 = \text{ind}(A),$$

$$A I_0 = \{ a \mid A(a) \in A \},$$

$$r I_0 = \{ (a, b) \mid r(a, b) \in A \}.$$  

For every $i \geq 0$, we obtain $I_{i+1}$ from $I_i$ by setting $I_{i+1} = I_i$ and applying the following rules to all $d, e \in \Delta I_i$:

1. If $d \in (A_1 \sqcap A_2) I_i$, but $d \not\in A I_i$ for some $A_1 \sqcap A_2 \subseteq A \subseteq T$, then add $d \in A I_{i+1}$;
2. If $d \in (\exists r. B) I_i$, but $d \not\in A I_i$ for some $\exists r. B \subseteq A \subseteq T$, then add $d \in A I_{i+1}$;
3. If $(d, e) \in r I_i$, but $(d, e) \not\in s I_i$ for some $s$ with $T \models r \subseteq s$, then add $(d, e) \in s I_{i+1}$;
4. If $d \in A I_i$, but $d \not\in (\exists r. B) I_i$ for some $A \subseteq \exists r. B \subseteq T$, then,
(a) if there is e with \((d, e) \in r^T\) and \(\text{func}(r) \in \mathcal{T}\) then add \(e \in B^{T+1}\);
(b) otherwise add a fresh domain element \(e\) with \((d, e) \in r^{T+1}\) and \(e \in B^{T+1}\).

Let \(\mathcal{T}\) be defined as \(A^T = \bigcup_{n \geq 0} A_n\), \(A^T = \bigcup_{n \geq 0} A_n\), and \(r^T = \bigcup_{n \geq 0} r^n\). It is standard to verify the following:

**Claim 1.** \(\mathcal{T} \rightarrow J\) for all models \(\mathcal{J}\) of \(\mathcal{T}\) and \(A\).

By definition of \(\mathcal{T}_0\), we have \(\mathcal{T} \models A\). Moreover, we have \(\mathcal{T} \models T\) where \(T \subseteq \mathcal{T}\) is obtained from \(T\) by dropping all CLs of the form \(A \subseteq \perp\) and all FAs. Since \(A\) is consistent with \(T\), there is a model \(\mathcal{J}\) of \(A\) and \(\mathcal{T}\); in particular, \(A^T = \emptyset\) for all \(A \subseteq \perp \subseteq \mathcal{T}\). By Claim 1, we have \(\mathcal{T} \rightarrow J\), and thus \(A^T = \emptyset\). For the FAs \(\text{func}(s)\), observe that they are obeyed by \(A\) (because of consistency with \(T\)) and that they are preserved, by rule 4(a). Thus, \(\mathcal{T}\) is a model of \(T\).

**Claim 2.** For all \(i \geq 0\), we have:

(a) For all \(a \in \text{ind}(A)\): if \(a \in A^T\), then there is a derivation tree \(A(a)\) in \(A\) w.r.t. \(\mathcal{T}\).
(b) If \(e\) was created because of \(d\) in Rule 4(b), then there is a derivation tree \(\mathcal{T} \models \bigcup \{A | d \in A^T\} \subseteq \exists r \bigcup \{A | e \in A^T\}\) for all \(r \in r^T\).

**Proof of Claim 2.** It is standard to show Part (b) of the Claim. We do Part (a) by induction on \(i\). By construction of \(\mathcal{T}_0\), it is true for \(i = 0\). Consider \(\mathcal{T}_{i+1}\). If \(a \in A^{T+1}\) because of Rule 1, construct a derivation tree of type (i) from the derivation trees for \(A(a)\) and \(A(a)\) which exist due to the induction hypothesis. If \(a \in A^{T+1}\) because of Rule 2, there is some \(d \in B^{T+1}\) with \((a, d) \in r^T\) and \(\exists r.a.B \subseteq \mathcal{T}\). If \(d \in \text{ind}(A)\), then there is some \(s(a, d) \in \mathcal{T} \models s \subseteq r\), by Rule 3. We can thus construct a derivation of type (ii) from the derivation tree of \(B(d)\), which exists due to induction hypothesis. If \(d \notin \text{ind}(A)\), then \(d\) was created because of \(a\) in Rule 4(b). By Part (b) of the Claim, we have \(\mathcal{T} \models \bigcup \{A' | a \in A^T\} \subseteq \exists r.B\). Hence, \(\mathcal{T} \models \bigcup \{A' | a \in A^T\} \subseteq A\), and we can construct a derivation tree of type (i) for \(A(a)\). If \(a \in A^{T+1}\) because of Rule 4(a), there is \((d, a) \in r^T\) and \(d \in B^{T+1}\), and \(B \subseteq \exists r.A\). If \(d \in \text{ind}(A)\), we can construct a derivation tree of type (i) for \(A(a)\) from the derivation tree of \(B(d)\) which exists by induction. If \(d \notin \text{ind}(A)\), then \(d\) was created because of \(a\) in Rule 4(b). By Part (b) of the Claim, we have \(\mathcal{T} \models \bigcup \{A' | a \in A^T\} \subseteq \exists r.B\). Hence, \(\mathcal{T} \models \bigcup \{A' | a \in A^T\} \subseteq A\), and we can construct a derivation tree of type (i) for \(A(a)\) based on this. This finishes the proof of Claim 2 and the Lemma.

In the following Lemma, we characterize consistency of ABoxes with TBoxes.

**Lemma 32** Let \(\mathcal{T}\) be a Horn-\(\mathcal{ALCHI}\) TBox and \(A\) an ABox. Then \(A\) is consistent with \(\mathcal{T}\) iff the following points are satisfied for all \(a \in \text{ind}(A)\):

1. the following ABox \(A_a\) is consistent with \(\mathcal{T}\):
   \[A_a = \{B(a) \mid B(a) \text{ has a derivation tree in } A \text{ w.r.t. } \mathcal{T}\}\]
2. for all \(\text{func}(s) \in \mathcal{T}\), there is at most one \(b \in \text{ind}(A)\) with \(s(a, b) \in A\).

**Proof.** The “only if”-direction is immediate, so we concentrate on the “if”-direction. Assume that all \(a \in \text{ind}(A)\) satisfy both items above. By the first item, there is a model \(\mathcal{I}_0\) of \(A_a\) and \(\mathcal{T}\). Since we are considering Horn-\(\mathcal{ALCHI}\)T, there is also a tree-model \(\mathcal{I}_0\) with root \(d_a \in \Delta^{T_0}\) satisfying, for all concept names \(B \in \mathcal{N}_C\):

\[d_a \in B^{T_0} \text{ iff } \mathcal{T}, A_a \models B(a)\]

We construct an interpretation \(\mathcal{I}_0\) as follows. Start with \(\mathcal{I}_0\) by taking

\[\Delta^{T_0} = \text{ind}(A)\]
\[A^{T_0} = \{a \mid A(a) \text{ has a derivation tree in } A \text{ w.r.t. } \mathcal{T}\}\]
\[r^{T_0} = \{(a, b) \mid s(a, b) \in A, \mathcal{T} \models s \subseteq r\}\]

Now, obtain \(\mathcal{I}_0\) from \(\mathcal{I}_0\) by performing the following operation for every \(a \in \text{ind}(A)\) and \(b \in \Delta^{T_0}\) such that \((d_a, b) \in r^T\) for some set of roles \(r\) which contains no role \(r\) such that there is \(a'\) with \(r(a', a') \in A\). Extend \(\mathcal{I}_0\) by adding the sub-interpolation of \(\mathcal{I}_0\) rooted at \(b\) as a \(r\)-successor of \(a\).

Based on (\(\ast\)) and the assumptions, it is straightforward to show that \(\mathcal{I}\) is a model of \(A\) and \(\mathcal{T}\).

We are now ready to give the automaton \(\mathcal{A}_3\). We take \(\mathcal{A}_3 = (Q_3, \Theta_0, \theta_3, \Delta_3)\) where

\[Q_3 = \{q_0, q_0 \} \cup \{q_A, \mathcal{T}_A | A \in \Theta_2 \cap \mathcal{N}_C\} \cup \{q_r, \mathcal{T}_r, q_A^r, q_A^{r^\prime}, q_r^r | r \in \Theta_2 \cap \mathcal{N}_C\} \cup \{q_r, \mathcal{T}_r, B | r \in \Theta_2 \cap \mathcal{N}_C, B \in \Theta_2 \cap \mathcal{N}_C\}\]

and \(\Omega_3\) assigns zero to all states, except for states of the form \(q_A\), to which it assigns 1. The automaton \(\mathcal{A}_3\) ensures that, for all \(n \in \text{ind}(A)\) we have:

(i) \(A \in L_2(n)\) iff there is a derivation tree for \(A(n)\) in \(A\),
(ii) for all \(n \neq e\), \(r \in L_2(n)\) iff there is some \(s\) such that \(s(n - 1, n) \in A\) and \(T_2 \models s \subseteq r\).

Intuitively, these points ensure that the represented interpretation \(L_2\) is the universal model of \(T_2\) and \(A\), in case \(A\) is consistent with \(T_2\). Having (i) and (ii), we can check inconsistency of \(A\) with \(T_2\) based on Lemma 32 that is, we verify the following conditions for all \(n \in \text{ind}(A)\):

(iii) the set \(L_2(n) \cap \mathcal{N}_C\) is consistent with \(T_2\);
(iv) for each \(s \in \text{func}(s) \in \mathcal{T}\), there are no \(n_1 \neq n_2\) such that both \(s(n, n_1) \in A\) and \(s(n, n_2) \in A\).

For Point (i), we use states \(q_A\) for the “if” part, and states \(\mathcal{T}_A\) for the “only if” part; for Point (ii), we use states \(q_r\) and \(\mathcal{T}_r\). For Point (iii), we precompute the set of consistent types and check (iii) while visiting all \(n \in \text{ind}(A)\). Point (iv) can be checked directly on \(A\), that is, independent from \(T_2\). The automaton starts with the following transitions, where we assume \(\sigma = (L_0, L_1, L_2)\):

\[- \delta_3(q_0, \sigma) = \text{true if } L_0 = 0;\]
\[- \delta_3(q_0, \sigma) = \text{false if } L_0 \neq 0 \text{ and } L_2 \cap \mathcal{N}_C\text{ inconsistent with } T_2, \text{ c.f. Point (iii)};\]
The transitions for state $p$ and $q$ of the form $\overline{q}_A$ as follows:

- $\delta_3(q_0, \sigma) = \square q_0 \land \square q_{0r} \land \bigwedge_{A \in L_2 \land q_A} q_A \land \bigwedge_{A \in (q_{2r} \land q_{2l}) \land L_2} \overline{q}_A$.
- $\delta_3(q_{0r}, \sigma) = \text{true if } L_0 = \emptyset$.
- $\delta_3(q_{0l}, \sigma) = \text{true if } L_0 = \emptyset$.

Now, for states $q_A$, we directly implement the conditions of a derivation tree. Finiteness of the derivation is ensured by the priority of states of the form $q_A$. The relevant transitions are as follows:

- $\delta_3(q_A, \sigma) = \text{false if } L_0 = \emptyset$.
- $\delta_3(q_A, \sigma) = \text{true if } A \in L_0$.
- $\delta_3(q_A, \sigma) = \text{false otherwise}$.

The transitions for $\overline{q}_A$ are obtained by taking the “complement” of the ones for $q_A$. More precisely, we define $\delta_3(\overline{q}_A, \sigma) = \delta_3(q_{A}, \sigma)$, where $\overline{q}$ is obtained from $q$ by exchanging $\land$ and $\lor$, $\square$ and $\blacksquare$, $\neg$, and $\neg\land$ and $\neg\lor$, and true and false, and replacing every state $p$ with $\overline{p}$; see the following set of transitions.

- $\delta_3(\overline{q}_A, \sigma) = \text{true if } L_1 = \emptyset$.
- $\delta_3(\overline{q}_A, \sigma) = \text{false if } A \in L_1$.
- $\delta_3(\overline{q}_A, \sigma) = \text{false otherwise}$.

Finally, states $q_r$ and $\overline{q}_r$ at some node $n$ represent the obligation to verify that the role atom $r(n \cdot 1, n)$ follows, respectively, does not follow, from $T$ and $A_2$. This is realized by the following transitions which implement Point (ii) above.

- $\delta_3(q_r, \sigma) = \bigvee_{T_2 \models s \in \overline{q}_r} \bigwedge_{T_2 \models s \in \overline{q}_r} \overline{q}_r$.

For the automaton $\mathfrak{A}_4$, we take $\mathfrak{A}_4 = (Q_4, \Theta, q_0, \delta_4, \Omega_4)$ where $Q_4 = \{q_0, q_1, q_r\} \cup \{q_t, q_{3t}^t, q_{3t}^\prime | t \in \text{tp}(T_2)\} \cup \{q_{\rho, t}, q_{\rho, t}^t | t \in \text{tp}(T_2), \rho \text{ set of sig}(T_2)-\text{roles}\}$, and $\Omega_4$ assigns zero to all states, except for states of the form $q_t$, $t \in \text{tp}(T_2)$, to which it assigns one. For some $n \in \text{ind}(A)$, denote with $J_n$ the universal model of the type $\{A(n) | A \in L_2(n)\}$ and $T_2$. The automaton ensures that indeed (1) or (2) from Theorem 14 is not satisfied, by verifying that there is some $n \in \text{ind}(A)$ such that one of the following conditions holds:

1. there is $r \in \Sigma$ and $n' \in \text{ind}(A)$ such that $(n, n') \in rT_2$, but $(n, n') \notin rT_2$;
2. $J_n \not\models I_1$;
3. there is a $\Sigma$-subtree $J$ of $J_n$ such that
   
   (a) $J \not\models \Sigma I_1$, and
   (b) $J \not\models \Sigma J_{n, t_{\text{tp}}(m)}$, for all $m$ with $L_0(m) \neq \emptyset$.

Condition 1 is straightforward (realized in state $q_r$). For Condition 2, we use states $q_t$ with $t \in \text{tp}(T_2)$. A state $q_t$ assigned to a node $n$ represents the obligation to verify that there is no $\Sigma$-homomorphism from the universal model of $t$ and $T_2$ to $I_1$ that maps the root to $n$. This is the case if either the root cannot be mapped to $n$, or, recursively, there is some $r$-successor $t'$ of $t$ in the universal model such that the universal model of $t'$ and $T_2$ cannot be mapped to any $r$-neighbor of $n$. This process is finite because of priority 1 for all $q_t$ with $t \in \text{tp}(T_2)$.

For Condition 3, we precompute the set $R_{\Sigma}(t)$ of all types of $\Sigma$-subtrees which appear in the universal model of $t$ and $T_2$, and the relation $\not\models \Sigma$ according to Theorem 12. Thus, the sets $R_{\Sigma}(t)$ and the test for finite homomorphisms can be used directly in the transition condition, see states $q_t$ and $q_{3t}^\prime$, respectively. Using states $q_{3t}^t$, the automaton ensures that a given root $t$ of a $\Sigma$-subtree satisfies 3(a) and 3(b).

Let $t|_\Sigma$ and $\rho|_\Sigma$ denote the restriction of $t$ and $\rho$, respectively, to symbols from $\Sigma$. For $\sigma = (L_1, L_2, L_3)$, we take the
Theorem 18
In any DL between $\mathcal{ELI} \land \mathcal{ELI}\mathcal{HF}_{L_1}$, deductive conservative extensions, deductive $\Sigma$-entailment, and deductive $\Sigma$-inseparability are $\text{coNEXPTime}$-hard.

The proof is by reduction of a $\text{NEXPTime}$-complete tiling problem, where the aim is to tile a $2^n \times 2^n$-grid, to the complement of $\text{stCQ}$-conservative extensions. This tiling problem was introduced as a special case of the origin constrained domino problem by Grädel [1989], and its $\text{NEXPTime}$-hardness follows from Grädel’s Theorem 3.3. An instance is given by a tuple $P = (\Xi, \mathcal{I}_0, H, V)$, where $\Xi$ is a finite set of tile types, $\mathcal{I}_0 \subseteq \Xi$ is a set of distinguished tiles to be placed on position $(0, 0)$ of the grid, and $H$ and $V$ are horizontal and vertical matching conditions. Let $|\Xi| = n$. A solution to $P$ is a function $\tau : 2^n \times 2^n \to \Xi$ such that

- if $\tau(i, j) = t$ and $\tau(i + 1, j) = t'$ then $(t, t') \in V$, for all $i < 2^n$, $j < 2^n$.
- if $\tau(0,0) \in \tau_0$.

We can assume w.l.o.g. that for every tile $t \in \Xi$, there is a $t'$ with $(t', t) \in V$.

Let $P = (\Xi, \mathcal{I}_0, H, V)$. We show how to construct $\mathcal{ELI}$ $\mathcal{T}_1$ and $\mathcal{T}_2$ such that $\mathcal{T}_1 \cup \mathcal{T}_2$ is a $(\mathcal{L}(\mathcal{T}_1), \mathcal{L}(\mathcal{T}_2))$-$\text{stCQ}$-conservative extension of $\mathcal{T}_1$ if and only if there is no solution for $P$. Hence, $\text{stCQ}$-conservative extensions, $(\Gamma, \Sigma)$-$\text{stCQ}$ entailment, and $(\Gamma, \Sigma)$-$\text{stCQ}$ inseparability are $\text{coNEXPTime}$-hard in $\mathcal{ELI}$ (and any DL that contains it as a fragment). Since $\mathcal{T}_1$ and $\mathcal{T}_2$ are formulated in $\mathcal{ELI}$, we trivially have $\mathcal{T}_1 \vdash_{\mathcal{L}(\mathcal{T}_1)} \mathcal{T}_1 \cup \mathcal{T}_2$. Thus, hardness of deductive conservative extensions follows from Lemma 24 in all DLs between $\mathcal{ELI}$ and $\mathcal{ELI}\mathcal{HF}_{L_1}$ since $\mathcal{T}_1$ and $\mathcal{T}_2$ are formulated in $\mathcal{ELI}$ and Lemma 24 covers deductive conservative extensions in $\mathcal{ELI}\mathcal{HF}_{L_1}$. This also implies hardness of deductive $\Sigma$-entailment and of deductive $\Sigma$-inseparability in the mentioned DLs.

The intuitions and correctness proofs are based on the following characterization of $\text{stCQ}$-conservative extensions.

Lemma 33 Let $\mathcal{T}_1$ and $\mathcal{T}_2$ be $\mathcal{ELI}$ TBoxes such that all role names in $\mathcal{T}_2$ are in $\mathcal{L}(\mathcal{T}_1)$. Then $\mathcal{T}_1 \cup \mathcal{T}_2$ is a $(\mathcal{L}(\mathcal{T}_1), \mathcal{L}(\mathcal{T}_2))$-$\text{stCQ}$-conservative extension of $\mathcal{T}_1$ if and only if $\mathcal{L}(\mathcal{T}_1 \cup \mathcal{T}_2, A) \rightarrow_{\mathcal{L}(\mathcal{T}_1)} \mathcal{L}(\mathcal{T}_2, A)$ for all tree-shaped $\mathcal{L}(\mathcal{T}_1)$-ABoxes $A$.

Proof. An interpretation is strongly tree-shaped if it is tree-shaped and does not contain multi-edges, that is, any $d, d' \in \Delta^T$ are involved in at most one role edge. Since $\mathcal{T}_1$ and $\mathcal{T}_2$ are formulated in $\mathcal{ELI}$ (and thus do not contain role inclusions), for any tree-shaped ABox $A$ the universal models $\mathcal{L}(\mathcal{T}_1 \cup \mathcal{T}_2, A)$ and $\mathcal{L}(\mathcal{T}_1, A)$ are strongly tree-shaped. The assumption on role names in $\mathcal{T}_2$ made in the lemma implies that every element in $\mathcal{L}(\mathcal{T}_1 \cup \mathcal{T}_2, A)$ can be reached from an ABox individual by traveling only along $\mathcal{L}(\mathcal{T}_1)$-roles. Together, this implies the following: there is a $\mathcal{L}(\mathcal{T}_1)$-simulation from $\mathcal{L}(\mathcal{T}_1 \cup \mathcal{T}_2, A)$ to $\mathcal{L}(\mathcal{T}_1, A)$ if and only if there is a $\mathcal{L}(\mathcal{T}_1)$-homomorphism from $\mathcal{L}(\mathcal{T}_1 \cup \mathcal{T}_2, A)$ to $\mathcal{L}(\mathcal{T}_1, A)$.

From Theorem 11 we get that $\mathcal{T}_1 \cup \mathcal{T}_2$ is a $(\mathcal{L}(\mathcal{T}_1), \mathcal{L}(\mathcal{T}_2))$-$\text{stCQ}$-conservative extension of $\mathcal{T}_1$ if and only if $\mathcal{L}(\mathcal{T}_1 \cup \mathcal{T}_2, A) \rightarrow_{\mathcal{L}(\mathcal{T}_1)} \mathcal{L}(\mathcal{T}_2, A)$ by the assumption on role names in $\mathcal{T}_2$ made in the lemma and simulations can be replaced with homomorphisms by (⋆). We will build $\mathcal{T}_1$ and $\mathcal{T}_2$ such that the same single role name $r$ is used in $\mathcal{T}_1$ and $\mathcal{T}_2$, thus the assumption in Lemma 33 will be satisfied.

For a clearer presentation, we proceed in two steps. We first define $\mathcal{T}_1$ and $\mathcal{T}_2$ to be an $\mathcal{ELI}$ TBox, i.e., on both sides of CI we allow concepts of the following form:

$$L, L' ::= T \mid A \mid L \cap L' \mid L \cup L' \mid r^+ \exists r^- \exists r^+ \forall r^- C.$$
a reflexive-symmetric role. Ideally, we would like \( T_1 \) to be empty (except introducing the required symbols) and \( T_2 \) to verify the existence of an \( S \)-path in the input ABox whose individuals represent the grid positions along with a tiling, row by row from left to right, starting at the lower left corner and ending at the upper right corner. The positions in the grid are represented in binary by the concept names \( X_1, \ldots, X_{2n} \) in the ABox where \( X_1, \ldots, X_n \) indicate the horizontal position and \( X_{n+1}, \ldots, X_{2n} \) the vertical position. The tiling is represented by concept names \( T_t, t \in \Sigma \). The verification is done by propagating a concept name as a marker bottom up and while doing this, verifying the horizontal matching condition. Under the assumption that an additional labeling with concept names \( T'_t, t \in \Sigma \), is such that

\[ (+) \text{ every point in the path is labeled with } T'_t \text{ if its descendant at distance exactly } 2^n \text{ (that is, the grid position immediately below it) is labeled with } T_t, \]

the vertical matching condition is also verified.

For several reasons, this program cannot quite be implemented in the desired way. First, we still have to make sure that \((+)\) actually holds. This is done as follows. We install yet another labeling with concept names \( T'_t, t \in \Sigma \), such that a node is labeled with \( T'_t \) if it is not labeled with \( T_t \). Then \( T_2 \) checks for a violation of \((+)\) in the following way: when the propagation reaches the final individual the verified path, the generation of a finite anonymous \( S \)-path is triggered. That path homomorphically embeds into the \( S \)-path in the ABox in many different ways since \( S \) is reflexive-symmetric. In fact, for any individual on the ABox path we can find a homomorphism such that the endpoint of the anonymous path maps to that individual because (a) the anonymous path is long enough to reach the first individual on the ABox path and (b) the homomorphism can always ‘fold’ the reflexive-symmetric role \( S \) in a suitable way. At the end of the anonymous path, we then guess (using disjunction) a tile \( t \), make \( T'_t \) true, continue building the anonymous path for another \( 2^n \) steps (in a way such that it cannot fold), and finally make \( T_t \) true. Let us pretend for a second that our TBoxes are formulated in \( \text{ELI}^2 \).

\[ \text{and let } M_0 \text{ be any model of } T_1. \]

\[ M_0 \text{ satisfies the following constraints:} \]

\[ \text{1.}\begin{cases} \quad \bigwedge_{t \in \Sigma} M_0 \models T_t \subseteq L \\
\end{cases} \]

2. The verification proceeds upwards. We first verify that the counter is incremented properly when moving upwards along the \( S \)-path in the ABox.

\[ B_0 \models X_1 \cup \exists S.(B_2 \cup X_i) \cup \bigcup_{1 \leq j < i} \exists S.(B_2 \cup X_j) \cup \text{ok}_i \]

\[ B_0 \models X_1 \cup \exists S.(B_2 \cup X_i) \cup \bigcup_{1 \leq j < i} \exists S.(B_2 \cup X_j) \cup \text{ok}_i \]

\[ B_0 \models X_1 \cup \exists S.(B_2 \cup X_i) \cup \bigcup_{1 \leq j < i} \exists S.(B_2 \cup X_j) \cup \text{ok}_i \]

\[ B_{j+1} \models X_i \cup \exists S.(B_2 \cup X_j) \cup \text{ok}_i \]

\[ B_{j+1} \models X_i \cup \exists S.(B_2 \cup X_j) \cup \text{ok}_i \]

\[ B_{j+1} \models X_i \cup \exists S.(B_2 \cup X_j) \cup \text{ok}_i \]

\[ \text{where } i \text{ ranges over } 1..2n \text{ and } j \text{ over } \{0, 1\}. \]
has two $S$-neighbors that are labeled with the same $B_i$ but are labeled differently regarding $X_i$ and $X_j$ for some $j$. We shall prevent this situation later using $T_1$.

3. We next make a verification step inside a row of the grid:

$$B_0 \cap o_k \cap \cdots \cap o_k_n \cap T_i \cap$$

$$\bar{X}_i \cap \exists S(B_2 \cap L \cap T_i) \subseteq L$$

$$B_1 \cap o_k \cap \cdots \cap o_k_n \cap T_i$$

$$\bar{X}_i \cap \exists S(B_1 \cap L \cap T_i) \subseteq L$$

$$B_2 \cap o_k \cap \cdots \cap o_k_n \cap T_i$$

$$\bar{X}_i \cap \exists S(B_1 \cap L \cap T_i) \subseteq L$$

where $t_1, t_2, t_3$ range over $T$ such that $(t_1, t_2) \in H$ and $(t_3, t_2) \in V$ and $i$ ranges over $1..n$. The use of $\bar{X}_i$ on the left-hand sides ensures that we move inside a row. In the first line, we make a move between horizontally neighboring grid positions, verifying the horizontal matching condition. In the other lines, we move along the three boring grid positions, verifying the horizontal matching condition. We shall prevent this situation later using $T_2$.

4. We also have to consider the case where we jump from one grid row to the next, ignoring the tiling condition:

$$B_0 \cap o_k \cap \cdots \cap o_k_n \cap T_i \cap$$

$$\bar{X}_i \cap \exists S(B_2 \cap L) \subseteq L$$

where $t$ ranges over $T$ and $i$ ranges over $n + 1..2n$. The use of $\bar{X}_i$ on the left-hand side ensures that we are not yet in the topmost row.

5. When the final individual of the ABox path is reached (maximum counter value and $B_2$-label), we make an extra step in the ABox to a $B_0$-labeled individual and then generate the first object of an existential path:

$$B_0 \cap \exists S(B_2 \cap X_1 \cap \cdots \cap X_{2n} \cap L) \subseteq \exists S.C$$

where

$$C = Y_1 \cap \cdots \cap Y_{2n} \cap B'_2$$

The purpose of the extra step will be explained later on.

6. Here and in the following, we use the abbreviation

$$\exists^{(3)}(X_1, X_2, X_3) := \exists S(X_1 \cap \exists S(X_2 \cap \exists S.X_3))$$

for concept names $X_1, X_2, X_3$.

We continue building the path, decrementing the $Y$-counter:

$$Y_i \cap Y'_i \subseteq \exists^{(3)}(B'_1, B'_0, B'_2)$$

$$B'_j \cap \exists S(B'_j+1 \cap Y'_i) \subseteq Y_i$$

$$B'_j \cap \exists S(B'_j+1 \cap Y'_i) \subseteq Y_i$$

where $i$ ranges over $1..2n$ and $j$ over $\{0, 1, 2\}$. It is essential to use different $B'_i$ and counter concepts $Y_i, Y'_i$ than in the ABox; otherwise the anonymous path could not homomorphically embed into the ABox path in a folded way. It would actually suffice to build a path of length $3 \cdot (2^{2n+1})$ because no violation of ($\ast$) can start in the bottommost row. However, overcounting does not compromise correctness.

7. At the end of the anonymous path, we implement a violation of ($\ast$) as described above: we guess a tile $t$ involved in the violation, make sure that $T'_2$ holds at the current point, start a new counter, travel exactly $3 \cdot 2^n$ steps (without any folding), and verify that $T'_1$ holds where we arrive:

$$\exists^{(3)}(B_1, B_2)$$

$$\exists S(B_2 \cap Y'_i \cap \exists S.Y'_i) \subseteq Y'_i$$

$$\exists S(B_2 \cap Y'_i \cap \exists S.Y'_i) \subseteq Y'_i$$

$$\exists S(B_2 \cap Y'_i \cap \exists S.Y'_i) \subseteq Y'_i$$

$$\exists S(B_2 \cap Y'_i \cap \exists S.Y'_i) \subseteq Y'_i$$

$$\exists S(B_2 \cap Y'_i \cap \exists S.Y'_i) \subseteq Y'_i$$

where $i$ ranges over $1..n$ and $t$ over $T$. Here we use the same $B_i$ as in the ABox to avoid folding.

This finishes the definition of $T_3$. We now define $T_1$, which uses the following additional concept names.

- $D$ for indicating the occurrence of a defect
- $Z_1, \ldots, Z_n$ for an additional counter.

$T_1$ consists of the following CIs.

1. Tiles are mutually exclusive: for all distinct $t, t' \in T$:

$$T \cap T' \subseteq D$$

where $D$ starts a path that implements a violation of ($\ast$), to be implemented below.

2. The problematic situation described at the end of Item 2 in the definition of $T_2$ cannot occur:

$$\exists S(B_k \cap X_i) \cap \exists S(B_k \cap X_i) \subseteq D$$

where $k$ ranges over $\{0, 1, 2\}$ and $i$ over $1..2n$;
We now show how to get rid of disjunction. The central property in the sense that for every model exist. Instead, there is a set of models for correctness of the reduction. Since there is no anonymous

\[
T \models \exists \mathcal{S}.(B_0 \sqcap B_1, B_2) \wedge B_0 \sqcap \exists \mathcal{S}.(B_2 \sqcap \exists \mathcal{Z}_i) \sqcap Z_i \sqcap B_0 \sqsubset \exists \mathcal{S}^{(3)}(B_0, B_1, B_2)
\]

\[
B_{j+1} \sqcap \exists \mathcal{S}.(B_j \sqcap Z_i) \sqsubset Z_i
\]

\[
B_0 \sqcap \exists \mathcal{S}.(B_2 \sqcap \exists \mathcal{S}(B_2 \sqcap Z_i) \sqsubset Z_i)
\]

\[
B_0 \sqcap \exists \mathcal{S}.(B_0 \sqcap \exists \mathcal{S}(B_0 \sqcap \exists \mathcal{S}(B_0 \sqcap \exists \mathcal{Z}_i)) \sqsubset Z_i
\]

\[
Z_1 \sqcap \cdots \sqcap Z_n \sqsubset T_t
\]

where \( i \) ranges over \( 1..n \) and \( t \in \Sigma \) is fixed.

Before we eliminate the disjunction used in \( T_2 \), let us mention the central property of \( T_1 \) and \( T_2 \) that can be used to show correctness of the reduction. Since \( T_2 \) uses disjunction, a universal model for \( T_2 \) and an ABox \( \mathcal{A} \) is not guaranteed to exist. Instead, there is a set of models for \( T_2 \) and \( \mathcal{A} \) that is universal in the sense that for every model \( \mathcal{I} \) of \( T_2 \) and \( \mathcal{A} \), there is a model in the set that admits a homomorphism into \( \mathcal{I} \). We refrain from giving a formal definition. Now, the central property of \( T_1 \) is as follows: \( P \) has a solution iff there is a tree-shaped \( \text{sig}(T_1) \)-ABox \( \mathcal{A} \) consistent with \( T_1 \cup T_2 \) such that, for every \( \mathcal{I} \) in the universal set of models for \( T_1 \cup T_2 \), there is no \text{sig}(T_1)-\text{homomorphism} from \( \mathcal{I} \) to \( \mathcal{I}_{T_1 \cup \mathcal{A}} \).

We now show how to get rid of disjunction. The central property of \( T_1 \) and \( T_2 \) will essentially be preserved, with a single universal model playing the role of the universal set of models. The disjunctions on the left-hand sides of clauses only serve as abbreviations and can easily be removed with only a polynomial blowup of TBox sizes. What remains is the disjunction in Item 7 of the definition of \( T_2 \). To get rid of it, we need to modify both \( T_1 \) and \( T_2 \):

- In the first line of Point 7 of the definition of \( T_2 \), the disjunction is replaced with a conjunction, generating \(|\Sigma| \) many defective chains at once:

\[
\bar{Y}_1 \sqcap \cdots \sqcap \bar{Y}_n \sqsubset \bigcap_{i \in \Sigma} \exists \mathcal{S}.(Y_i' \sqcap \cdots \sqcap Y'_n \sqcap M_2 \sqcap T_i' \sqcap M_i)
\]

The resulting universal model is illustrated in Figure 1, where we assume \( \Sigma = \{t_1, t_2, t_3\} \), showing the final individual on the ABox path, the extra step from Item 5 of the definition of \( T_2 \), the anonymous path, and the branching gadget attached to the end of it.

- We have now generated too many paths and thus the desired homomorphism may not exist even if \( + \) is violated in the ABox. We compensate by enforcing in \( T_1 \) that when a \( M_2 \)-individual in the ABox path is labeled with \( T_i' \), then it’s \( B_0 \)-predecessor on that path roots \(|\Sigma| - 1 \) many additional paths, realizing every possible violation of \( + \) except the one induced by \( t \in \Sigma \). This is illustrated in Figure 2 where we again assume \( \Sigma = \{t_1, t_2, t_3\} \), showing a \( B_2 \)-individual labeled with \( T_i' \) and the extra successors of it’s \( B_0 \)-predecessor generated by \( T_1 \).

![Figure 1: Part of the universal model of \( T_2 \).](image)

Note that this explains the extra step in Item 5 of the definition of \( T_2 \) since also the final \( B_2 \)-element of the ABox path must have a \( B_0 \)-predecessor.

We add the following to \( T_1 \), using fresh concept names \( M'_i, t \in \Sigma \):

\[
B_0 \sqcap \exists \mathcal{S}.(B_2 \sqcap T_i') \sqsubset \bigcap_{t \in \Sigma} \exists \mathcal{S}.(Y_i' \sqcap \cdots \sqcap Y'_n \sqcap B_2 \sqcap T_i' \sqcap M_i)
\]

where \( i \) ranges over \( 1..n \) and \( t \) over \( \Sigma \).

**Lemma 34** \( T_1 \cup T_2 \) is a \( \text{sig}(T_1), \text{sig}(T_2) \)-stCQ-conservative extension of \( T_1 \) iff there is no solution for \( P \).

**Proof.** By Lemma 33 it suffices to show the following.

**Claim.** \( P \) has a solution iff there is a tree-shaped \( \text{sig}(T_1) \)-ABox \( \mathcal{A} \) such that there is no \( \text{sig}(T_1) \)-homomorphism from \( \mathcal{I}_{T_1 \cup T_2 \cup \mathcal{A}} \) to \( \mathcal{I}_{T_1 \cup \mathcal{A}} \).

We now sketch a proof of the claim.
Figure 2: Extra successors to eliminate disjunction

“⇒”. Assume that $P$ has a solution. Let $A$ be the ABox that contains a single $S$-path of length $3 \cdot 2^n$ which correctly encodes the solution to $P$ via the concept names $X_i, \overline{X}_i, B_i, T_i, T'_i$. Since $A$ correctly encodes the tiling, there is no sig($T_i$)-homomorphism from $I_{T_i \cup T'_i, A}$ to $I_{T_i, A}$; in particular, the anonymous path described by $T'_2$ that ends in $|\Sigma|$ many violations of $(\ast)$, each represented via a path, cannot be mapped to $I_{T_i, A}$.

“⇐”. Assume $P$ has no solution and let $A$ be a tree-shaped sig($T_i$)-ABox. If $A$ contains no path of length $3 \cdot 2^n$ that is labeled in the desired way with the concept names $X_i, \overline{X}_i, B_i, T_i, T'_i$ (and which does not necessarily satisfy $(\ast)$), then the generation of the anonymous path in $I_{T_i \cup T'_i, A}$ is not triggered and the identity is a sig($T_i$)-homomorphism from $I_{T_i \cup T'_i, A}$ to $I_{T_i, A}$. If there is such a path, then it violates $(\ast)$ since $P$ has no solution. Consequently, the anonymous path in $I_{T_i \cup T'_i, A}$ homomorphically maps to $I_{T_i, A}$, which is sufficient to show that there is a homomorphism from $I_{T_i \cup T'_i, A}$ to $I_{T_i, A}$. □