## Forward with Hoare!

2009: Tony Hoare is 75 and Hoare Logic is 40 !
An Axiomatic Basis for
Computer Programming
C. A. R. Hoare, 1969

Overview of talk:

- Review of Hoare Logic
- Mechanical proof
- Forwards versus backwards
[Slides that follow are based on joint work with Hélène Collavizza]


## Hoare's Axiomatic Basis for Computer Programming

- Originally both
- an axiomatic language definition method and
- a proof theory for program verification
- This talk focuses on the verification role
- after 40 years it is still a key idea in program correctness
- However, instead of
"... accepting the axioms and rules of inference as the ultimately definitive specification of the meaning of the language."
can derive axioms and rules from language semantics


## Range of methods for proving $\{P\} C\{Q\}$

- Bounded model checking (BMC)
- unwind loops a finite number of times
- then symbolically execute
- check states reached satisfy decidable properties
- Full proof of correctness
- add invariants to loops
- generate verification conditions
- prove verification conditions with a theorem prover
- Goal: unifying framework for a spectrum of methods


## Some history: concepts related to $\{P\} C\{Q\}$

- WP C Q is Dijkstra's 'weakest liberal precondition'
(i.e. partial correctness: wlp.c. \& from Dijkstra \& Scholten)
- precondition WP C Q ensures $Q$ holds after $C$ terminates
- wlp.C. $Q$ is weakest solution of $P:(\{P\} C\{Q\})$
( Predicate Calculus \& Program Semantics, Dijkstra \& Scholten, 1990)
- SP C P is 'strongest postcondition'
(sp.C.Q in Dijkstra \& Scholten, Ch. 12 - not stp.C.Q)
- SP C $P$ holds after $C$ terminates if started when $P$ holds
- sp.C.P is strongest solution of $Q:(\{P\} C\{Q\})$


## Defining specification notions by semantic embedding

- Semantics of commands $C$ given by binary relation $\llbracket C \rrbracket$
- $\llbracket C \rrbracket\left(s, s^{\prime}\right)$ means if $C$ run in $s$ then it will terminate in $s^{\prime}$
- $s$ is the initial state; $s^{\prime}$ is a final state
- commands assumed deterministic - at most one final state ("Formalizing Dijkstra" by J. Harrison for non-determinism)
- $\{P\} C\{Q\}={ }_{\operatorname{def}} \forall s s^{\prime} . P s \wedge \llbracket C \rrbracket\left(s, s^{\prime}\right) \Rightarrow Q s^{\prime}$
- WP C Q $={ }_{\operatorname{def}} \lambda s . \forall s^{\prime} . \llbracket C \rrbracket\left(s, s^{\prime}\right) \Rightarrow Q s^{\prime}$
$-\vdash\{P\} C\{Q\}=\forall s . P s \Rightarrow W P C Q s$
- $S P C P=\operatorname{def} \lambda s^{\prime} . \exists s . P s \wedge \llbracket C \rrbracket\left(s, s^{\prime}\right)$
$-\vdash\{P\} C\{Q\}=\forall s . S P C P s \Rightarrow Q s$


## Details and notations

－$\{P\} C\{Q\}=\operatorname{def} \forall s s^{\prime} . P s \wedge \llbracket C \rrbracket\left(s, s^{\prime}\right) \Rightarrow Q s^{\prime}$
－P，$Q$ ：state $\rightarrow$ bool
－state $=$ string $\mapsto$ value（finite map）
－$s[x \rightarrow v]$ is the state mapping $x$ to $v$ and like $s$ elsewhere
－$\left[x_{1} \rightarrow v_{1} ; \cdots ; x_{n} \rightarrow v_{n}\right]$ has domain $\left\{x_{1}, \cdots, x_{n}\right\}$ ；maps $x_{i}$ to $v_{i}$

- 【C】 ：state $\times$ state $\rightarrow$ bool
- 【B】 ：state $\rightarrow$ bool
- 【E』 ：state $\rightarrow$ value
－WP C ：$($ state $\rightarrow$ bool $) \rightarrow($ state $\rightarrow$ bool $)$
－SP C ：$($ state $\rightarrow$ bool $) \rightarrow($ state $\rightarrow$ bool $)$
－Overload $\wedge, \vee, \Rightarrow$ ，$\neg$ to pointwise operations on predicates
－$\left(P_{1} \wedge P_{2}\right) s=P_{1} s \wedge P_{2} s$
－$\left(P_{1} \vee P_{2}\right) s=P_{1} s \vee P_{2} s$
－$\left(P_{1} \Rightarrow P_{2}\right) s=P_{1} s \Rightarrow P_{2} s$
－$(\neg P) s=\neg(P s)$
－Define： $\operatorname{TAUT}(P)=d_{\text {def }} \forall s . P s$ and $\operatorname{sAT}(P)=d_{d e f} \exists s . P s$


## Proving $\{P\} C\{Q\}$ by calculating WP $C Q$

- Easy consequences of definition of WP
- WP (SKIP) $Q=Q$
- WP $(X:=E) Q=\lambda s . Q(s[X \rightarrow \llbracket E \rrbracket s])$
- WP $\left(C_{1} ; C_{2}\right) Q=W P C_{1}\left(W P C_{2} Q\right)$
- WP (IF B THEN $C_{1}$ ELSE $\left.C_{2}\right) Q=$

$$
\left(\llbracket B \rrbracket \Rightarrow W P C_{1} Q\right) \wedge\left(\neg \llbracket B \rrbracket \Rightarrow W P C_{2} Q\right)
$$

- WP (WHILE B DO C) $Q=$

$$
(\llbracket B \rrbracket \Rightarrow W P C(W P(\text { WHILE } B D O C) Q)) \wedge(\neg \llbracket B \rrbracket \Rightarrow Q)
$$

- To prove $\{P\} C\{Q\}$ for straight line code
- calculate WPC Q $\ldots \ldots$. ... back substitution + case splits
- prove $\forall s . P s \Rightarrow W P C Q s \ldots . . .$. use a theorem prover


## Proving $\{P\} C\{Q\}$ by calculating $S P C P$

- Easy consequences of definition of $S P$
- SPSKIP $P=P$
- $S P(X:=E) P=\lambda s^{\prime} . \exists s . P s \wedge\left(s^{\prime}=s[X \rightarrow \llbracket E \rrbracket s]\right)$
- $S P\left(C_{1} ; C_{2}\right) P=S P C_{2}\left(S P P C_{1}\right)$
- $S P\left(\right.$ IF $B$ THEN $C_{1}$ ELSE $\left.C_{2}\right) P=$ $S P C_{1}(P \wedge \llbracket B \rrbracket) \vee S P C_{2}(P \wedge \neg \llbracket B \rrbracket)$
- $S P($ WHILE $B$ DO C) $P=$ $S P($ WHILE $B$ DO $C)(S P(P \wedge \llbracket B \rrbracket) C) \vee(P \wedge \neg \llbracket B \rrbracket)$
- To prove $\{P\} C\{Q\}$ for straight line code
- calculate SP P C ..... assignment generated $\exists$ s a problem
- prove $\forall s^{\prime}$. SP C $P s^{\prime} \Rightarrow Q s^{\prime} \ldots \ldots$..... use a theorem prover


## Pruning conditional branches when going forwards

- Recall

$$
\begin{aligned}
& S P\left(\text { IF } B \text { THEN } C_{1} \text { ELSE } C_{2}\right) P= \\
& S P C_{1}(P \wedge \llbracket B \rrbracket) \vee S P C_{2}(P \wedge \neg \llbracket B \rrbracket)
\end{aligned}
$$

- Because SPC( $\lambda s . F)=\lambda s^{\prime}$. $F$ it follows that

$$
\begin{aligned}
& (P \Rightarrow \llbracket B \rrbracket) \\
& \Rightarrow \vec{S} P\left(\text { IF } B \text { THEN } C_{1} \text { ELSE } C_{2}\right) P=S P C_{1}(P \wedge \llbracket B \rrbracket) \\
& (P \Rightarrow \neg \llbracket B \rrbracket) \\
& \Rightarrow \vec{S} P\left(\text { IF } B \text { THEN } C_{1} \text { ELSE } C_{2}\right) P=S P C_{2}(P \wedge \neg \llbracket B \rrbracket)
\end{aligned}
$$

- Hence can simplify if accumulated constraints implies test


## Pruning conditional branches when going backwards

- Recall

$$
\begin{aligned}
& W P\left(\text { IF } B \text { THEN } C_{1} \text { ELSE } C_{2}\right) Q= \\
& \left(\llbracket B \rrbracket \Rightarrow W P C_{1} Q\right) \wedge\left(\neg \llbracket B \rrbracket \Rightarrow W P C_{2} Q\right)
\end{aligned}
$$

- Hence

$$
\begin{aligned}
& \left(\llbracket B \rrbracket \Rightarrow W P C_{1} Q\right) \\
& \vec{W} P\left(\operatorname{IF} B \text { THEN } C_{1} \text { ELSE } C_{2}\right) Q=\left(\neg \llbracket B \rrbracket \Rightarrow W P C_{2} Q\right) \\
& \left(\neg \llbracket B \rrbracket \Rightarrow W P C_{2} Q\right) \\
& \stackrel{\rightharpoonup}{W} P\left(\text { IF } B \text { THEN } C_{1} \operatorname{ELSE} C_{2}\right) Q=\left(\llbracket B \rrbracket \Rightarrow W P C_{1} Q\right)
\end{aligned}
$$

- Backwards pruning conditions involve $C_{1}$ or $C_{2}$
- forwards pruning natural - generalised execution
- forwards pruning conditions don't involve $C_{1}$ or $C_{2}$


## Backwards or forwards?

- Calculating WP C Q is easy but leads to big formulae
- can't use symbolic state to prune case splits 'on-the-fly'
- Calculating SPC P generates $\exists$ at assignments
- at branches symbolic state can reject infeasible paths
- Consider $\{P\} C_{1} ;\left(\right.$ IF $B$ THEN $C_{2}$ ELSE $\left.C_{3}\right) ; C_{4}\{Q\}$
- going forwards $P$ and effect of $C_{1}$ might determine $B$
- if $P$ specifies a unique state, computing $S P$ is execution
- Example

$$
\begin{aligned}
& \{J \leq I\} \\
& K:=0 ; \\
& \text { IF } I<J \text { THEN } K:=K+1 \text { ELSE SKIP; } \\
& \text { IF } K=1 \wedge \neg(I=J) \text { THEN } R:=J-I \text { ELSE } R:=I-J \\
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## Summary so far

- Define $\{P\} C\{Q\}, W P C Q$ and $S P C P$ from semantics
- Prove rules for calculating WP C Q and SP C P
- one-off proofs
- For particular $P, C, Q$, to prove $\{P\} C\{Q\}$ :
- calculate WP C Q by backwards substitution
- prove $\forall s . P s \Rightarrow W P C Q s$ using theorem prover
or
- calculate $S P C P$ by symbolic execution
- prove $\forall s^{\prime}$. SP C $P s^{\prime} \Rightarrow Q s^{\prime}$ using theorem prover
- Next: what about loops?


## Can't compute finite WP or SP for loops

- Loop-free: can calculate finite formulae for WP and SP
- Loops: no simple finite formula for WP or $S P$ in general
- WP (WHILE BDO C) $Q=$
$(\llbracket B \rrbracket \wedge$ WP $C(W P(W H I L E B D O C) Q)) \vee(\neg \llbracket B \rrbracket \wedge Q)$
- SP(WHILE B DO C) $P=$ $(S P($ WHILE $B D O C)(S P C(P \wedge \llbracket B \rrbracket))) \vee(P \wedge \neg \llbracket B \rrbracket)$
- Solution inspired by Hoare logic rule ( $R$ is an invariant)

$$
\frac{\vdash P \Rightarrow R \quad \vdash\{R \wedge B\} C\{R\} \quad \vdash R \wedge \neg B \Rightarrow Q}{\qquad\{P\} \text { WHILE } B \text { DO } C\{Q\}}
$$

- Use approximate WP or $S P$ plus verification conditions


## Method of verification conditions (VCs)

- Define AWP and ASP ("A" for "approximate")
- like WP, SP for skip, assignment, sequencing, conditional
- for while-loops assume invariant $R$ magically supplied
$A W P($ WHILE $B$ DO $\{R\} C) Q=R$
$A S P($ WHILE $B$ DO $\{R\} C) P=R \wedge \neg \llbracket B \rrbracket$
- Define WVC C Q and SVC C P to generate VCs (details later)
- Prove $\{P\} C\{Q\}$ using theorems

$$
\begin{aligned}
& W V C C Q \Rightarrow\{A W P C Q\} C\{Q\} \\
& S V C C P \Rightarrow\{P\} C\{A S P C P\}
\end{aligned}
$$

- If $C$ is loop-free (i.e. straight line code) then this becomes

$$
\begin{aligned}
& \mathrm{T} \Rightarrow\{W P C Q\} C\{Q\} \\
& \mathrm{T} \Rightarrow\{P\} C\{S P C P\}
\end{aligned}
$$

## A problem

- Have SP C $(\lambda s . F)=\left(\lambda s^{\prime} . F\right)$ so can reduce $S P\left(\right.$ IF $B$ THEN $C_{1}$ ELSE $\left.C_{2}\right) P$
to
$S P C_{1}(P \wedge \llbracket B \rrbracket)$ or $S P C_{2}(P \wedge \neg \llbracket B \rrbracket)$ if $P$ determines value of $\llbracket B \rrbracket$
- But ASP C $(\lambda s . F)$ is not necessarily ( $\lambda s^{\prime} . \mathrm{F}$ ) $A S P$ (WHILE $B$ DO $\{R\} C) P=R \wedge \neg \llbracket B \rrbracket$ so cannot reduce $A S P\left(\right.$ IF $B$ THEN $C_{1}$ ELSE $\left.C_{2}\right) P$
- A solution is to define

ASP (WHILE B DO \{R\} C) $P=$ $\lambda s^{\prime} . \operatorname{SAT}(P) \wedge R s^{\prime} \wedge \neg\left(\llbracket B \rrbracket s^{\prime}\right)$

- Can then show $A S P C(\lambda s . F)=\left(\lambda s^{\prime} . F\right)$


## A problem

- Have SP C $(\lambda s . F)=\left(\lambda s^{\prime} . F\right)$ so can reduce $S P\left(\right.$ IF $B$ THEN $C_{1}$ ELSE $\left.C_{2}\right) P$
to
$S P C_{1}(P \wedge \llbracket B \rrbracket)$ or $S P C_{2}(P \wedge \neg \llbracket B \rrbracket)$ if $P$ determines value of $\llbracket B \rrbracket$
- But ASP C $(\lambda s . F)$ is not necessarily $\left(\lambda s^{\prime} . F\right)$
$A S P(W H I L E B D O\{R\} C) P=R \wedge \neg \llbracket B \rrbracket$
so cannot reduce $A S P$ (IF $B$ THEN $C_{1}$ ELSE $C_{2}$ ) $P$
- A solution is to define

ASP (WHILE B DO \{R\} C) $P=$ $\lambda s^{\prime} . \operatorname{SAT}(P) \wedge R s^{\prime} \wedge \neg\left(\llbracket B \rrbracket s^{\prime}\right)$

- Can then show ASP C $(\lambda s . F)=\left(\lambda s^{\prime} . F\right)$
- A dual argument suggests defining
$A W P($ WHILE $B$ DO $\{R\} C) Q=\lambda s . \operatorname{SAT}(\neg Q) \Rightarrow R s$ (note: $\operatorname{SAT}(\neg Q)=\neg(\operatorname{TAUT}(Q)))$


## Summary: definitions of $A S P$ and $A W P$

ASPSKIP $P=P$
$\operatorname{ASP}(X:=E) P=\lambda s^{\prime} . \exists s . P s \wedge\left(s^{\prime}=s[X \rightarrow \llbracket E \rrbracket s]\right)$
$A S P\left(C_{1} ; C_{2}\right) P=A S P C_{2}\left(A S P C_{1} P\right)$
$A S P\left(\right.$ IF $B$ THEN $C_{1}$ ELSE $\left.C_{2}\right) P=$
$S P C_{1}(P \wedge \llbracket B \rrbracket) \vee S P C_{2}(P \wedge \neg \llbracket B \rrbracket)$
$A S P($ WHILE $B$ DO $\{R\} C) P=\lambda s^{\prime} . \operatorname{SAT}(P) \wedge R s^{\prime} \wedge \neg\left(\llbracket B \rrbracket s^{\prime}\right)$
$A W P \operatorname{skIP} Q=Q$
$\operatorname{AWP}(X:=E) Q=\lambda s . Q(s[X \rightarrow \llbracket E \rrbracket s])$
$\operatorname{AWP}\left(C_{1} ; C_{2}\right) Q=A W P C_{1}\left(A W P C_{2} Q\right)$
$A W P\left(\right.$ IF $B$ THEN $C_{1}$ ELSE $\left.C_{2}\right) Q=$

$$
\left(\llbracket B \rrbracket \Rightarrow W P C_{1} Q\right) \wedge\left(\neg \llbracket B \rrbracket \Rightarrow W P C_{2} Q\right)
$$

$A W P(W H I L E B D O\{R\} C) Q=\lambda s \operatorname{SAT}(\neg Q) \Rightarrow R s$

## Calculating verification conditions <br> - SVC P C is a 'forwards' calculation

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- SVC P C is a 'forwards' calculation

$$
\begin{aligned}
& \operatorname{SVC} \operatorname{SKIP} P=\mathrm{T} \\
& \operatorname{SVC}(X:=E) P=\mathrm{T} \\
& \operatorname{SVC}\left(C_{1} ; C_{2}\right) P=\operatorname{SVC} C_{1} P \wedge \operatorname{SVC} C_{2}\left(A S P C_{1} P\right) \\
& \operatorname{SVC}\left(I F B \operatorname{THEN} C_{1} \operatorname{ELSE} C_{2}\right) P= \\
& \operatorname{SAT}(P \wedge \llbracket B \rrbracket) \Rightarrow \operatorname{SVC} C_{1}(P \wedge \llbracket B \rrbracket) \wedge \\
& \operatorname{SAT}(P \wedge \neg \square \rrbracket) \Rightarrow \operatorname{SVC} C_{2}(P \wedge \neg \llbracket B \rrbracket) \\
& \operatorname{SVC}(W H I L E B D O\{R\} C) P= \\
& \operatorname{TAUT}(P \Rightarrow R) \wedge \operatorname{TAUT}(A S P C(R \wedge \llbracket B \rrbracket) \Rightarrow R) \wedge \operatorname{SVCC}(R \wedge \llbracket B \rrbracket)
\end{aligned}
$$

## Calculating verification conditions

- SVC P C is a 'forwards' calculation

$$
\begin{aligned}
& \operatorname{SVC} \operatorname{SKIP} P=\mathrm{T} \\
& \operatorname{SVC}(X:=E) P=\mathrm{T} \\
& \operatorname{SVC}\left(C_{1} ; C_{2}\right) P=\operatorname{SVC} C_{1} P \wedge \operatorname{SVC} C_{2}\left(A S P C_{1} P\right) \\
& \operatorname{SVC}\left(\text { IF } B \operatorname{THEN} C_{1} \operatorname{ELSE} C_{2}\right) P= \\
& \operatorname{SAT}(P \wedge \llbracket \|) \Rightarrow \operatorname{SVC} C_{1}(P \wedge \llbracket B \|) \wedge \\
& \operatorname{SAT}(P \wedge \llbracket B \|) \Rightarrow \operatorname{SVC} C_{2}(P \wedge \neg[B \rrbracket) \\
& \operatorname{SVC}(\operatorname{WHILE} B \operatorname{DO}\{R\} C) P= \\
& \operatorname{TAUT}(P \Rightarrow R) \wedge \operatorname{TAUT}(A S P C(R \wedge \llbracket B \rrbracket) \Rightarrow R) \wedge \operatorname{SVC} C(R \wedge \llbracket B \rrbracket)
\end{aligned}
$$

- WVC C Q is a standard 'backwards' calculation


## Calculating verification conditions

- SVC P C is a 'forwards' calculation

```
SVCSKIP P = T
SVC(X := E)P = T
SVC (C\mp@subsup{C}{1}{};\mp@subsup{C}{2}{})P=SVC C P P S SVC C C (ASP C C P)
SVC(IF B THEN C C ELSE C C ) P=
    SAT(P\wedge\llbracketB\rrbracket) = SVC C ( }(P\wedge\llbracketB\rrbracket
    SAT (P\wedge\neg\llbracketB\rrbracket) => SVC C2 (P\wedge\neg\llbracketB\rrbracket)
SVC(WHILE B DO {R} C) P =
    TAUT (P=>R)^ TAUT (ASP C (R\wedge\llbracketB\rrbracket) =>R) ^ SVC C (R^\llbracketB\rrbracket)
```

- WVC C Q is a standard 'backwards' calculation

```
WVC (SKIP) Q = T
WVC}(X:=E)Q=
WVC}(\mp@subsup{C}{1}{};\mp@subsup{C}{2}{})Q=WVC\mp@subsup{C}{1}{}(AWP C C Q)^WVC C C Q
WVC(IF B THEN C CLSE C C ) Q =
    TAUT(Q) \vee (WVC C C Q \ WVC C C Q )
WVC(WHILE B DO {R} C) Q =
TAUT (R\wedge\llbracketB\rrbracket=> AWP C R) ^ TAUT (R\wedge \neg\llbracketB\rrbracket=> Q) ^ WVC C R
```


## Symbolic execution of loops

```
ASP(WHILE B DO {R} C) P=\lambdas'.SAT (P)^R s'^\neg(\llbracketB\rrbracket s')
```

- New state satisfying invariant $R$ and loop-exit condition
- Pre and post loop states linked by verification conditions

```
SVC(WHILE B DO {R} C) P=
    TAUT (P=>R)}\wedge TAUT (ASP C (R\wedge\llbracketB\rrbracket)=>R) ^ SVC C (R\wedge\llbracketB\rrbracket)
```

- Various approaches to symbolic execution:
- generate fresh set of state variables (need some metatheoretic proof of correctness)
- manage variable scopes inside logic using $\exists$ (correct-by-construct, but inefficient)


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- Various approaches to symbolic execution:
- generate fresh set of state variables (need some metatheoretic proof of correctness)
- manage variable scopes inside logic using $\exists$ (correct-by-construct, but inefficient)
- Question (Plotkin)
- is there a semantics characterisation of AWP and ASP ?


## Shallow embedding of symbolic execution in logic

$-\vdash S P(X:=E) P=\lambda s^{\prime} . \exists s . P s \wedge\left(s^{\prime}=s[X \rightarrow \llbracket E \rrbracket s]\right)$

- Consider $P$ of form
$\lambda s . \exists x_{1} \cdots x_{n} . S \wedge(s=[\bar{X} \rightarrow \bar{e}])$
where
- $X_{1}, \ldots, X_{n}$ are distinct program variables (string constants)
- $x_{1}, \ldots, x_{n}$ are logic variables (i.e. symbolic values)
- $S, e_{1}, \ldots, e_{n}$ only contain variables $x_{1}, \ldots, x_{n}$ and constants
- $[\bar{X} \rightarrow \bar{e}]$ abbreviates $\left[X_{1} \rightarrow e_{1} ; \ldots ; X_{n} \rightarrow e_{n}\right]$
- It follows that

$$
\begin{aligned}
& \vdash S P\left(X_{i}:=E_{i}\right)\left(\lambda s . \exists x_{1} \cdots x_{n} . S \wedge(s=[\bar{X} \rightarrow \bar{e}])\right) \\
& \quad=\lambda s . \exists x_{1} \cdots x_{n} . S \wedge\left(s=[\bar{X} \rightarrow \bar{e}]\left[X_{i} \rightarrow\left(\llbracket E_{i} \rrbracket[\bar{X} \rightarrow \bar{e}]\right)\right]\right)
\end{aligned}
$$

where

$$
\begin{aligned}
& \quad[\bar{X} \rightarrow \bar{e}]\left[X_{i} \rightarrow\left(\llbracket E_{i} \rrbracket[\bar{X} \rightarrow \bar{e}]\right)\right] \\
& \quad=\left[X_{1} \rightarrow e_{1}, \ldots, X_{i} \rightarrow\left(\llbracket E_{i} \rrbracket[\bar{X} \rightarrow \bar{e}]\right), \ldots, X_{n} \rightarrow e_{n}\right]
\end{aligned}
$$

## Symbolic state notation for predicates

- Abbreviate
$\lambda s . \exists x_{1} \cdots x_{n} . S \wedge(s=[\bar{X} \rightarrow \bar{e}])$
as
$\left\langle\exists \bar{x} . S \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle$
then it follows that

$$
\begin{aligned}
& S P\left(X_{i}:=E_{i}\right)\left\langle\exists \bar{x} . S \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle \\
& =\left\langle\exists \bar{x} . S \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{i}=\llbracket E_{i} \rrbracket[\bar{X} \rightarrow \bar{e}] \wedge \ldots \wedge X_{n}=e_{n}\right\rangle
\end{aligned}
$$

- Computing $S P$ is now symbolic execution
- symbolic state term: $\left\langle\exists \bar{x} . S \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle$
- no new existential quantifiers generated by assignments!
- SPSKIP $P=P$
- $S P\left(C_{1} ; C_{2}\right) P=S P C_{2}\left(S P C_{1} P\right)$


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\end{aligned}
$$

- Computing $S P$ is now symbolic execution
- symbolic state term: $\left\langle\exists \bar{x} . S \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle$
- no new existential quantifiers generated by assignments!
- SPSKIP $P=P$
- $S P\left(C_{1} ; C_{2}\right) P=S P C_{2}\left(S P C_{1} P\right)$
- Simpler symbolic state represention OK for loop-free code


## Symbolic execution of conditional branches

- Recall

```
SP(IF B THEN C ELSE C C ) P
    =SP C ( }P\wedge|B\rrbracket)\veeSP\mp@subsup{C}{2}{}(P\wedge\neg\llbracketB\rrbracket
```

- Now

$$
\begin{aligned}
& \left\langle\exists \bar{X} . S \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle \wedge \llbracket B \rrbracket \\
& =\left(\lambda s . \exists x_{1} \cdots x_{n} . S \wedge(s=[\bar{X} \rightarrow \bar{e}])\right) \wedge \llbracket B \rrbracket \\
& =\lambda s .\left(\exists x_{1} \cdots x_{n} . S \wedge(s=[\bar{X} \rightarrow \bar{e}])\right) \wedge \llbracket B \rrbracket s \\
& =\lambda s . \exists x_{1} \cdots x_{n} . S \wedge(s=[\bar{X} \rightarrow \bar{e}]) \wedge \llbracket B \rrbracket s \\
& =\lambda s .\left(\exists x_{1} \cdots x_{n} . S \wedge(s=[\bar{X} \rightarrow \bar{e}]) \wedge \llbracket B \rrbracket[\bar{X} \rightarrow \bar{e}]\right. \\
& =\lambda s . \exists x_{1} \cdots x_{n} .(S \wedge \llbracket B \rrbracket[\bar{X} \rightarrow \bar{e}]) \wedge(s=[\bar{X} \rightarrow \bar{e}]) \\
& =\left\langle\exists \bar{x} \cdot(S \wedge \llbracket B \rrbracket[\bar{X} \rightarrow \bar{e}]) \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle
\end{aligned}
$$

- Hence
$S P\left(\right.$ IF $B$ THEN $C_{1}$ ELSE $\left.C_{2}\right)\left\langle\exists \bar{x} . S \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle$
$=S P C_{1}\left\langle\exists \bar{X} .(S \wedge \llbracket B \rrbracket[\bar{X} \rightarrow \bar{e}]) \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle$ $S P C_{2}\left\langle\exists \bar{X} .(S \wedge \neg \llbracket B \rrbracket[\bar{X} \rightarrow \bar{e}]) \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle$
- Prune paths by checking $S \wedge \llbracket B \rrbracket[\bar{X} \rightarrow \bar{e}]$ and $S \wedge \neg \llbracket B \rrbracket[\bar{X} \rightarrow \bar{e}]$


## Approximate symbolic execution of while-loops

- Symbolically execute straight line code as before
- For while-loops, recall from previous slide

$$
A S P(\text { WHILE } B \mathrm{DO}\{R\} C) P=\lambda s^{\prime} . \mathrm{SAT}(P) \wedge R s^{\prime} \wedge \neg\left(\llbracket B \rrbracket s^{\prime}\right)
$$

- Hence execute while-loops as follows

$$
\begin{aligned}
& A S P(\text { WHILE } B \text { DO }\{R\} C)\left\langle\exists \bar{X} . S \wedge X_{1}=e_{1} \wedge \ldots \wedge X_{n}=e_{n}\right\rangle \\
& =\langle\exists \bar{X} .((\exists \bar{x} . S \bar{x}) \wedge R[\bar{X} \rightarrow \bar{X}] \wedge \neg \llbracket B \rrbracket[\bar{X} \rightarrow \bar{x}]) \\
& \wedge \\
& \left.\quad X_{1}=x_{1} \wedge \ldots \wedge X_{n}=x_{n}\right\rangle
\end{aligned}
$$

- constraint $S$ computed up to loop is discarded
- create new state satisfying invariant and loop exit condition
- link between pre and post loop states provided by VCs

$$
\begin{aligned}
& \operatorname{SVC}(\text { WHILE } B \operatorname{DO}\{R\} C) P= \\
& \operatorname{TAUT}(P \Rightarrow R) \wedge \operatorname{TAUT}(A S P C(R \wedge \llbracket B \rrbracket) \Rightarrow R) \wedge S V C C(R \wedge \llbracket B \rrbracket)
\end{aligned}
$$

## Two cultures have evolved from Floyd-Hoare ideas

- Bounded model checking (BMC)
- unwind loops a finite number of times
- then symbolically execute forwards
- essentially $S P \subset P \Rightarrow Q$
- automatically check states reached satisfy properties
- Full proof of correctness
- generate verification conditions
- usually backwards by computing weakest preconditions
- essentially $P \Rightarrow$ WP C Q
- interactively prove resulting subgoal formulae
- Computing postconditions unifies BMC and full verification
- symbolic execution is ASP calculation
- add forward VCs for verification of loops

Other application of Floyd-Hoare ideas

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- symbolic execution is ASP calculation
- add forward VCs for verification of loops
- Other application of Floyd-Hoare ideas
- refinement:
synthesize code to achive a postcondition (WP)
- reverse engineering: execute symbolically to find out what code does (SP)


## Overview of implementation

- Everything is programmed deduction in a theorem prover
- semantic embedding plus custom theorem proving tools
- for efficiency external oracles used to prune paths
- oracle provenance tracking via theorem tags
- HOL4 used for implementation of theorem proving
- provides higher order logic for representing semantics
- LCF-style proof tools (deriving Hoare logic, solving VCs)
- ML for proof scripting and general programming
- YICES used as oracle (future: Z3)
- SMT solver from SRI International
- used to quickly check conditional branch feasibility
- 'blow away' easy VCs (hard ones by HOL4 interactive proof)
- Experiments needed to compare forwards vs backwards!


## THE END

## Slides at:

## THE END

Slides at: http://www.cl.cam.ac.uk/~mjcg/Hoare75/

