

## Lecture 05 (19.11.2013)

# Statische Programmanalyse

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## Today: Static Program Analysis

- ▶ Analysis of run-time behavior of programs without executing them (sometimes called static testing)
- ▶ Analysis is done for **all** possible runs of a program (i.e. considering all possible inputs)
- ▶ Typical tasks
  - Does the variable  $x$  have a constant value ?
  - Is the value of the variable  $x$  always positive ?
  - Can the pointer  $p$  be null at a given program point ?
  - What are the possible values of the variable  $y$  ?
- ▶ These tasks can be used for verification (e.g. is there any possible dereferencing of the null pointer), or for optimisation when compiling.

## Usage of Program Analysis

### Optimising compilers

- ▶ Detection of sub-expressions that are evaluated multiple times
- ▶ Detection of unused local variables
- ▶ Pipeline optimisations

### Program verification

- ▶ Search for runtime errors in programs
- ▶ Null pointer dereference
- ▶ Exceptions which are thrown and not caught
- ▶ Over/underflow of integers, rounding errors with floating point numbers
- ▶ Runtime estimation (worst-case executing time, wctet; *AbsInt* tool)

## Program Analysis: The Basic Problem

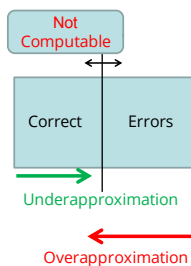
### Basic Problem:

All interesting program properties are undecidable.

- ▶ Given a property  $P$  and a program  $p$ , we say  $p \models P$  if a  $P$  holds for  $p$ . An algorithm (tool)  $\phi$  which decides  $P$  is a computable predicate  $\phi: p \rightarrow Bool$ . We say:
  - $\phi$  is **sound** if whenever  $\phi(p)$  then  $p \models P$ .
  - $\phi$  is **safe** (or **complete**) if whenever  $p \models P$  then  $\phi(p)$ .
- ▶ From the basic problem it follows that there are no sound and safe tools for interesting properties.
  - In other words, all tools must either under- or overapproximate.

## Program Analysis: Approximation

- ▶ **Underapproximation** only finds correct programs but may miss out some
  - Useful in optimising compilers
  - Optimisation must respect semantics of program, but may optimise.
- ▶ **Overapproximation** finds all errors but may find non-errors (false positives)
  - Useful in verification.
  - Safety analysis must find all errors, but may report some more.
  - Too high rate of false positives may hinder acceptance of tool.



## Program Analysis Approach

- ▶ Provides approximate answers
  - yes / no / don't know or
  - superset or subset of values
- ▶ Uses an abstraction of program's behavior
  - Abstract data values (e.g. sign abstraction)
  - Summarization of information from execution paths e.g. branches of the if-else statement
- ▶ Worst-case assumptions about environment's behavior
  - e.g. any value of a method parameter is possible
- ▶ Sufficient precision with good performance

## Flow Sensitivity

### Flow-sensitive analysis

- ▶ Considers program's flow of control
- ▶ Uses control-flow graph as a representation of the source
- ▶ Example: available expressions analysis

### Flow-insensitive analysis

- ▶ Program is seen as an unordered collection of statements
- ▶ Results are valid for any order of statements e.g.  $S1 ; S2$  vs.  $S2 ; S1$
- ▶ Example: type analysis (inference)

## Context Sensitivity

### Context-sensitive analysis

- ▶ Stack of procedure invocations and return values of method parameters then results of analysis of the method  $M$  depend on the caller of  $M$

### Context-insensitive analysis

- ▶ Produces the same results for all possible invocations of  $M$  independent of possible callers and parameter values

## Intra- vs. Inter-procedural Analysis

### Intra-procedural analysis

- ▶ Single function is analyzed in isolation
- ▶ Maximally pessimistic assumptions about parameter values and results of procedure calls

### Inter-procedural analysis

- ▶ Whole program is analyzed at once
- ▶ Procedure calls are considered

## Data-Flow Analysis

Focus on questions related to values of variables and their lifetime

Selected analyses:

- ▶ **Available expressions (forward analysis)**
  - Which expressions have been computed already without change of the occurring variables (optimization)?
- ▶ **Reaching definitions (forward analysis)**
  - Which assignments contribute to a state in a program point? (verification)
- ▶ **Very busy expressions (backward analysis)**
  - Which expressions are executed in a block regardless which path the program takes (verification)?
- ▶ **Live variables (backward analysis)**
  - Is the value of a variable in a program point used in a later part of the program (optimization)?

## A Very Simple Programming Language

- ▶ In the following, we use a very simple language with
  - Arithmetic operators given by
 
$$a ::= x \mid n \mid a_1 \text{ op}_a a_2$$
 with  $x$  a variable,  $n$  a numeral,  $\text{op}_a$  arith. op. (e.g. +, -, \*)
  - Boolean operators given by
 
$$b ::= \text{true} \mid \text{false} \mid \text{not } b \mid b_1 \text{ op}_b b_2 \mid a_1 \text{ op}_r a_2$$
 with  $\text{op}_b$  boolean operator (e.g. and, or) and  $\text{op}_r$  a relational operator (e.g. =, <)
  - Statements given by
 
$$S ::= [x := a]^l \mid [\text{skip}]^l \mid S_1; S_2 \mid \text{if } [b]^l \text{ then } S_1 \text{ else } S_2 \mid \text{while } [b]^l \text{ do } S$$

▶ An Example Program:

```
[x := a+b]1;
[y := a*b]2;
while [y > a+b]3 do ([a:=a+1]4; [x:= a+b]5)
```

## The Control Flow Graph

- ▶ We define some functions on the abstract syntax:
  - The initial label (entry point)  $\text{init}: S \rightarrow \text{Lab}$
  - The final labels (exit points)  $\text{final}: S \rightarrow \mathbb{P}(\text{Lab})$
  - The elementary blocks  $\text{block}: S \rightarrow \mathbb{P}(\text{Blocks})$  where an elementary block is
    - an assignment  $[x:= a]$ ,
    - or  $[\text{skip}]$ ,
    - or a test  $[b]$
  - The control flow flow:  $S \rightarrow \mathbb{P}(\text{Lab} \times \text{Lab})$  and reverse control flow  $R: S \rightarrow \mathbb{P}(\text{Lab} \times \text{Lab})$ .
- ▶ The **control flow graph** of a program  $S$  is given by
  - elementary blocks  $\text{block}(S)$  as nodes, and
  - $\text{flow}(S)$  as vertices.

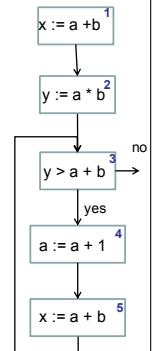
## Labels, Blocks, Flows: Definitions

$\text{final}([x := a]^l) = \{l\}$ $\text{final}([\text{skip}]^l) = \{l\}$ $\text{final}(S_1; S_2) = \text{final}(S_2)$ $\text{final}(\text{if } [b]^l \text{ then } S_1 \text{ else } S_2) = \text{final}(S_1) \cup \text{final}(S_2)$ $\text{final}(\text{while } [b]^l \text{ do } S) = \{l\}$	$\text{init}([x := a]^l) = l$ $\text{init}([\text{skip}]^l) = l$ $\text{init}(S_1; S_2) = \text{init}(S_1)$ $\text{init}(\text{if } [b]^l \text{ then } S_1 \text{ else } S_2) = l$ $\text{init}(\text{while } [b]^l \text{ do } S) = l$
$\text{flow}([x := a]^l) = \emptyset$ $\text{flow}([\text{skip}]^l) = \emptyset$ $\text{flow}(S_1; S_2) = \text{flow}(S_1) \cup \text{flow}(S_2) \cup \{(l, \text{init}(S_2)) \mid l \in \text{final}(S_1)\}$ $\text{flow}(\text{if } [b]^l \text{ then } S_1 \text{ else } S_2) = \text{flow}(S_1) \cup \text{flow}(S_2) \cup \{(l, \text{init}(S_1)), (l, \text{init}(S_2))\}$ $\text{flow}(\text{while } [b]^l \text{ do } S) = \text{flow}(S) \cup \{(l, \text{init}(S)) \mid l \in \text{final}(S)\}$	$\text{flow}^R(S) = \{(l', l) \mid (l, l') \in \text{flow}(S)\}$
$\text{blocks}([x := a]^l) = \{[x := a]^l\}$ $\text{blocks}([\text{skip}]^l) = \{[\text{skip}]^l\}$ $\text{blocks}(S_1; S_2) = \text{blocks}(S_1) \cup \text{blocks}(S_2)$ $\text{blocks}(\text{if } [b]^l \text{ then } S_1 \text{ else } S_2) = \{[b]^l\} \cup \text{blocks}(S_1) \cup \text{blocks}(S_2)$ $\text{blocks}(\text{while } [b]^l \text{ do } S) = \{[b]^l\} \cup \text{blocks}(S)$	$\text{labels}(S) = \{l \mid [B]^l \in \text{blocks}(S)\}$ $\text{FV}(a) = \text{free variables in } a$ $\text{Aexp}(S) = \text{nontrivial subexpressions of } S$

## Another Example

$P = [x := a+b]^1; [y := a*b]^2; \text{while } [y > a+b]^3 \text{ do } ([a:=a+1]^4; [x:= a+b]^5)$

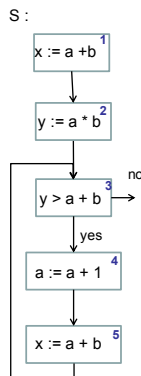
$\text{init}(P) = 1$   
 $\text{final}(P) = \{3\}$   
 $\text{blocks}(P) = \{[x := a+b]^1, [y := a*b]^2, [y > a+b]^3, [a:=a+1]^4, [x:= a+b]^5\}$   
 $\text{flow}(P) = \{(1, 2), (2, 3), (3, 4), (4, 5), (5, 3)\}$   
 $\text{flow}^R(P) = \{(2, 1), (3, 2), (4, 3), (5, 4), (3, 5)\}$   
 $\text{labels}(P) = \{1, 2, 3, 4, 5\}$   
 $\text{FV}(a+b) = \{a, b\}$



## Available Expression Analysis

- ▶ The available expression analysis will determine:

For each program point, which expressions must have already been computed, and not later modified, on all paths to this program point.

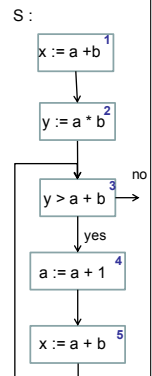


## Available Expression Analysis

$\text{gen}([x := a]^l) = \{a' \in \text{Aexp}(a) \mid x \notin \text{FV}(a')\}$   
 $\text{gen}([\text{skip}]^l) = \emptyset$   
 $\text{gen}([b]^l) = \text{Aexp}(b)$   
 $\text{kill}([x := a]^l) = \{a' \in \text{Aexp}(S) \mid x \in \text{FV}(a')\}$   
 $\text{kill}([\text{skip}]^l) = \emptyset$   
 $\text{kill}([b]^l) = \emptyset$   
 $\text{AE}_{\text{in}}(l) = \emptyset$ , if  $l \in \text{init}(S)$  and  
 $\text{AE}_{\text{in}}(l) = \bigcap \{\text{AE}_{\text{out}}(l') \mid (l', l) \in \text{flow}(S)\}$ , otherwise  
 $\text{AE}_{\text{out}}(l) = (\text{AE}_{\text{in}}(l) \setminus \text{kill}(B^l)) \cup \text{gen}(B^l)$  where  $B^l \in \text{blocks}(S)$

l	kill(l)	gen(l)
1		
2		
3		
4		
5		

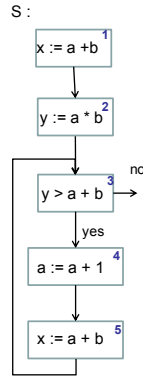
l	AE <sub>in</sub>	AE <sub>out</sub>
1		
2		
3		
4		
5		



## Available Expression Analysis

$gen([x := a]^l) = \{a' \in Aexp(a) \mid x \notin FV(a')\}$   
 $gen([skip]^l) = \emptyset$   
 $gen([b]^l) = Aexp(b)$   
 $kill([x := a]^l) = \{a' \in Aexp(S) \mid x \in FV(a')\}$   
 $kill([skip]^l) = \emptyset$   
 $kill([b]^l) = \emptyset$   
 $AE_{in}(l) = \emptyset$ , if  $l \in \text{init}(S)$  and  
 $AE_{in}(l) = \bigcap \{AE_{out}(l') \mid (l', l) \in \text{flow}(S)\}$ , otherwise  
 $AE_{out}(l) = (AE_{in}(l) \setminus kill(B^l)) \cup gen(B^l)$  where  $B^l \in \text{blocks}(S)$

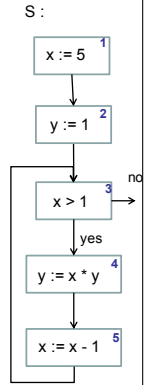
l	kill(l)	gen(l)	l	AE <sub>in</sub>	AE <sub>out</sub>
1	$\emptyset$	$\{a+b\}$	1	$\emptyset$	$\{a+b\}$
2	$\emptyset$	$\{a*b\}$	2	$\{a+b\}$	$\{a+b, a*b\}$
3	$\emptyset$	$\{a+b\}$	3	$\{a+b\}$	$\{a+b\}$
4	$\{a+b, a*b, a+1\}$	$\emptyset$	4	$\{a+b\}$	$\emptyset$
5	$\emptyset$	$\{a+b\}$	5	$\emptyset$	$\{a+b\}$



## Reaching Definitions Analysis

► Reaching definitions (assignment) analysis determines if:

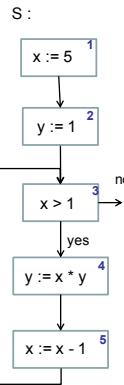
An assignment of the form  $[x := a]^l$  may reach a certain program point  $k$  if there is an execution of the program where  $x$  was last assigned a value at  $l$  when the program point  $k$  is reached



## Reaching Definitions Analysis

$gen([x := a]^l) = \{(x, l)\}$   
 $gen([skip]^l) = \emptyset$   
 $gen([b]^l) = \emptyset$   
 $kill([skip]^l) = \emptyset$   
 $kill([b]^l) = \emptyset$   
 $kill([x := a]^l) = \{(x, ?)\} \cup \{(x, k) \mid B^k \text{ is an assignment to } x \text{ in } S\}$   
 $RD_{in}(l) = \{(x, ?) \mid x \in FV(S)\}$ , if  $l \in \text{init}(S)$  and  
 $RD_{in}(l) = \bigcup \{RD_{out}(l') \mid (l', l) \in \text{flow}(S)\}$ , otherwise  
 $RD_{out}(l) = (RD_{in}(l) \setminus kill(B^l)) \cup gen(B^l)$  where  $B^l \in \text{blocks}(S)$

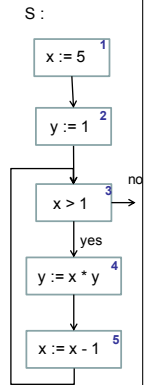
l	RD <sub>in</sub>	RD <sub>out</sub>
1		
2		
3		
4		
5		



## Reaching Definitions Analysis

$gen([x := a]^l) = \{(x, l)\}$   
 $gen([skip]^l) = \emptyset$   
 $gen([b]^l) = \emptyset$   
 $kill([skip]^l) = \emptyset$   
 $kill([b]^l) = \emptyset$   
 $kill([x := a]^l) = \{(x, ?)\} \cup \{(x, k) \mid B^k \text{ is an assignment to } x \text{ in } S\}$   
 $RD_{in}(l) = \{(x, ?) \mid x \in FV(S)\}$ , if  $l \in \text{init}(S)$  and  
 $RD_{in}(l) = \bigcup \{RD_{out}(l') \mid (l', l) \in \text{flow}(S)\}$ , otherwise  
 $RD_{out}(l) = (RD_{in}(l) \setminus kill(B^l)) \cup gen(B^l)$  where  $B^l \in \text{blocks}(S)$

l	RD <sub>in</sub>	RD <sub>out</sub>
1	$\{(x, ?), (y, ?)\}$	$\{(x, 1), (y, ?)\}$
2	$\{(x, 1), (y, ?)\}$	$\{(x, 1), (y, 2)\}$
3	$\{(x, 1), (x, 5), (y, 2), (y, 4)\}$	$\{(x, 1), (x, 5), (y, 2), (y, 4)\}$
4	$\{(x, 1), (x, 5), (y, 2), (y, 4)\}$	$\{(x, 1), (x, 5), (y, 4)\}$
5	$\{(x, 1), (x, 5), (y, 4)\}$	$\{(x, 5), (y, 4)\}$



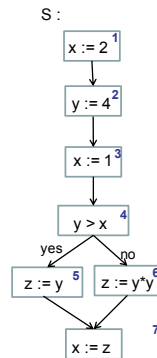
## Live Variables Analysis

► A variable  $x$  is **live** at some program point (label  $l$ ) if there exists a path from  $l$  to an exit point that does not change the variable.

► Live Variables Analysis determines:

For each program point, which variables *may* be live at the exit from that point.

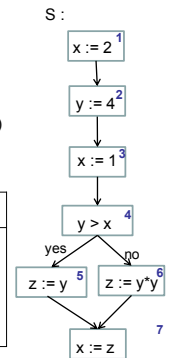
► Application: dead code elimination.



## Live Variables Analysis

$gen([x := a]^l) = FV(a)$   
 $gen([skip]^l) = \emptyset$   
 $gen([b]^l) = FV(b)$   
 $kill([x := a]^l) = \{x\}$   
 $kill([skip]^l) = \emptyset$   
 $kill([b]^l) = \emptyset$   
 $LV_{out}(l) = \emptyset$ , if  $l \in \text{final}(S)$  and  
 $LV_{out}(l) = \bigcup \{LV_{in}(l') \mid (l', l) \in \text{flow}^R(S)\}$ , otherwise  
 $LV_{in}(l) = (LV_{out}(l) \setminus kill(B^l)) \cup gen(B^l)$  where  $B^l \in \text{blocks}(S)$

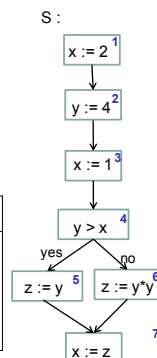
l	kill(l)	gen(l)	l	LV <sub>in</sub>	LV <sub>out</sub>
1			1		
2			2		
3			3		
4			4		
5			5		
6			6		
7			7		



## Live Variables Analysis

$gen([x := a]^l) = FV(a)$   
 $gen([skip]^l) = \emptyset$   
 $gen([b]^l) = FV(b)$   
 $kill([x := a]^l) = \{x\}$   
 $kill([skip]^l) = \emptyset$   
 $kill([b]^l) = \emptyset$   
 $LV_{out}(l) = \emptyset$ , if  $l \in \text{final}(S)$  and  
 $LV_{out}(l) = \bigcup \{LV_{in}(l') \mid (l', l) \in \text{flow}^R(S)\}$ , otherwise  
 $LV_{in}(l) = (LV_{out}(l) \setminus kill(B^l)) \cup gen(B^l)$  where  $B^l \in \text{blocks}(S)$

l	kill(l)	gen(l)	l	LV <sub>in</sub>	LV <sub>out</sub>
1	$\{x\}$	$\emptyset$	1	$\emptyset$	$\emptyset$
2	$\{y\}$	$\emptyset$	2	$\emptyset$	$\{y\}$
3	$\{x\}$	$\emptyset$	3	$\{y\}$	$\{x, y\}$
4	$\emptyset$	$\{x, y\}$	4	$\{x, y\}$	$\{y\}$
5	$\{z\}$	$\{y\}$	5	$\{y\}$	$\{z\}$
6	$\{z\}$	$\{y\}$	6	$\{y\}$	$\{z\}$
7	$\{x\}$	$\{z\}$	7	$\{z\}$	$\emptyset$



## First Generalized Schema

► Analyse<sub>\*</sub>( $l$ ) = **EV**, if  $l \in \mathbf{E}$  and  
 ► Analyse<sub>\*</sub>( $l$ ) =  $\sqcup \{ \text{Analyse}_*(l') \mid (l', l) \in \mathbf{Flow}(S) \}$ , otherwise  
 ► Analyse<sub>\*</sub>( $l$ ) =  $f_l(\text{Analyse}_*(l))$

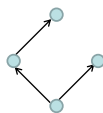
With:

- $\sqcup$  is either  $\cup$  or  $\cap$
- EV is the initial / final analysis information
- Flow is either flow or flow<sup>R</sup>
- E is either {init(S)} or final(S)
- $f_l$  is the transfer function associated with  $B^l \in \text{blocks}(S)$

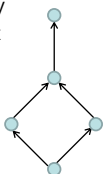
Backward analysis:  $F = \text{flow}^R$ ,  $\bullet = \text{IN}$ ,  $\circ = \text{OUT}$   
 Forward analysis:  $F = \text{flow}$ ,  $\bullet = \text{OUT}$ ,  $\circ = \text{IN}$

## Partial Order

- ▶  $L = (M, \sqsubseteq)$  is a **partial order** iff
  - Reflexivity:  $\forall x \in M. x \sqsubseteq x$
  - Transitivity:  $\forall x, y, z \in M. x \sqsubseteq y \wedge y \sqsubseteq z \Rightarrow x \sqsubseteq z$
  - Anti-symmetry:  $\forall x, y \in M. x \sqsubseteq y \wedge y \sqsubseteq x \Rightarrow x = y$



- ▶ Let  $L = (M, \sqsubseteq)$  be a partial order,  $S \subseteq M$ .
  - $y \in M$  is **upper bound** for  $S$  ( $S \sqsubseteq y$ ) iff  $\forall x \in S. x \sqsubseteq y$
  - $y \in M$  is **lower bound** for  $S$  ( $y \sqsubseteq S$ ) iff  $\forall x \in S. y \sqsubseteq x$
  - **Least upper bound**  $\sqcup X \in M$  of  $X \subseteq M$ :
    - ▶  $X \sqsubseteq \sqcup X \wedge \forall y \in M: X \sqsubseteq y \Rightarrow \sqcup X \sqsubseteq y$
  - **Greatest lower bound**  $\sqcap X \in M$  of  $X \subseteq M$ :
    - ▶  $\sqcap X \sqsubseteq X \wedge \forall y \in M: y \sqsubseteq X \Rightarrow y \sqsubseteq \sqcap X$



## Lattice

A **lattice** ("Verbund") is a partial order  $L = (M, \sqsubseteq)$  such that

- ▶  $\sqcup X$  and  $\sqcap X$  exist for all  $X \subseteq M$
- ▶ Unique greatest element  $T = \sqcup M = \sqcap \emptyset$
- ▶ Unique least element  $\perp = \sqcap M = \sqcup \emptyset$

## Transfer Functions

- ▶ Transfer functions to propagate information along the execution path (i.e. from input to output, or vice versa)
- ▶ Let  $L = (M, \sqsubseteq)$  be a lattice. Set  $F$  of transfer functions of the form  $f_i: L \rightarrow L$  with  $i$  being a label
- ▶ Knowledge transfer is monotone
  - $\forall x, y. x \sqsubseteq y \Rightarrow f_i(x) \sqsubseteq f_i(y)$
- ▶ Space  $F$  of transfer functions
  - $F$  contains all transfer functions  $f_i$
  - $F$  contains the identity function  $\text{id}$ , i.e.  $\forall x \in M. \text{id}(x) = x$
  - $F$  is closed under composition, i.e.  $\forall f, g \in F. (f \circ g) \in F$

## The Generalized Analysis

- ▶  $\text{Analyse}_*(I) = \sqcup \{ \text{Analyse}_*(I') \mid (I', I) \in \text{Flow}(S) \} \sqcup \perp_{I \in E}$   
with  $\perp_{I \in E} = \text{EV}$  if  $I \in E$  and  $\perp_{I \in E} = \perp$  otherwise
- ▶  $\text{Analyse}_*(I) = f_i(\text{Analyse}_*(I))$

With:

- ▶  $L$  property space representing data flow information with  $(L, \sqsubseteq)$  being a lattice
- ▶ Flow is a finite flow (i.e. flow or flow<sup>R</sup>)
- ▶ **EV** is an extremal value for the extremal labels  $E$  (i.e.  $\{\text{init}(S)\}$  or  $\{\text{final}(S)\}$ )
- ▶ transfer functions  $f_i$  of a space of transfer functions  $F$

## Summary

- ▶ Static Program Analysis is the analysis of run-time behavior of programs without executing them (sometimes called static testing).
- ▶ Approximations of program behaviours by analyzing the program's cfg.
- ▶ Analysis include
  - available expressions analysis,
  - reaching definitions,
  - live variables analysis.
- ▶ These are instances of a more general framework.
- ▶ These techniques are used commercially, e.g.
  - AbsInt aiT (WCET)
  - Astrée Static Analyzer (C program safety)